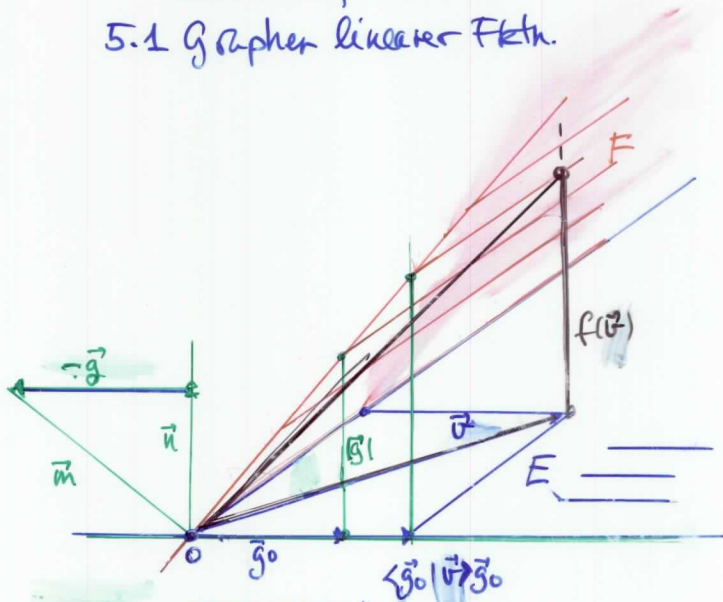


5. Differentiation von Skalarfeldern

5.1 Graphen linearer Fktn.



$$|\vec{g}_0| = 1$$

$$= |\vec{n}|$$

$$\vec{n} \perp \vec{F}$$

$$f(\vec{x}) = \langle \vec{g} | \vec{u} \rangle$$

$$\vec{m} = \vec{n} - \vec{g} + \vec{F}$$

$$-\vec{g} = \vec{m} - \vec{n}$$

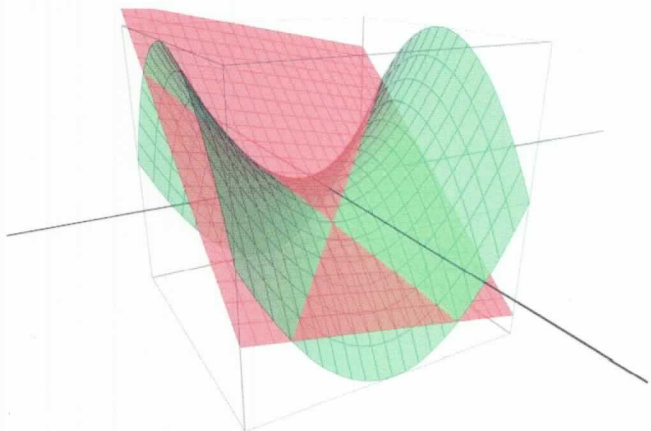
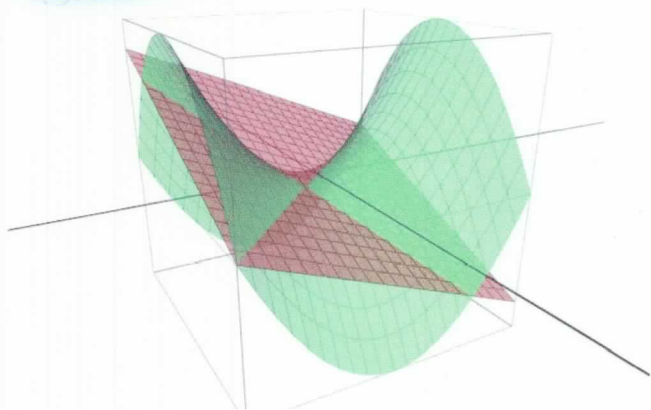
$\vec{g} = \text{Gradient}$

