Lecture Script

Analysis I

Winter Semester 2007/08
Department of Mathematics
TU Darmstadt

January 28, 2010

Contents

Ι	Nur	mber Basics
	1	The Real Numbers
	2	The Complex Numbers
II	Con	evergence of Sequences and Series 15
	1	Convergence of Sequences
	2	Bolzano-Weierstrass Theorem
	3	Infinite Series
	4	Rearrangement and Products of Series
	5	Power Series
II	I Cor	tinuous Functions and the Basics of Topology 49
	1	Continuous Functions
	2	Basics of Topology
	3	Compactness
	4	The exponential function and related functions
ΙV	Diff	erential Calculus in one Variable 8'
	1	Differentiable Functions
	2	The Mean Value Theorem and Applications
	3	Taylor's theorem
	4	Convergence of Sequences of Functions
\mathbf{V}	Inte	egration in one Variable 115
	1	Step functions and jump continuous functions
	2	The integral and its properties
	3	Integration techniques
	1	Improper integrals 126

Chapter I

Number Basics

1 The Real Numbers

What are the real numbers? Depending on your point of view this can be a difficult question. In the following, we describe the set \mathbb{R} of real numbers by giving rules which allow us to 'calculate' with these numbers. This set of rules (or axioms) form the axiom system of the real numbers.

This system consists of the following:

- Field axioms
- Ordering axioms
- Completeness axiom

All statements about the real numbers can be derived exclusively from these axioms. We begin with the field axioms.

1.1. The Field Axioms.

There are two operations on the set \mathbb{R} , namely addition '+' and multiplication '.':

Addition: $\mathbb{R} \times \mathbb{R} \to \mathbb{R}$

 $(x,y) \mapsto x + y$

Multiplication: $\mathbb{R} \times \mathbb{R} \to \mathbb{R}$

 $(x,y)\mapsto x\cdot y$

These satisfy the following field axioms:

Axioms of Addition

- **(A1)** Law of Commutativity: for all $x, y \in \mathbb{R}$, x + y = y + x.
- **(A2)** Law of Associativity: for all $x, y, z \in \mathbb{R}$, (x + y) + z = x + (y + z).
- (A3) Existence of a Neutral Element: There exists $0 \in \mathbb{R}$ such that x + 0 = x for all $x \in \mathbb{R}$.
- (A4) Existence of an Inverse Element: For every $x \in \mathbb{R}$ there exists a $-x \in \mathbb{R}$ such that x + (-x) = 0.

Axioms of Multiplication

- (M1) Law of Commutativity: for all $x, y \in \mathbb{R}$, $x \cdot y = y \cdot x$.
- (M2) Law of Associativity: for all $x, y, z \in \mathbb{R}$, $(x \cdot y) \cdot z = x \cdot (y \cdot z)$.
- (M3) Existence of a Neutral Element: There exists a $1 \in \mathbb{R}$, $1 \neq 0$ such that $x \cdot 1 = x$ for all $x \in \mathbb{R}$.
- (M4) Existence of an Inverse Element: for every $x \in \mathbb{R}$ with $x \neq 0$, there exists an $x^{-1} \in \mathbb{R}$ such that $x \cdot (x^{-1}) = 1$.

The law of distributivity shows how addition and multiplication interact.

(D) Law of Distributivity: for all
$$x, y, z \in \mathbb{R}$$
, $x \cdot (y+z) = (x \cdot y) + (x \cdot z)$

A set \mathbb{K} of elements a, b, \ldots , together with the binary operations a+b and $a \cdot b$ which satisfy the above axioms, is called a *field*. In the lecture *linear algebra*, fields and their axioms will be treated in greater detail. At this point, we only remark that the elements 0 and 1 are uniquely determined and that the statement $x \cdot y = 0$ implies that at least one of x and y is zero.

We introduce the following simplifying notations

$$xy := x \cdot y, \quad \frac{x}{y} := x \cdot y^{-1}, \quad x - y := x + (-y), \quad x^2 := x \cdot x, \quad 2x := x + x$$

1.2. The Ordering Axioms.

In \mathbb{R} , certain numbers have the distinguished property of being positive (written x > 0) such that we have:

(O1) For every $x \in \mathbb{R}$, exactly one of the following relations is true: x = 0, x > 0, -x > 0

- (O2) $x > 0, y > 0 \Rightarrow x + y > 0$
- (O3) If x > 0, y > 0, it follows that $x \cdot y > 0$

The second axiom states compatibility with addition, the third one compatibility with multiplication.

The following definition enables us to compare any two elements of \mathbb{R} :

1.3 Definition. Let $x, y \in \mathbb{R}$. We define

$$x > y :\Leftrightarrow x - y > 0$$

 $x > y :\Leftrightarrow x - y > 0 \text{ or } x - y = 0.$

An element $x \in \mathbb{R}$ with x > 0 is called *positive (positiv)*.

For x > y and $x \ge y$ one can also write y < x respectively $y \le x$. If x < 0, then x is called *negative* (negativ).

- **1.4. Calculation rules.** Let $x, y, z, u, v \in \mathbb{R}$. Then the following statements hold:
- a) Exactly one of the following relations holds: x = y, x < y or x > y (Law of Trichotomy)
- b) x < y and $y < z \Rightarrow x < z$, (Transitivity)
- c) x < y and u < v implies x + u < y + v (Monotonicity of Addition)
- d) $x < y \Rightarrow -x > -y$
- $(e) x < y, u > 0 \Rightarrow xu < yu,$ (Monotonicity of Multiplication)
- f) $x \neq 0 \Rightarrow x^2 > 0$, particularly 1 > 0
- $(g) \ 0 < x < y \Rightarrow 0 < \frac{1}{y} < \frac{1}{x}$
- $h) \ x < y \Rightarrow x < \frac{x+y}{2} < y$

Proof. a) Follows from Definition 1.3 and Ordering Axiom (O1).

