

Satz 16.3

Hörner VIII 1.3

Ana II ss08.pdf

$F: U \rightarrow \mathbb{R}^n$, $\vec{p} \in U \subseteq \mathbb{R}^n$

F stetig diffbar

$J_F(\vec{p})$ invertierbar

$\Leftrightarrow \exists \tilde{U}' \subseteq U, V' \subseteq \mathbb{R}^n$

$g: V' \rightarrow U'$ stetig diffbar

$F(\vec{x}) = \vec{y} \Leftrightarrow g(\vec{y}) = \vec{x} \quad \forall \vec{x} \in U'$
 $\quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \forall \vec{y} \in V'$

Zusatz $J_F(\vec{x})$ invertierbar für $\vec{x} \in U'$

$J_g(\vec{y}) = J_F(\vec{x})^{-1} \quad \vec{y} = F(\vec{x})$

Beispiel

$$\begin{pmatrix} r \\ \varphi \end{pmatrix} \xrightarrow{F} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \end{pmatrix}$$

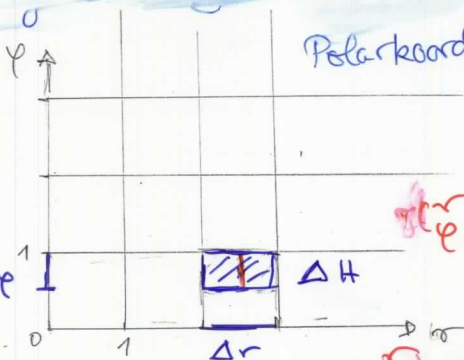
$$\left(\begin{array}{c} \sqrt{x^2 + y^2} \\ \arcsin \frac{y}{\sqrt{x^2 + y^2}} \end{array} \right) \xleftarrow{g}$$

$$J_F = \begin{pmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{pmatrix}$$

$$U' = \left\{ \begin{pmatrix} r \\ \varphi \end{pmatrix} \mid 0 < r < \infty, -\pi < \varphi < \pi \right\}$$

$$V' = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \mid x > 0 \right\}$$

Beweis $\phi_y(x) = y + x - F(x)$ $g(y) = x$
 $\Leftrightarrow \phi_y(x) = x$



Polarkoordinaten

B

$\Delta\varphi$

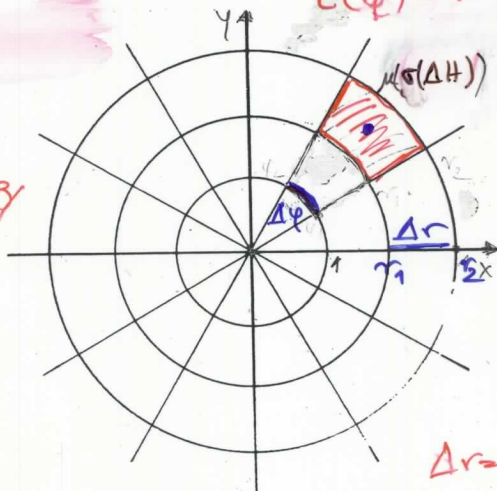
ΔH

Δr

$$\sigma(r) = r \begin{pmatrix} \cos\varphi \\ \sin\varphi \end{pmatrix} \\ \leq \sigma(\varphi)$$

$$\sigma(\varphi) = r$$

$\sigma\varphi$



$$\mu(\sigma(\Delta H)) = r \mu(\Delta H)$$

$$\Delta r = r_2 - r_1$$

$$\begin{aligned} \mu(\sigma(\Delta H)) &= \frac{1}{2} \Delta\varphi r_2^2 - \frac{1}{2} \Delta\varphi r_1^2 \\ &= r \Delta\varphi \Delta r \quad r = \frac{1}{2} (r_1 + r_2) \end{aligned}$$