$\vec{g} = \text{grad} f$

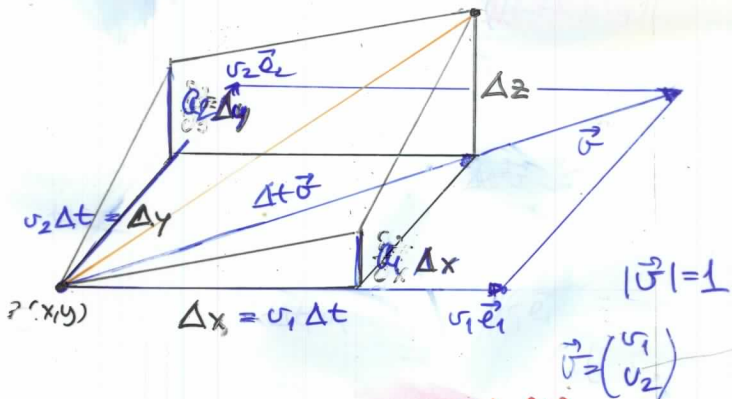
$$d\vec{u} = \frac{f(\vec{u})}{|\vec{u}|}$$

$$= \langle \vec{g} | \frac{\vec{u}}{|\vec{u}|} \rangle$$

5.2



5.3 Richtungsableitung u. Gradient (3)



$$\lim_{\Delta t \rightarrow 0} \frac{\Delta z}{\Delta t} = \lim_{\Delta t \rightarrow 0} \frac{f(P + \Delta t \vec{u}) - f(P)}{\Delta t}$$

$$= \lim_{\Delta t \rightarrow 0} a_1 \frac{\Delta x}{\Delta t} + a_2 \frac{\Delta y}{\Delta t} + \frac{R(\Delta x, \Delta y)}{\Delta t}$$

$$= a_1 u_1 + a_2 u_2$$

$$= \langle \text{grad } f, \vec{u} \rangle$$

Ableitung in Richtung \vec{u}

$$\text{grad } f = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

Gradient

⊥ Höhenlinien

max in Richtung grad f

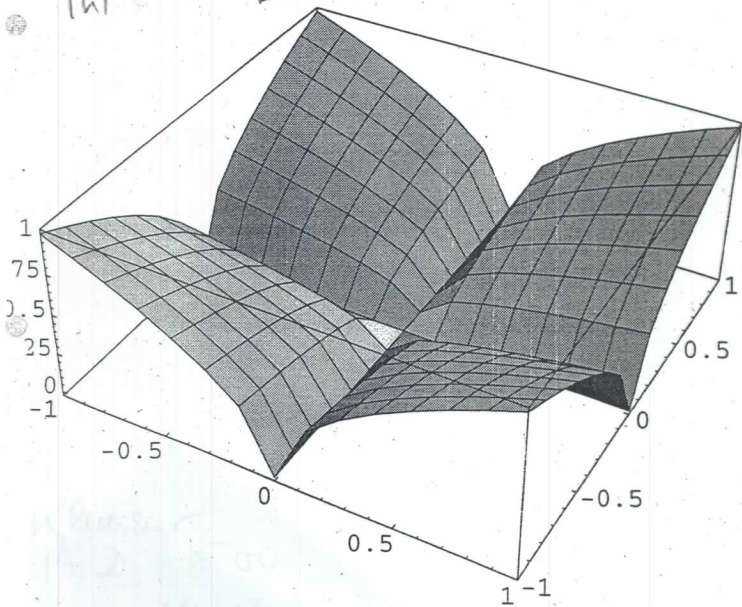
5.4

$$z = f(x, y) = \sqrt{|xy|}$$

$$\frac{\partial z}{\partial x}(x, y) = \mp \frac{y}{2\sqrt{|x|}} \quad \frac{\partial z}{\partial y}(x, y) = \mp \frac{x}{2\sqrt{|y|}} \quad y \neq 0$$

$$\frac{\partial z}{\partial x}(x, 0) = \frac{\partial z}{\partial y}(0, y) = 0$$