- b) By Definiton 1.3, y x > 0 and z y > 0. Ordering Axiom (O2) implies $\underbrace{(y-x) + (z-y)}_{=z-x} > 0 \Rightarrow z > x \Rightarrow x < z$
- c) e) Exercises
- f) Let x > 0, then $x \cdot x = x^2 > 0$ by (O2). If x < 0, then d) implies that -x > 0 and from there $(-x)(-x) = (-x)^2 > 0$ by (O3). That $(-x)(-x) = x^2$ follows from results in the solution of Tutorial 1. Namely, we get $(-x)(-x) = (-1)x \cdot (-1)x = (-1)^2x^2$.
- We get also $(-1)(-1) = -(1 \cdot (-1)) = -(-1) = 1$. So $(-x)(-x) = x^2$. g) $x^{-1} = \underbrace{x}_{>0} \cdot \underbrace{(x^{-1})^2}_{>0} > 0$, analogously $y^{-1} > 0$. Therefore $x^{-1} \cdot y^{-1} > 0$. Given this, together with 0 < x < y, it holds that:

$$y^{-1} = x \cdot (x^{-1}y^{-1}) < y(x^{-1}y^{-1}) = x^{-1}$$

h) Exercise

The field- and ordering axioms imply that in addition to 0, 1, other numbers exist in \mathbb{R} . In fact, adding 0 resp. 1 to both sides of the inequality 0 < 1, we get 0 + 0 = 0 < 1 + 0 = 1, 1 < 1 + 1 = 2, therefore $2 \neq 0$, $2 \neq 1$.

1.5 Definition. (Absolute Value). Let $x \in \mathbb{R}$. We define the absolute value (Absolute betrag) of x as

$$|x| := \left\{ \begin{array}{cc} x, & x \ge 0, \\ -x, & x < 0. \end{array} \right.$$

1.6 Remark. For the absolute value, we have the following rules:

- a) $|x| \ge 0 \ \forall \ x \in \mathbb{R}$ and $|x| = 0 \Leftrightarrow x = 0$.
- b) $|-x| = |x|, \quad x \in \mathbb{R}$
- c) $||x|| = |x|, \quad x \in \mathbb{R}$
- d) $|x \cdot y| = |x| \cdot |y|$, $x, y \in \mathbb{R}$
- e) $\left|\frac{x}{y}\right| = \frac{|x|}{|y|}, \quad x \in \mathbb{R}, y \neq 0$
- f) $|x+y| \le |x| + |y|$, $x, y \in \mathbb{R}$ (Triangle Inequality)
- g) $||x| |y|| \le |x y|$, $x, y \in \mathbb{R}$ (Reverse Triangle Inequality)

Proof. a) b) c) d) e) g) as exercises. For f): Let $x, y \in \mathbb{R}$. Then $x \leq |x|, y \leq |y|$ and also $-x \leq |x|$ and $-y \leq |y|$. The monotonicity of addition 1.4. c) gives that $-x-y \leq |x|+|y|$ and also that $x+y \leq |x|+|y|$. Therefore, it holds that $|x+y| \leq |x|+|y|$.

We now consider the positive integers as a subset of \mathbb{R} . To this end, we have the following definition:

1.7 Definition. Let $M \subset \mathbb{R}$. Then M is called *inductive (induktiv)*, if the following hold:

- a) $0 \in M$
- b) $x \in M \Rightarrow x + 1 \in M$.

1. THE REAL NUMBERS

5

Obviously, the set \mathbb{R} of real numbers is inductive. If we define $M := \{x \in \mathbb{R} : x \ge a\}$, then M is inductive if we have $a \le 0$.

1.8. Theorem and Definition. There exists a smallest inductive subset of \mathbb{R} ; this is called the set of nonnegative integers and is denoted by \mathbb{N}_0 .

Proof. Let $M \subset \mathbb{R}$ be inductive. Set

$$\mathbb{N}_0 := \bigcap_{\substack{M \subset \mathbb{R} \\ M \text{ inductive}}} M;$$

in other words, \mathbb{N}_0 is the intersection of all inductive subsets of \mathbb{R} . Therefore, it holds that $0 \in \mathbb{N}_0$, since $0 \in M$ for all inductive sets $M \subset \mathbb{R}$.

Additionally, let
$$x \in \mathbb{N}_0 \implies x \in M$$
 for all inductive subsets $M \subset \mathbb{R}$
 $\Rightarrow x + 1 \in M$ for all inductive subsets $M \subset \mathbb{R}$
 $\Rightarrow x + 1 \in \mathbb{N}_0$.

Therefore, \mathbb{N}_0 is inductive and since $\mathbb{N}_0 \subset M$ for all inductive sets $M \subset \mathbb{R}$, then \mathbb{N}_0 is the smallest inductive subset of \mathbb{R} .

- **1.9 Corollary.** (Induction). Let $N \subset \mathbb{N}_0$ be a set with the following properties:
 - $a) \ 0 \in N$

$$b) \ x \in N \Rightarrow x + 1 \in N$$

Then $N = \mathbb{N}_0$.

The proof is obvious since \mathbb{N}_0 is the smallest inductive subset of \mathbb{R} .

This corollary enables us to consider the method of proof by induction.

- **1.10 Theorem.** For every $n \in \mathbb{N}_0$ let the proposition A(n) be defined. If it holds that:
 - a) A(0) is true (Induction Start).
 - b) If A(n) is true, then A(n+1) is also true (Induction Step).

Then A(n) holds for all $n \in \mathbb{N}_0$.

Proof. Set $N := \{n \in \mathbb{N}_0 : A(n) \text{ is true }\} \Rightarrow N \subset \mathbb{N}_0 \text{ inductive } \stackrel{1.9}{\Rightarrow} N = \mathbb{N}_0.$

The assumption in b) that A(n) is true is called the Induction Hypothesis.

1.11 Examples.

a) The Bernoulli Inequality: Let x > -1 and $n \in \mathbb{N}_0$. Then

$$(1+x)^n > 1 + nx.$$

The proof is left as an exercise.

b) Geometric Series: Let $q \in \mathbb{R}$ with $q \neq 1$ and $n \in \mathbb{N}_0$. Then

$$q^{0} + q^{1} + q^{2} \cdots + q^{n} = \frac{1 - q^{n+1}}{1 - q}.$$

Proof. Induction Start: A(0) is true since $q^0 = 1 = \frac{1-q}{1-q} = 1$. *Induction Step (IS):*

By assumption, A(n) is true. Then:

$$\underbrace{q^{0} + q^{1} + \dots + q^{n}}_{} + q^{n+1} = \frac{1 - q^{n+1}}{1 - q} + q^{n+1} = \frac{1 - q^{n+1} + (1 - q)q^{n+1}}{1 - q}$$

$$= \frac{1 - q^{n+2}}{1 - q}$$

Therefore A(n) holds for all $n \in \mathbb{N}_0$.