3. Bikoni

18.4

 $\vec{x}(t)$ $t \in [a, b]$ stetig differenzierbar

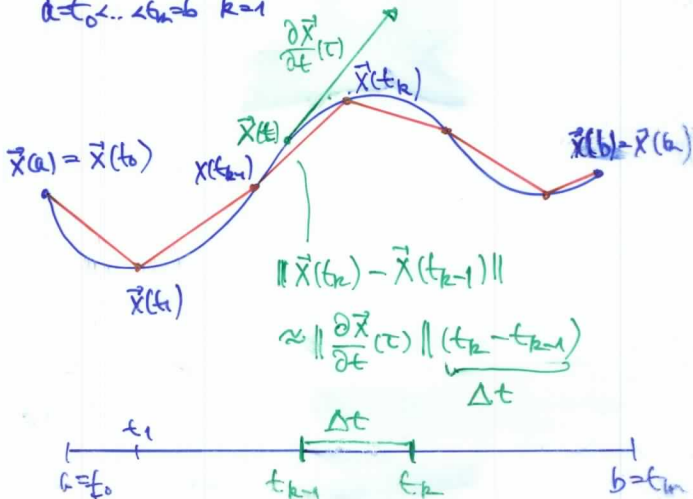
$$\frac{\partial \vec{x}}{\partial t}(t) = \begin{pmatrix} \partial x_1 / \partial t \\ \vdots \\ \partial x_n / \partial t \end{pmatrix}(t) \text{ stetig}$$

$$\|\frac{\partial \vec{x}}{\partial t}\| > 0$$

Weglänge $L(\vec{x}_{[a,b]}) = \int_a^b \|\frac{\partial \vec{x}}{\partial t}\| dt$

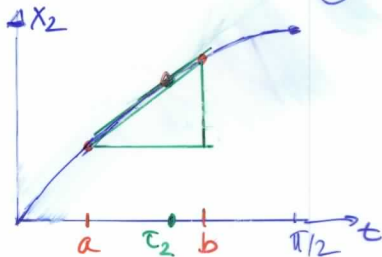
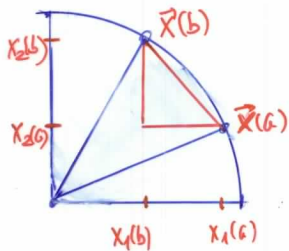
$$= \int_a^b \sqrt{\left(\frac{\partial x_1}{\partial t}\right)^2 + \dots + \left(\frac{\partial x_n}{\partial t}\right)^2} dt$$

$$= \sup_{a=t_0 < \dots < t_n=b} \sum_{k=1}^n \|\vec{x}(t_k) - \vec{x}(t_{k-1})\|$$

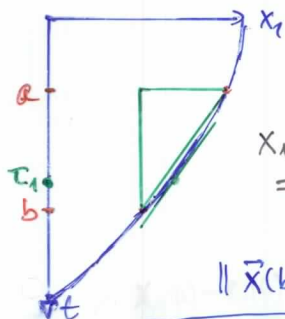


Mittelwertsatz

(1)



$$\begin{aligned} & x_2(a) - x_2(b) \\ &= \frac{\partial x_2}{\partial t}(\tau_2)(b-a) \end{aligned}$$



$$\begin{aligned} & x_1(a) - x_1(b) \\ &= \frac{\partial x_1}{\partial t}(\tau_1)(b-a) \end{aligned}$$

$$\|\bar{x}(b) - \bar{x}(a)\|$$

$$= \sqrt{[x_1(b) - x_1(a)]^2 + [x_2(b) - x_2(a)]^2}$$

$$= \sqrt{\left[\frac{\partial x_1}{\partial t}(\tau_1)(b-a)\right]^2 + \left[\frac{\partial x_2}{\partial t}(\tau_2)(b-a)\right]^2}$$

$$= \sqrt{\frac{\partial x_1}{\partial t}(\tau_1)^2 + \frac{\partial x_2}{\partial t}(\tau_2)^2} (b-a)$$

$$\left\| \frac{\partial \bar{x}}{\partial t} \right\| = 1 \Rightarrow \searrow 1 \text{ für } b-a \rightarrow 0$$