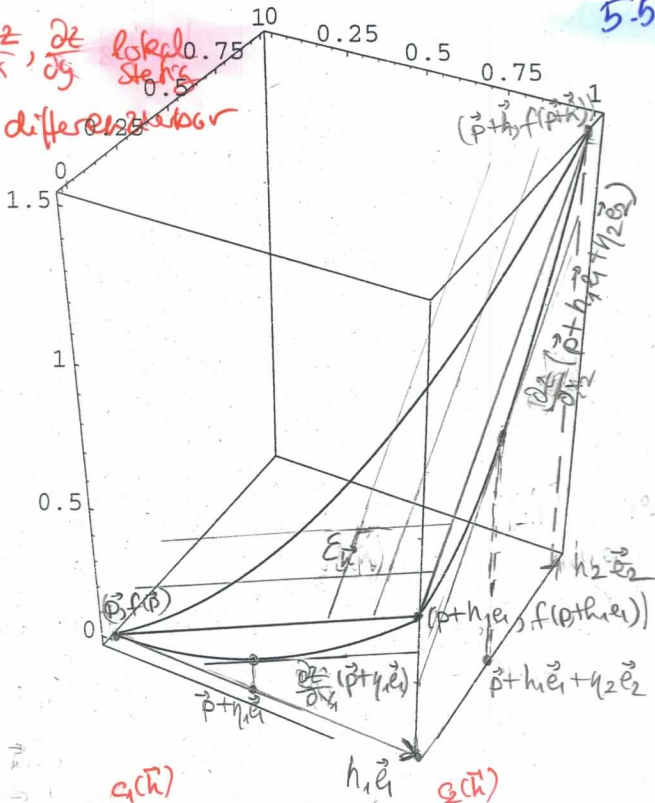
wird differbar an $(0, 0)$ - sonst $R(\vec{h}) = f(\vec{h})$
 aber $\frac{1}{|\vec{h}|} R(\vec{h}) = \frac{|\vec{h}|}{|\vec{h}|} = 1 \neq 0$ für $|\vec{h}| = |\vec{h}| \rightarrow 0$



$$\vec{p} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \vec{h} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \Delta x_1 \\ \Delta x_2 \end{pmatrix} \quad z = f(x_1, x_2) = \frac{1}{2} x_1^2 + x_2^2$$

5.5

$\frac{\partial z}{\partial x_1}, \frac{\partial z}{\partial x_2}$ lokale Steigung
 \Rightarrow differenzierbar



$$R(\Delta \vec{h}) = \frac{\partial z}{\partial x_1}(\vec{p} + \eta_1 \vec{e}_1) \Delta x_1 + \frac{\partial z}{\partial x_2}(\vec{p} + \Delta x_1 \vec{e}_1 + \eta_2 \vec{e}_2) \Delta x_2 - \frac{\partial z}{\partial x_1}(\vec{p}) \Delta x_1 - \frac{\partial z}{\partial x_2}(\vec{p}) \Delta x_2 = \langle \begin{pmatrix} a_1 - g_1(\vec{h}) \\ a_2 - g_2(\vec{h}) \end{pmatrix} | \vec{h} \rangle$$

$$R(\Delta \vec{h}) / \underbrace{\sqrt{\Delta x_1^2 + \Delta x_2^2}}_{\|\vec{h}\|} \rightarrow 0 \text{ f\u00fcr } \begin{pmatrix} \Delta x_1 \\ \Delta x_2 \end{pmatrix} \rightarrow \vec{0}$$

5.5

$$z = f(x,y) = \begin{cases} \sqrt{|xy|} & e^{-\left(\frac{1}{x} - \frac{1}{y}\right)^2} \\ 0 & \end{cases} \quad xy \neq 0$$

$\frac{\partial z}{\partial x}$ ($\frac{\partial z}{\partial y}$) ex absolut stetig für $(x,y) \neq (0,0)$

keine Tangentialebene an $(0,0)$

Beachte für $\gamma(t) = (t,t) \quad t \geq 0$

$$f(\gamma(t)) = t \quad (f \circ \gamma)'(0) = 1 + \sum \underbrace{\frac{\partial f}{\partial x_i}}_0 \cdot \frac{dx_i}{dt}$$