1.12 Theorem. (Properties of \mathbb{N}_0). The following statements hold:

- $a) \ 0, 1 \in \mathbb{N}_0$
- b) $n \in \mathbb{N}_0 \Rightarrow n = 0 \text{ or } n > 1$
- c) $n, m \in \mathbb{N}_0 \Rightarrow n + m, n \cdot m \in \mathbb{N}_0$
- d) $n, m \in \mathbb{N}_0, n \geq m \Rightarrow n m \in \mathbb{N}_0$
- e) Let $n \in \mathbb{N}_0$. There does not exist an $m \in \mathbb{N}_0$ such that n < m < n + 1.
- f) Every nonempty set M of nonnegative integers contains a smallest element, i.e. let $M \neq \emptyset$, $M \subset \mathbb{N}_0 \Rightarrow \exists m \in M \text{ with } m \leq n \ \forall n \in M$.

Proof. a) $0 \in \mathbb{N}_0$ by definition and \mathbb{N}_0 is inductive. Therefore $0+1=1 \in \mathbb{N}_0$. b) Set $B := \{0\} \cup \{n \in \mathbb{N}_0 : n-1 \in \mathbb{N}_0 \text{ and } n-1 \geq 0\} \subset \mathbb{N}_0$. Then B is inductive. In fact, $0 \in B$. Additionally, let $n \in B$. We need to show that $n+1 \in B$. If n=0, then it follows that $n+1=1 \in B$. If $n \neq 0$, then $0 \leq n-1 \Rightarrow 0 < 1 \leq n = (n+1)-1 \in \mathbb{N}_0$ and therefore $n+1 \in B$. $\Rightarrow B = \mathbb{N}_0$ and therefore, the claim. (c)d)e)f as exercises

1. THE REAL NUMBERS

7

1.13. A Variant of the Induction Principle.

If for some $n_0 \in \mathbb{N}_0$:

- a) $A(n_0)$ is true.
- b) $A(n_0), A(n_0+1), \dots A(n)$ being true $\Rightarrow A(n+1)$ is also true Then A(n) is true for all $n \ge n_0$.

Thus one can show, for example, that $2^n > n^2$ if $n \ge 5$.

1.14. Examples of Induction. We now consider recursive definitions:

a) Powers: For $x \in \mathbb{R}$ set

$$\begin{array}{rcl}
x^0 & := & 1 \\
x^{n+1} & := & x \cdot x^n, & n \in \mathbb{N}_0
\end{array}$$

b) Factorials:

$$0! := 1
(n+1)! := (n+1) \cdot n!, \quad n \in \mathbb{N}_0$$

c) Finite Series and Products: Let $a_j \in \mathbb{R}$ for $j \in \mathbb{N}_0$. We set

$$\sum_{j=0}^{0} a_j := a_0, \quad \sum_{j=0}^{n+1} a_j := a_{n+1} + \sum_{j=0}^{n} a_j, \quad n \in \mathbb{N}_0$$

$$\prod_{j=0}^{0} a_j := a_0, \quad \prod_{j=0}^{n+1} a_j := a_{n+1} \cdot \prod_{j=0}^{n} a_j, \quad n \in \mathbb{N}_0.$$

Analogously, we define

$$\sum_{j=l}^{n} a_j \quad \text{and} \quad \prod_{j=l}^{n} a_j, \qquad n \ge l$$

d) Binomial coefficients: For $a \in \mathbb{R}$, $n \in \mathbb{N}_0$, set

$$\begin{pmatrix} a \\ 0 \end{pmatrix} := 1, \quad \begin{pmatrix} a \\ n+1 \end{pmatrix} := \frac{a-n}{n+1} \begin{pmatrix} a \\ n \end{pmatrix}$$

The following statements can be proved by induction:

- i) Let $a \in \mathbb{R}$ and $n, m \in \mathbb{N}_0 \Rightarrow a^n \cdot a^m = a^{n+m}$
- ii) For $n, k \in \mathbb{N}_0$ with $0 \le k \le n$, we have $\binom{n}{k} = \frac{n!}{k!(n-k)!}$
- iii) For $n, k \in \mathbb{N}_0$, we have $\binom{n}{k} = \begin{cases} \binom{n}{n-k} & \text{falls } k \leq n \\ 0 & \text{falls } k > n \end{cases}$
- iv) For $n, k \in \mathbb{N}_0$, we have $\binom{n}{k} + \binom{n}{k+1} = \binom{n+1}{k+1}$ "Pascal's Triangle"
- **1.15 Theorem.** (Binomial Theorem). Let $a, b \in \mathbb{R}$ and $n \in \mathbb{N}_0$. Then

$$(a+b)^n = \sum_{j=0}^n \binom{n}{j} a^j b^{n-j}.$$

Proof. Induction Start: For n = 0, it holds that:

$$1 = (a+b)^0 = \sum_{j=0}^{0} {0 \choose j} a^0 b^0 = 1.$$

Induction Step: Let the statement from the theorem hold for some $n \in \mathbb{N}_0$: Then

$$(a+b)^{n+1} = (a+b)(a+b)^{n}$$

$$= (a+b)\sum_{j=0}^{n} \binom{n}{j} a^{j} b^{n-j}$$

$$= \sum_{j=0}^{n} \binom{n}{j} a^{j+1} b^{n-j} + \sum_{j=0}^{n} \binom{n}{j} a^{j} b^{n-j+1}$$

$$= \sum_{j=1}^{n+1} \binom{n}{j-1} a^{j} b^{n-(j-1)} + \sum_{j=0}^{n} \binom{n}{j} a^{j} b^{n-j+1}$$

$$= \sum_{j=1}^{n} \left[\binom{n}{j-1} + \binom{n}{j} \right] a^{j} b^{n-j+1} + \binom{n}{0} a^{0} b^{n+1} + \binom{n}{n} a^{n+1} b^{0}$$

$$= \sum_{j=0}^{n+1} \binom{n+1}{j} a^{j} b^{n-j+1},$$

i.e. the statement from the theorem also holds for n+1.

1. THE REAL NUMBERS

9

1.16 Definition. a) A set $M \subset \mathbb{R}$ is said to be bounded from above (nach oben beschränkt), if there exists an $s \in \mathbb{R}$ such that

$$m \leq s$$
 for all $m \in M$.