②

Lemma 18.5 $\vec{x}: [a, b] \rightarrow \mathbb{R}^n$ stetig diffbar

$$\left\| \frac{\partial \vec{x}}{\partial t} \right\| = 1 \Rightarrow$$

$$b - a = \sup \sum_{k=1}^m \|\vec{x}(t_k) - \vec{x}(t_{k-1})\|$$

$$a = t_0 < t_1 < \dots < t_m = b$$

=: L

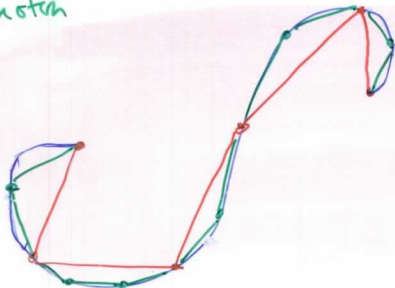
Bew.

$$L = \sum_{k=1}^m \sqrt{\sum_{i=1}^n \left(\frac{\partial x_i}{\partial t}(t_{ik}) \right)^2} (t_k - t_{k-1})$$

 $\rightarrow 1$

$$L \rightarrow \sum_{k=1}^m (t_k - t_{k-1}) = b - a \quad \square$$

monoton



(3)

Korollar 18.7 $\vec{x}(t) \in [a, b]$ stetig diffbar

$$\left\| \frac{\partial \vec{x}}{\partial t} \right\| > 0 \rightarrow L(\vec{x}_{[a, b]}) = \int_a^b \left\| \frac{\partial \vec{x}}{\partial t} \right\| dt$$

Beweis $s = s(t) = \int_a^t \left\| \frac{\partial \vec{x}}{\partial t}(\tau) \right\| dt$

$$\frac{\partial s}{\partial t} = \left\| \frac{\partial \vec{x}}{\partial t}(t) \right\| > 0$$

$t = t(s)$ Umkehrfunktion

$$\frac{\partial \vec{x}}{\partial s} = \frac{\partial \vec{x}}{\partial t} \frac{\partial t}{\partial s} = \frac{\partial \vec{x}}{\partial t} \frac{1}{\frac{\partial s}{\partial t}} = \frac{\partial \vec{x}}{\partial t} \frac{1}{\left\| \frac{\partial \vec{x}}{\partial t} \right\|}$$

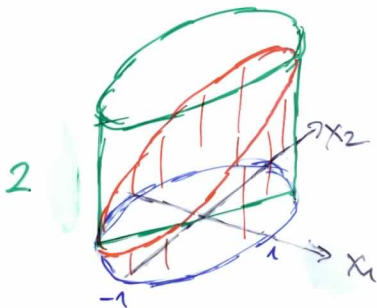
$$\Rightarrow \left\| \frac{\partial \vec{x}}{\partial s} \right\| = 1$$

$$L(\vec{x}_{[a, b]}) = L(\vec{x}(t(s))_{[s(a), s(b)]})$$

$$= \underbrace{s(b) - s(a)}_{=0} = \int_a^b \left\| \frac{\partial \vec{x}}{\partial t} \right\| dt$$

(5)

19.1 Wegintegral in Skalarfeld



$$\vec{x}(t) = \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} \quad t \in [0, 2\pi]$$

$$f(\vec{x}) = x_1 + x_2 + \sqrt{2} \quad \left\| \frac{\partial \vec{x}}{\partial t} \right\| = 1$$

$$\int_0^{2\pi} f(\vec{x}(t)) dt = \text{III}$$

$$= \int_0^{2\pi} \cos t + \sin t + \sqrt{2} dt$$

$$= 2\sqrt{2}\pi$$

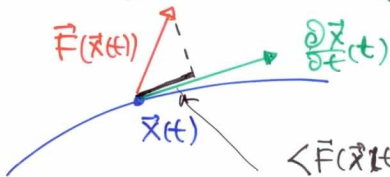
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Vektorfeld $\vec{F}(\vec{x}) = \begin{pmatrix} F_1(\vec{x}) \\ \vdots \\ F_n(\vec{x}) \end{pmatrix}$

(Kurven) Integral entlang $\Gamma: \vec{x}(t) \quad t \in [a, b]$

$$\int_{\Gamma} \vec{F} \cdot d\vec{x} = \int_a^b \left\langle \vec{F}(\vec{x}(t)) \mid \frac{\partial \vec{x}}{\partial t}(t) \right\rangle dt$$

$$= \int_{\Gamma} \sum_i F_i dx_i$$



$$\left\langle \vec{F}(\vec{x}(t)) \mid \frac{\partial \vec{x}}{\partial t}(t) \right\rangle$$

$$= \sum_{i=1}^n \int F_i(\vec{x}(t)) \cdot \frac{\partial x_i}{\partial t}(t) dt$$

falls $\left\| \frac{\partial \vec{x}}{\partial t}(t) \right\| = 1$

$\int_{\Gamma} \vec{F} \cdot d\vec{x}$ unabhängig von Parametrisierung

$$s = s(t), \quad t = t(s),$$

$$\int_{s(a)}^{s(b)} \left\langle \vec{F}(\vec{x}(t(s))) \mid \frac{\partial \vec{x}}{\partial s} \right\rangle ds$$

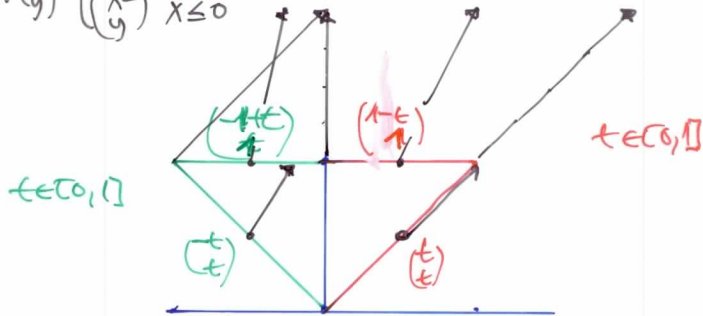
$$= \int_a^b \left\langle \vec{F}(\vec{x}(t)) \mid \frac{\partial \vec{x}}{\partial t} \right\rangle \frac{\partial t}{\partial s} ds$$

$$= \int_a^b \left\langle \vec{F}(\vec{x}(t)) \mid \frac{\partial \vec{x}}{\partial t} \right\rangle dt$$

$$F(x,y) = \begin{cases} (x,y) & x \geq 0 \\ (x,-y) & x \leq 0 \end{cases}$$

19.3

Wegintegral
im Vektorfeld (8)



$$\int_0^1 \langle \begin{pmatrix} t \\ t \end{pmatrix} | \begin{pmatrix} 1 \\ 1 \end{pmatrix} \rangle dt + \int_0^1 \langle \begin{pmatrix} 1-t \\ 1-t \end{pmatrix} | \begin{pmatrix} -1 \\ 0 \end{pmatrix} \rangle dt$$

$$= \int_0^1 3t - 1 dt = \frac{1}{2}$$

$$\int_0^1 \langle \begin{pmatrix} t+t^2 \\ t \end{pmatrix} | \begin{pmatrix} -1 \\ 1 \end{pmatrix} \rangle dt + \int_0^1 \langle \begin{pmatrix} t+t^2 \\ t \end{pmatrix} | \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rangle dt$$

$$= \int_0^1 -t^2 + t + (t-1)^2 dt$$

$$= -\frac{1}{3} + \frac{1}{2} - \frac{1}{3} = -\frac{1}{6}$$

(E)

19.3 Wegintegral in Vektorfeld

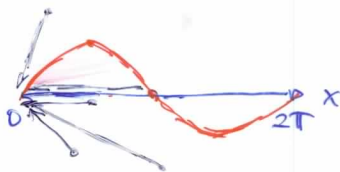
$$F(\vec{x}) \in \mathbb{R}^n, \quad \vec{x}(t) \in \mathbb{R}^n \quad t \in [a, b]$$

$$\int_a^b \left\langle F(\vec{x}(t)) \mid \frac{\partial \vec{x}}{\partial t}(t) \right\rangle dt$$

$$F\begin{pmatrix} x \\ y \end{pmatrix} = -\begin{pmatrix} x \\ y \end{pmatrix}$$