If this is the case, s is called an *upper bound (obere Schranke)* of M.

b) An upper bound s_0 is called the *least upper bound (kleinste obere Schranke)* or the supremum of $M \subset \mathbb{R}$, if for every upper bound s of M,

$$s_0 \leq s$$
.

Remark. a) If s_0, s'_0 are both least upper bounds of M, it follows that $s_0 \le s'_0, s'_0 \le s_0$, therefore $s_0 = s'_0$. Therefore the supremum is uniquely (eindeutig) determined.

b) The following axiom states that there exists a supremum in any nonempty upper bounded set of real numbers.

1.17. Completeness Axiom. Let $M \subset \mathbb{R}$ be a nonempty set with an upper bound. Then M has a supremum s_0 . We define $\sup M := s_0$.

Now we have axiomatically introduced \mathbb{R} as a set that is equipped with addition +, multiplication \cdot , and order <, and that satisfies the field-, order- and completeness axioms.

1.18 Definition. Let $\emptyset \neq M \subset \mathbb{R}$ and $s_0 = \sup M$. If $s_0 \in M$, then s_0 is called the maximum of M. We define $\max M := s_0$.

1.19 Examples. a) Let $M := \{x \in \mathbb{R}, x < 1\}$. Then $\sup M = 1 =: s_0$, although M has no maximum. $s_0 = 1$ is clearly an upper bound of M. Assume there exists an upper bound s < 1 of M. $\stackrel{1.6.h}{\Rightarrow} s < \frac{s+1}{2} < 1$ this contradicts the assumption that s is an upper bound of M. Additionally, $1 \notin M$, therefore $s_0 = 1$ is not a maximum.

b) Let $a \geq 0$ and $M := \{x \in \mathbb{R} : x^2 \leq a\}$. Then M is bounded from above, for example by $1 + \frac{a}{2}$. Furthermore, M is obviously nonempty, as $0 \in M$. Therefore, the completeness axiom implies that $s_0 := \sup M$ exists. Moreover, we have

$$s_0^2 = a.$$

Proof.

i) If a = 0, then we have $s_0 = 0$. In the following, we therefore assume that a > 0.

ii) We first prove $s_0^2 \ge a$: We assume the statement is false. Then $a-s_0^2>0$, therefore $\varepsilon:=\frac{a-s_0^2}{2s_0+1}>0$.

Furthermore we have $\varepsilon < 1$, because $\varepsilon \ge 1$ would imply that

$$a - s_0^2 \ge 2s_0 + 1 \Leftrightarrow a \ge s_0^2 + 2s_0 + 1 = (s_0 + 1)^2$$
.

This would imply $s_0 + 1 \in M$ and hence $s_0 + 1 \leq \sup M = s_0$. Contradiction! Therefore

$$(s_0 + \varepsilon)^2 = s_0^2 + 2s_0\varepsilon + \varepsilon^2 < s_0^2 + (2s_0 + 1)\varepsilon = s_0^2 + a - s_0^2 = a.$$

Hence $s_0 + \varepsilon \in M$ and consequently $s_0 + \varepsilon \leq s_0$, contradicting the definition of s_0 . Therefore, $s_0^2 \geq a$.

iii) Now we prove $s_0^2 \leq a$: Assume that the statement is false. Then, $s_0^2 - a > 0$. Define $\delta := \frac{s_0^2 - a}{2s_0} > 0$. Then $s := s_0 - \delta = \frac{2s_0^2 - s_0^2 + a}{2s_0} = \frac{s_0^2 + a}{2s_0} > 0$ and $s^2 = s_0^2 - 2s_0\delta + \delta^2 = s_0^2 - s_0^2 + a + \delta^2 = a + \delta^2 > a$. Therefore $s^2 > a \geq x^2$ for all $x \in M$ and s > x for all $x \in M$. Hence $s^2 < s_0^2$ is an upper bound of M in contradiction to the minimality of s_0 .

Statements ii) and iii) imply $s_0^2 = a$.

- c) Corollary. For every real number a > 0, there exists exactly one real number w > 0 with $w^2 = a$. The number w is called the square root (Wurzel) of a and is denoted by $w = \sqrt{a}$.
- **1.20 Definition.** a) A set $M \subset \mathbb{R}$ is said to be bounded from below (nach unten beschränkt), if there exists an $r \in \mathbb{R}$ such that

$$r < m$$
 for all $m \in M$.

In this case, r is called a *lower bound* (untere Schranke) of M.

b) A lower bound r_0 is called the greatest lower bound (größte untere Schranke) or the infimum, if for all lower bounds r of M,

$$r < r_0$$
.

We define $\inf M := r_0$.

- c) If $r_0 \in M$, then r_0 is called the *minimum* of M, and we define min $M := r_0$.
- d) If $M \subset \mathbb{R}$ is bounded from above and below, then M is called bounded (beschränkt).

1. THE REAL NUMBERS

11

1.21 Lemma. Let $M \subset \mathbb{R}$ and $-M := \{-m : m \in M\}$. Then the following statements hold:

- a) M is bounded from below \Leftrightarrow -M is bounded from above.
- b) Every nonempty set M that is bounded from below has an infimum. The infimum is uniquely determined.
- c) $M \neq \emptyset$ is bounded from below \Rightarrow inf $M = -\sup(-M)$.

Proof. Exercise

1.22 Theorem. (Characterization Theorem for Suprema). Let $\emptyset \neq M \subset \mathbb{R}$ be an upper bounded set and $s_0 \in \mathbb{R}$. Then:

 $\sup M = s_0 \Leftrightarrow For \ all \ m \in M \ we \ have \ m \leq s_0, \ and \ moreover, \ to \ each \ \varepsilon > 0 \ there$ exists an $m_1 \in M$ such that $m_1 > s_0 - \varepsilon$.

Proof. \Rightarrow : Let $s_0 = \sup M$. Then $m \leq s_0$ for all $m \in M$. Assume there exists $\varepsilon > 0$ such that for all $m_1 \in M$ we have $m_1 \leq s_0 - \varepsilon$. Then $s := s_0 - \varepsilon$ is an upper bound. Contradiction!

 \Leftarrow : Let s_0 be an upper bound of M. Assume there exists $s \in \mathbb{R}$ such that $s < s_0$ and $m \le s \ \forall \ m \in M$. Set $\varepsilon := s_0 - s > 0$. Then $s = s_0 - \varepsilon$ and $m \le s_0 - \varepsilon \ \forall \ m \in M$. Contradiction!