$$\vec{x}(t) = \begin{pmatrix} t \\ 0 \end{pmatrix} \quad t \in [0, 2\pi]$$

$$\vec{x}(t) = \begin{pmatrix} t \\ \sin t \end{pmatrix} \quad t \in [0, 2\pi]$$



$$\frac{\partial \vec{x}}{\partial t} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \int_0^{2\pi} \left\langle -\begin{pmatrix} t \\ 0 \end{pmatrix} \mid \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\rangle dt = \int_0^{2\pi} -t dt = -2\pi^2$$

$$\frac{\partial \vec{x}}{\partial t} = \begin{pmatrix} 1 \\ \cos t \end{pmatrix} \quad \int_0^{2\pi} \left\langle -\begin{pmatrix} t \\ \sin t \end{pmatrix} \mid \begin{pmatrix} 1 \\ \cos t \end{pmatrix} \right\rangle dt$$

$$= \int_0^{2\pi} -t - \sin t \cos t dt = \left[-\frac{1}{2}t^2 - \frac{1}{2}\sin^2 t \right]_0^{2\pi} = -2\pi^2$$

$$\vec{x}(t) = \begin{pmatrix} 2t \\ 0 \end{pmatrix} \quad \frac{\partial \vec{x}}{\partial t} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$\int_0^{\pi} \left\langle -\begin{pmatrix} t \\ 0 \end{pmatrix} \mid \begin{pmatrix} 2 \\ 0 \end{pmatrix} \right\rangle dt = \int_0^{\pi} -2t dt = -2\pi^2$$

20.1 $M \subseteq \mathbb{R}^n$ offen, $F: M \rightarrow \mathbb{R}^n$

$\varphi: M \rightarrow \mathbb{R}$ stetig part. diffbar

$$F(\varphi) = \text{grad} \varphi \quad \forall \varphi \in M$$

φ Potential / Stammfunktion
für F

$\Gamma: \vec{x}(t) \in M \quad t \in [a, b]$ stetig diffbar

$$\begin{aligned} \rightarrow \int_{\Gamma} F \cdot d\vec{x} &= \int_a^b \left\langle F(\vec{x}(t)) \mid \frac{\partial \vec{x}}{\partial t} \right\rangle dt \\ &= \varphi(\vec{x}(b)) - \varphi(\vec{x}(a)) \end{aligned}$$

Wegunabhängigkeit

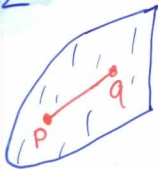
Folg. $\varphi + C$ eindeutig bis auf C

Folg. Sind die F_i stetig diffbar

$$\text{so } \frac{\partial F_i}{\partial x_j} = \frac{\partial F_j}{\partial x_i}$$

$$\text{Schwarz} \Rightarrow \frac{\partial^2 \varphi}{\partial x_j \partial x_i} = \frac{\partial^2 \varphi}{\partial x_i \partial x_j}$$

20.2

konvex $\forall p, q$ 

Sternförmig

 $\exists p \forall q$ Weg zusammenhängend
 $\forall p, q$ 

nicht wegzusammenhängend

20.5 Satz

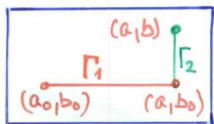
 $M \subseteq \mathbb{R}^n$ offen, sternförmig $F: M \rightarrow \mathbb{R}^n$ F_i stetig diffbar $i=1, \dots, n$

exakt $\frac{\partial F_i}{\partial x_j} = \frac{\partial F_j}{\partial x_i}$ alle i, j

 $\Rightarrow F$ hat ein Potential

2.13

5



$$\varphi(a,b) = \int_{\Gamma_1} \mathbf{F} \cdot d\vec{x} + \int_{\Gamma_2} \mathbf{F} \cdot d\vec{x}$$

$$= \int_{a_0}^a \langle \mathbf{F}(t, b_0) | \vec{e}_1 \rangle dt + \int_{b_0}^b \langle \mathbf{F}(a, t) | \vec{e}_2 \rangle dt$$

$$= \int_{a_0}^a F_1(t, b_0) dt + \int_{b_0}^b F_2(a, t) dt$$

$$\frac{\partial \varphi}{\partial x}(a,b) \stackrel{?}{=} F_1(a,b)$$

Hauptsatz $\rightarrow \frac{\partial}{\partial x} \int_{a_0}^a F_1(t, b_0) dt = F_1(a, b_0)$

$$F_1(a,b) - F_1(a, b_0) = \int_{b_0}^b \underbrace{\frac{\partial F_1}{\partial y}(a, t)}_{\parallel \text{exakt}} dt$$

Vertauschung

$$\frac{\partial}{\partial x} \int_{b_0}^b F_2(a, t) dt = \int_{b_0}^b \underbrace{\frac{\partial F_2}{\partial x}(a, t)}_{\parallel \text{exakt}} dt$$

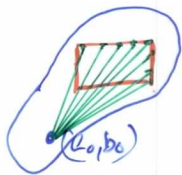
$$\frac{\partial \varphi}{\partial y}(a,b) = \frac{\partial}{\partial y} \int_{b_0}^b F_2(a, t) dt = F_2(a,b)$$

(6)
M sternförmig, Zentralpunkt (a_0, b_0)

1. R Rechteck, $\delta(R) \subseteq M$

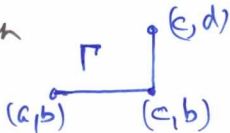
$$\Rightarrow R \subseteq M$$

$\int_{\Gamma} F d\vec{x}$ wegunabhängig
für $\Gamma \cong R$



Bew: Potential auf R

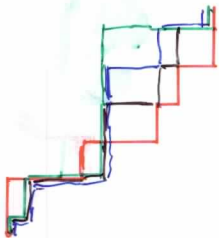
2. Haken



$$\vec{x}(t) = \begin{cases} (t, b) & t \in [a, c] \\ (c, t) & t \in [b, d] \end{cases}$$

3. Hakenweg $\Gamma = \Gamma_1 \oplus \dots \oplus \Gamma_n$ Γ_i : Haken

4. Verfeinerung von Hakenwegen

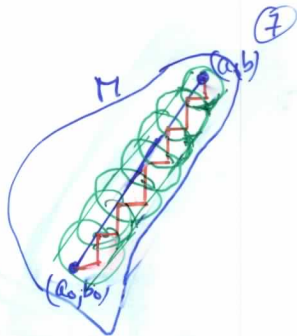


$$\begin{aligned} \int_{\Gamma} F d\vec{x} &= \int_{\Gamma} F d\vec{x} \\ &= \int_{\Gamma} F \cdot dx = \int_{\Gamma} F \cdot d\vec{x} \end{aligned}$$

Bew. Wegunabhängigkeit
auf Rechtecken

5. Für alle $(a,b) \in M$
 gibt es Hakenweg Γ
 von (a_0, b_0) nach (a,b)

Bew: Kompaktheit
 der Strecke $(a_0, b_0), (a,b)$



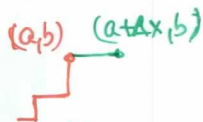
6. Def $\varphi(a,b) = \int_{\Gamma} F \cdot dx$
 unabhängig von Γ

Bew 4.

$$7. \frac{\partial \varphi}{\partial x}(a,b) = F_1(a,b)$$

$$= \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} \int_a^{a+\Delta x} F_1(t,b) dt$$

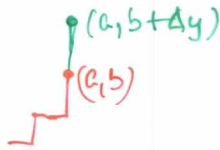
$$= \frac{\partial}{\partial x} \int F_1(t,b) dt (a) = F_1(a,b)$$



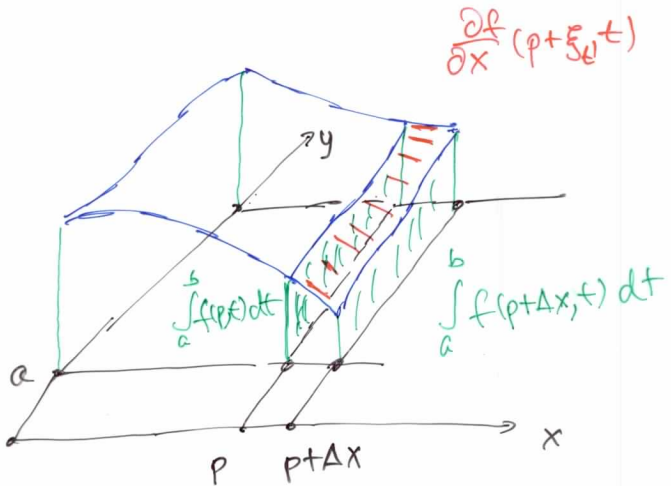
$$8. \frac{\partial \varphi}{\partial y}(a,b) = F_2(a,b)$$