To conclude this section, we define the natural numbers $\mathbb N$ and the integers $\mathbb Z$ as

$$\mathbb{N} := \mathbb{N}_0 \setminus \{0\} \text{ and } \mathbb{Z} := \mathbb{N}_0 \cup \{-n : n \in \mathbb{N}\}.$$

The set \mathbb{Q} of rational numbers is then given as

$$\mathbb{Q} := \{ p/q : p, q \in \mathbb{Z}, q \neq 0 \};$$

Furthermore, we call the elements of $\mathbb{R} \setminus \mathbb{Q}$ irrational numbers.

- **1.23 Corollary.** a) \mathbb{N}_0 is not bounded from above.
 - b) Archimedes' Principle: $\forall a > 0, b \in \mathbb{R} \ \exists n \in \mathbb{N}_0 \ such \ that \ n \cdot a > b.$
 - c) "Classical Method of Deduction" in Analysis: If $0 \le a < \frac{1}{n}$ for all $n \in \mathbb{N}$, then a = 0. (Recall $\mathbb{N} := \mathbb{N}_0 \setminus \{0\}$.)

Proof. a) Assume \mathbb{N}_0 is bounded from above. Then there exists an $s_0 = \sup \mathbb{N}_0$ by the Completeness Axiom. The Characterization Theorem of sup (see Theorem 1.22) with $\varepsilon = 1$ implies that there exists an $n \in \mathbb{N}_0$ with $n > s_0 - 1$. $\Rightarrow n + 1 > s_0$ in contradiction to the definition of s_0 .

- b) Assume $n \cdot a \leq b$ for all $n \in \mathbb{N}_0$. Then \mathbb{N}_0 is bounded from above by $\frac{b}{a}$. Contradiction to a)!
- c) Assume a > 0. Then $n \cdot a < 1$ for all $n \in \mathbb{N}_0$ in contradiction to b).

2 The Complex Numbers

In this chapter we give an axiomatic introduction to the field of complex numbers and begin with the following definition:

2.1 Definition. On $\mathbb{R}^2 := \{(a, b) : a, b \in \mathbb{R}\}$ we define addition and multiplication as follows:

Addition
$$\oplus : \mathbb{R}^2 \times \mathbb{R}^2 \to \mathbb{R}^2 : (a,b) \oplus (c,d) := (a+c,b+d)$$

Multiplication $\odot : \mathbb{R}^2 \times \mathbb{R}^2 \to \mathbb{R}^2 : (a,b) \odot (c,d) := (ac-bd,ad+bc)$

Then for x=(a,b),y=(c,d) and $z=(e,f)\in\mathbb{R}^2,\oplus$ and \odot fulfill the field axioms from § 1, where

For the proof of this fact we refer to linear algebra. \mathbb{R}^2 equipped with \oplus and \odot is therefore a field, which we call the field of *complex numbers*, denoted by \mathbb{C} .

For $(a,0) \in \mathbb{C}$ we have

$$(a,0) \oplus (b,0) = (a+b,0),$$

 $(a,0) \odot (b,0) = (a \cdot b,0),$

i.e. if one identifies $a \in \mathbb{R}$ with $(a,0) \in \mathbb{C}$, then \mathbb{R} is a subfield of \mathbb{C} .

2.2 Definition. We define $i := (0,1) \in \mathbb{C}$. The number $i \in \mathbb{C}$ is called the *imaginary* unit (imaginare Einheit).

Then by definition of \odot :

$$i^2 = (0,1) \odot (0,1) = (-1,0) = -1.$$

i.e. i is a solution to the equation $x^2 + 1 = 0$.

2.3 Remark. The field \mathbb{C} cannot be ordered, i.e. there cannot exist a relation "<", such that in \mathbb{C} the ordering axioms from Chapter 1 hold. For if it were the case that such an ordering existed, then in the same way as for \mathbb{R} we would be able to prove that $x^2 > 0$ for all $x \in \mathbb{C}$ s.t. $x \neq 0$. Thus we would get $-1 = i^2 > 0$. But we can prove that -1 < 0, so this is a contradiction.

2.4 Remark. Let $z=(a,b)\in\mathbb{C}$ with $a,b\in\mathbb{R}$. Then

$$(a,b) = \underbrace{(a,0)}_{=a} \oplus \underbrace{(0,1)}_{=i} \odot \underbrace{(b,0)}_{=b}.$$

If we identify a with (a,0) as above, then we get that

$$\mathbb{C} \ni (a, b) = z = a + i \cdot b.$$

The real number a is called the real part (Realteil) of z = a + ib and is denoted by Re(z) = a. The number b is called the imaginary part (Imaginärteil) of z = a + ib. We set Im(z) = b.

- **2.5 Definition.** (Conjugation and Absolute Value).
 - a) Let $a, b \in \mathbb{R}$ and $z = a + ib \in \mathbb{C}$. The complex number

$$\overline{z} := a - ib$$

is called the *complex conjugate* of z.

b) The absolute value |z| of z is defined as $|z| := \sqrt{z\overline{z}} = \sqrt{a^2 + b^2} \ge 0$.

For $z \in \mathbb{R}$ the definition coincides with that of Section 1.

- **2.6 Lemma.** (Calculation Rules for Complex Numbers). For complex numbers $z, w \in \mathbb{C}$, we have the following calculation rules:
 - a) Re(z+w) = Re(z) + Re(w), Im(z+w) = Im(z) + Im(w)
 - $b) \ \overline{z+w} = \overline{z} + \overline{w}, \quad \overline{z\cdot w} = \overline{z} \cdot \overline{w}$
 - $c) \ z \cdot \overline{z} = |z|^2$
 - d) $z = 0 \Leftrightarrow |z| = 0 \Leftrightarrow Re(z) = 0 = Im(z)$
 - $e) |z| = |\overline{z}|$
 - $f) |z+w| \le |z| + |w|$

Proof. Exercise

Chapter II

Convergence of Sequences and Series

Many of the basic theorems about infinite sequences and series, that we will examine in the following, are due to Augustin-Louis Cauchy (1789–1857), one of the greatest french mathematicians of his time. Already as a twelve year old pupil, he stood out because of his talent, why Lagrange said about him

Vous voyez ce petit jeune homme, eh bien! il nous remplacera tous tant que nous sommes de géomètres.

and advised Cauchy's father

Don't let this child touch a mathematical book before his seventeenth year. If you do not hurry up to give him a solid literary education, his inclination will carry him away.

In 1816, Cauchy was appointed a position as professor at the Ecole Polytechnique in Paris and his three textbooks *Cours d'Analyse*, *Résumé des leçons sur le calcul infinitésimal*, *Leçons sur le calcul différentiel* are said to have introduced the formal rigour in modern analysis. The systematic way, in which the theory of infinite series is developed in *Cours d'Analyse* is still exemplary today.

The infinitely small quantities, that were used by Cauchy, were replaced by precise and clear expressions involving inequalities by Karl Weierstrass (1815–1897). Thereby, a standardised choice of variable names proved very useful. ε is used as an arbitrarily small positive number (probably derived from the french erreur), and δ is the number that corresponds to ε .

From 1864 on, Weierstrass taught at the university of Berlin. In his lectures, he treats the convergence of sequences and series and, more generally, the infinitesimal calculus in 'Weierstrassian rigour' and thus became the father of 'epsilonics' which is standard today in any lecture about analysis.

1 Convergence of Sequences

We begin this chapter, which is very important for this analysis class and for the further development of analysis, by some remarks on functions and their properties.

1.1. Introduction.

a) Let X, Y be two sets. A function or a mapping $f: X \to Y$ is a rule, which assigns to every $x \in X$ one unique element $y \in Y$. We write

$$f: X \to Y, x \mapsto f(x)$$
.

- b) The set graph $(f) := \{(x, f(x)) : x \in X\} \subset X \times Y \text{ is called the graph of } f.$
- c) Two functions $f, g: X \to Y$ are equal, if f(x) = g(x) for all $x \in X$.
- d) The set $\operatorname{Fun}(X,Y)$ is defined to be the set of all functions $f:X\to Y$.
- e) Let $f: X \to Y$ be a function. Then X is called the *domain* of f and f(X) is called the *range* of f. Further we say:

f is called *injective*, if $x_1, x_2 \in X, x_1 \neq x_2 \Rightarrow f(x_1) \neq f(x_2)$ f is called *surjective*, if f(X) = Y.

f is called *bijective*, if f is injective and surjective.

f) If $Y \subset \mathbb{R}$ $(Y \subset \mathbb{C})$ holds, then f is called a real-valued (complex-valued) function.

Let M be a set. We call a mapping $f: \mathbb{N} \to M$, which assigns an element a_n of M to each $n \in \mathbb{N}$, a sequence in M. If we let $a_n := f(n)$ for all $n \in \mathbb{N}$, we write $(a_n)_{n \in \mathbb{N}}$. If we have $a_n \in \mathbb{R}$ for all $n \in \mathbb{N}$, then $(a_n)_{n \in \mathbb{N}}$ is called a real sequence; analogously, if we have $a_n \in \mathbb{C}$, $n \in \mathbb{N}$, then $(a_n)_{n \in \mathbb{N}}$ is called a complex sequence. Occasionally it is convenient to start a sequence with a_0 . In this case, the sequence is a mapping $\mathbb{N}_0 \to M$ and we write $(a_n)_{n \in \mathbb{N}_0}$

1.2 Definition. A complex sequence $(a_n)_{n\in\mathbb{N}_0}$ converges to $a\in\mathbb{C}$, if

$$(\forall \varepsilon > 0) (\exists N_0 \in \mathbb{N}) (\forall n > N_0) |a - a_n| < \varepsilon.$$

The number a is called the *limit value* or just *limit* of the sequence $(a_n)_{n\in\mathbb{N}}$ and we write

$$\lim_{n \to \infty} a_n = a \quad \text{or} \quad a_n \stackrel{n \to \infty}{\longrightarrow} a.$$

If there exists an $a \in \mathbb{C}$ with $\lim a_n = a$, then $(a_n)_{n \in \mathbb{N}_0}$ is called a convergent sequence, otherwise a divergent sequence. If $(a_n)_{n \in \mathbb{N}_0}$ converges to 0, then $(a_n)_{n \in \mathbb{N}_0}$ is called a null sequence.

1. CONVERGENCE OF SEQUENCES

17

1.3 Remarks. a) The limit is uniquely determined, i.e.

$$\begin{vmatrix} a_n \to a^* \\ a_n \to a_* \end{vmatrix} \Rightarrow a^* = a_*$$

Proof. Let $\varepsilon > 0$ be arbitrarily chosen. Then $n_0^1, n_0^2 \in \mathbb{N}_0$ exist, with:

$$|a_n - a^*| < \frac{\varepsilon}{2} \quad \forall \ n \ge n_0^1$$
$$|a_n - a_*| < \frac{\varepsilon}{2} \quad \forall \ n \ge n_0^2$$

Here $a^* - a_* = a^* - a_n + a_n - a_*$ implies

$$0 \le |a^* - a_*| \le |a^* - a_n| + |a_n - a_*| < \varepsilon \ \forall \ n \ge \max\{n_0^1, n_0^2\},$$

i.e. $|a^* - a_*| = 0 \Leftrightarrow a^* = a_*$ due to the classical conclusion method of Analysis (Chapter I, 1.23).

b) If a_n is defined only for $n \geq N$, then we denote (a_N, a_{N+1}, \cdots) as a sequence too, and write $(a_n)_{n>N}$.

1.4 Examples.

- a) For $a \in \mathbb{C}$, the constant sequence (a, a, \cdots) converges to a.
- b) The sequence $(\frac{1}{n})_{n\geq 1}$ is a null sequence. We prove this as follows: Let $\varepsilon>0$ be arbitrary. By the Archimedean Property I 1.23 there exists $n_0\in\mathbb{N}_0$ with $n_0\cdot\varepsilon>1$. Thus:

$$|0 - \frac{1}{n}| \le \frac{1}{n_0} < \varepsilon, \quad \forall \ n \ge n_0$$

c) The sequence $(\frac{n}{n+1})_{n\in\mathbb{N}}$ converges to 1.