$$= \lim_{\Delta y \rightarrow 0} \frac{1}{\Delta y} \int_b^{b+\Delta y} F_2(a,t) dt$$

$$= \frac{\partial}{\partial y} \int F_2(a,t) dt (b) = F_2(a,b)$$



(1)

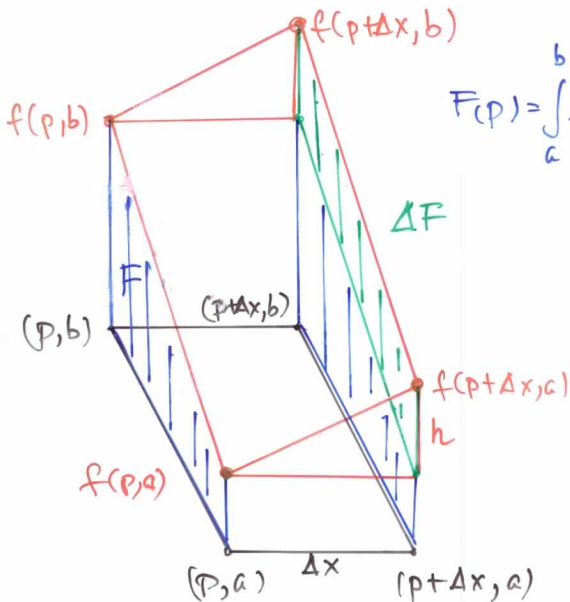


Satz 21.1. Satz $M \subseteq \mathbb{R}^n$ offen

$f: M \times [a, b]$ stetig, $\frac{\partial f}{\partial x_i}$ stet

$$\begin{aligned} \Rightarrow \left(\frac{\partial}{\partial x_i} \int_a^b f(x, t) dt \right) (p) \\ = \int_a^b \frac{\partial f}{\partial x_i}(p, t) dt \quad \text{stet Fktmap} \end{aligned}$$

(2)



$$F(p) = \int_a^b f(p, t) dt$$

$$\Delta F \approx h(b-a)$$

$h =$ Funktionswert
 $b-a =$ Höhe

$$\frac{h}{\Delta x} \approx \frac{\partial f}{\partial x}(p, a)$$

$$\frac{\partial}{\partial x} \int_a^b f(p, t) dt \approx \frac{\Delta F}{\Delta x} \approx \frac{\partial f}{\partial x}(p, a) (b-a) \approx \int_a^b \frac{\partial f}{\partial x}(p, t) dt$$

GB&A n=1

(3)

Schreibweise $x = y \pm \varepsilon \Leftrightarrow y - \varepsilon \leq x \leq y + \varepsilon$

geg. $\varepsilon > 0$ ex. $\delta > 0$: $|\Delta x| < \delta \Rightarrow$

$$\frac{1}{\Delta x} \left(\int_a^b f(p+\Delta x, t) dt - \int_a^b f(p, t) dt \right)$$

$$\int_a^b (f(p+\Delta x, t) - f(p, t)) dt$$

$$\Delta x \left(\frac{\partial f}{\partial x}(p + \xi_{\Delta x}, t) \right)$$

Mittelwert

$$\frac{\partial f}{\partial x}(p, t) \pm \varepsilon$$

$\frac{\partial f}{\partial x}$
glm. stetig

auf $K \times [c, b]$
 $K \subseteq M$ komp.

$$= \frac{1}{\Delta x} \int_a^b \Delta x \left(\frac{\partial f}{\partial x}(p, t) \pm \varepsilon \right) dt$$

$$= \int_a^b \left(\frac{\partial f}{\partial x}(p, t) \pm \varepsilon \right) dt$$

$$= \int_a^b \frac{\partial f}{\partial x}(p, t) dt \pm \varepsilon(b-a)$$

$\rightarrow 0$