Again choose $\varepsilon > 0$ arbitrarily. By the Archimedean Property I 1.23 there exists $n_0 \in \mathbb{N}_0$ with $n_0 \cdot \varepsilon > 1$. Thus:

$$|1 - \frac{n}{n+1}| = |\frac{1}{n+1}| < \frac{1}{n_0} < \varepsilon, \quad \forall \ n \ge n_0.$$

d) Let $a_n := \sum_{i=1}^n \frac{1}{j(j+1)}$ for $n \ge 1$.

Since $\frac{1}{j(j+1)} = \frac{1}{j} - \frac{1}{j+1}$, it follows that $a_n = 1 - \frac{1}{n+1}$; hence $a_n \to 1$ for $n \to \infty$.

e) Let $a_n = (-1)^n$. Then $(a_n)_{n \in \mathbb{N}_0}$ diverges: Assume for the moment that (a_n) converges to $a \in \mathbb{C}$. Then there exists $n_0 \in \mathbb{N}$ with $|a - a_n| < \frac{1}{2} \, \forall \, n \geq n_0$. Thus

$$2 = |a_{n+1} - a_n| \le |a_{n+1} - a| + |a - a_n| < \frac{1}{2} + \frac{1}{2} = 1.$$

Here we get a contradiction, which means that $(a_n)_{n\in\mathbb{N}}$ is divergent.

1.5 Definition. A sequence $(a_n)_{n\geq 1}\subset \mathbb{C}$ is called *bounded*, if there exists a constant M>0 with

$$|a_n| \leq M \quad \forall \ n \in \mathbb{N}.$$

1.6 Theorem. Every convergent sequence $(a_n)_{n\geq 0}$ is bounded.

Proof. Let $\lim_{n\to\infty} a_n = a \in \mathbb{C}$. By hypothesis, in particular for $\varepsilon = 1$ there exists $n_0 \ge 1$ with $|a - a_n| < 1$ for all $n \ge n_0$. Thus for $n \ge n_0$ we have:

$$|a_n| \le |a_n - a| + |a| \le 1 + |a|.$$

Hence

$$|a_n| \le \max \underbrace{\{|a_0|, |a_1|, \cdots |a_{n_0-1}|, 1+|a|\}}_{\text{finitely many}} =: M \quad \forall \ n \in \mathbb{N}_0.$$

1.7 Examples. a) The sequence $((-1)^n)_{n\in\mathbb{N}}$ is bounded, but not convergent.

- b) For $q \in \mathbb{C}$ let $a_n := q^n$. Then:
 - i) if |q| > 1, then (a_n) is not bounded, thus divergent.
 - ii) if |q| < 1, then (a_n) is a null sequence.

1.8 Lemma. (Calculation rules for convergent sequences). Let $(a_n)_{n\in\mathbb{N}_0}$ and $(b_n)_{n\in\mathbb{N}_0}$ be two convergent sequences with $\lim_{n\to\infty} a_n = a$ and $\lim_{n\to\infty} b_n = b$. Then the following statements hold:

- a) $(a_n + b_n) \xrightarrow{n \to \infty} a + b$
- b) $(a_n \cdot b_n) \stackrel{n \to \infty}{\longrightarrow} ab$
- c) If $b \neq 0$, then there exists $n_0 \in \mathbb{N}_0$ with $b_n \neq 0 \ \forall \ n \geq n_0$ and $\frac{a_n}{b_n} \xrightarrow{n \to \infty, \ n \geq n_0} \frac{a}{b}$.

Proof. a) Let $\varepsilon > 0$ be arbitrary. Then there exist $n_1, n_2 \in \mathbb{N}_0$ with

$$|a - a_n| < \frac{\varepsilon}{2}, \quad \forall n \ge n_1,$$

 $|b - b_n| < \frac{\varepsilon}{2}, \quad \forall n \ge n_2.$

1. CONVERGENCE OF SEQUENCES

19

For $n_0 := \max\{n_1, n_2\}$ holds:

$$|a+b-(a_n+b_n)| \le \underbrace{|a-a_n|}_{<\frac{\varepsilon}{2}} + \underbrace{|b-b_n|}_{<\frac{\varepsilon}{2}} < \varepsilon \quad \forall \ n \ge n_0,$$

thus the claim.

- b) Exercise.
- c) Exercise.

The following example illustrates the above calculation rules for convergent sequences. For $n \geq 2$, we let

$$a_n = \frac{3n^2 - 2n + 1}{-n^2 + n} = \frac{3 - \frac{2}{n} + \frac{1}{n^2}}{-1 + \frac{1}{n}}.$$

Now the above Lemma 1.8 implies that $\lim_{n\to\infty} a_n = -3$.

An important approach to determine whether a given sequence converges is to estimate its terms by the terms of a convergent sequence. For that, we have to assure that convergence and order are compatible. This is the statement of the following lemma.

1.9 Lemma. (Compatibility of convergence and order). Let $(a_n)_{n\in\mathbb{N}_0}$ and $(b_n)_{n\in\mathbb{N}_0}$ be two real and convergent sequences with $\lim a_n = a$ and $\lim b_n = b$. If a number $n_0 \in \mathbb{N}$ exists with $a_n \leq b_n$ for all $n \geq n_0$, then $a \leq b$ holds.

Proof. Assume, that a > b. Then $\varepsilon := \frac{a-b}{2} > 0$ and hence, by hypotheses, there exists $n_0 \in \mathbb{N}$ with

$$\begin{aligned} a - a_n &\leq |a - a_n| < \varepsilon \quad \forall \ n \geq n_0, \\ b_n - b &\leq |b - b_n| < \varepsilon \quad \forall \ n \geq n_0. \end{aligned}$$

Thus

$$b_n < b + \varepsilon = \frac{2b}{2} + \frac{a-b}{2} = \frac{a+b}{2} = a - \varepsilon < a_n \quad \forall \ n \ge n_0.$$

Contradiction!

1.10 Corollary. (Sandwich Theorem). Let $(a_n)_n$, $(b_n)_n$ and $(c_n)_n$ be real sequences, for which $\lim a_n = a$ and $\lim b_n = a$. Let also $n_0 \in \mathbb{N}$ exist with

$$a_n < c_n < b_n, \ \forall \ n > n_0.$$

Then $\lim_{n\to\infty} c_n = a$.

П

Proof. Exercise.

Criteria which imply the convergence of a sequence without explicit knowledge about the limit are especially important. For this, we introduce the following notions.

- **1.11 Definition.** A real sequence $(a_n)_{n\in\mathbb{N}}$ is called
- a) (monotone) increasing, if $a_{n+1} \geq a_n$ for all $n \in \mathbb{N}$
- b) strictly (monotone) increasing, if $a_{n+1} > a_n$ for all $n \in \mathbb{N}$
- c) (monotone) decreasing, if $a_{n+1} \leq a_n$ for all $n \in \mathbb{N}$
- d) strictly (monotone) decreasing, if $a_{n+1} < a_n$ for all $n \in \mathbb{N}$.

If one of the cases i)-iv) holds, then (a_n) is simply called *monotone*.

- **1.12 Theorem.** Every bounded and monotone real sequence $(a_n)_{n\geq 1}$ converges.
 - a) If (a_n) is increasing, then $a_n \to \sup\{a_n, n \in \mathbb{N}\}.$
 - b) If (a_n) is decreasing, then $a_n \to \inf\{a_n, n \in \mathbb{N}\}$.

Proof. a) The hypothesis implies that $s := \sup\{a_n : n \in \mathbb{N}\}$ exists. Let $\varepsilon > 0$ be given. The characterisation of the supremum from Theorem I 1.22 implies that there exists $n_0 \in \mathbb{N}$ with

$$s - \varepsilon < a_{n_0} \le a_n \le s \quad \forall \ n \ge n_0.$$

Hence, $-\varepsilon < a_n - s \le 0 \quad \forall \ n \ge n_0 \text{ and thus } |a_n - s| < \varepsilon \ \forall \ n \ge n_0.$

b) Exercise

We now apply the theorem above to define the root function.

1.13 Theorem. Let a > 0 and $k \in \mathbb{N}$ with $k \geq 2$. Then there exists one and only one real number w > 0 with $w^k = a$. In this case we write $\sqrt[k]{a} := a^{1/k} := w$.

Proof. We begin with the *existence* of the number w. For this we define the sequence (a_j) recursively via

$$a_0 := a + 1, \quad a_{j+1} := a_j \left(1 + \frac{a - a_j^k}{k \cdot a_j^k} \right), \quad j \in \mathbb{N}_0.$$

Then we claim:

- a) $a_j > 0 \quad \forall j \in \mathbb{N}_0$
- b) $a_j^k \ge a \quad \forall j \in \mathbb{N}_0$

1. CONVERGENCE OF SEQUENCES

21

c) $a_{j+1} \leq a_j \quad \forall j \in \mathbb{N}_0$, i.e. (a_j) is monotone decreasing.

We prove this by induction.

n=0: It is trivial that $a_0>0$, $a_0^k\geq a$ and $a_1\leq a_0$.

Induction step: Let $n \in \mathbb{N}_0$ be such that $a_n > 0$, $a_n^k \ge a$ and $a_{n+1} \le a_n$. $ka_n^k + a - a_n^k > 0$, hence $a_{n+1} > 0$. By the Bernoulli inequality we have

$$a_{n+1}^k = a_n^k \left(1 + \frac{a - a_n^k}{k a_n^k} \right)^k \ge a_n^k \left(1 + \frac{k(a - a_n^k)}{k a_n^k} \right) = a,$$

i.e. $a_{n+1}^k \ge a$. Finally, $a_{n+2} \le a_{n+1}$ since $a - a_{n+1}^k \le 0$. Thus the properties a), b) and

So $(a_j)_{j\in\mathbb{N}_0}$ is a bounded and monotone decreasing sequence. Therefore, Theorem 1.12 implies that

$$w := \lim_{j \to \infty} a_j = \inf\{a_j : j \in \mathbb{N}\}.$$

Further $\lim_{j\to\infty} a_{j+1} = w$ and $(\lim_{j\to\infty} a_j)^k = \lim_{j\to\infty} a_j^k \ge a > 0$. In addition

$$w \leftarrow a_{j+1} = a_j \left(1 + \frac{a - a_j^k}{k \cdot a_j^k} \right) \to w \cdot \left(1 + \frac{a - w^k}{k \cdot w^k} \right),$$

thus $w = w(1 + \frac{a - w^k}{k \cdot w^k})$, and so $a = w^k$. Uniqueness. Let u, v > 0 with $u^k = w = v^k$ and $u \neq v$. Without loss of generality, let u < v. Then $w = u^k < v^k = w$. Contradiction!

At this point, we want to give a geometric interpretation of the sequence $(a_i)_{i\in\mathbb{N}_0}$. This sequence is the foundation for a method to calculate approximations of the root of a given number - cf. also the 'Newton method'. Consider the tangent of the function $f(x) = x^k - a$ at the point $x = a_i$. This tangent intersects the x-axis in the point $x = a_{j+1}$. We furthermore remark that this method converges for every initial value $a_1 > 0$ and that there exists a constant M > 0 with $|\sqrt[k]{a} - a_{j+1}| \leq M|\sqrt[k]{a} - a_{j}|^2$, $j \in \mathbb{N}$. We therefore speak of quadratic convergence of the method.

1.14 Remark. Starting from the n-th root $\sqrt[n]{a}$ of a real number $a \geq 0$, for $p, q \in \mathbb{N}$ we define more generally

$$a^{p/q} := (a^{1/q})^p = (a^p)^{1/q},$$

and for a > 0

$$a^{-p/q} := (a^{-1})^{p/q}.$$

If we furthermore define $a^0 = 1$, we obtain by induction the following calculation rules

$$a^{p+q} = a^p a^q, \quad a^{pq} = (a^p)^q, \quad a^p b^p = (ab)^p$$

for a > 0, b > 0 and $p, q \in \mathbb{Q}$. The general power a^x for a > 0 and $x \in \mathbb{R}$ will be defined later via the exponential function; therefore we do not elaborate the above elementary examination of the powers with rational exponent any further.

Now, we come to another application of Theorem 1.12

1.15 Theorem. (The number e). Let $(a_n)_{n\geq 1}$ be the sequence defined by

$$a_n := \left(1 + \frac{1}{n}\right)^n, \quad n \ge 1.$$

Then $(a_n)_{n\geq 1}$ converges. The limit, called Euler's number, is denoted by e and satisfies

$$2 \le \lim_{n \to \infty} a_n = e \le 3.$$

Proof. By Theorem 1.12 and Lemma 1.9 it is enough to show that

- a) (a_n) is increasing and
- b) $2 \le a_n \le 3$ for all $n \ge 1$.

Proof of a). For $n \geq 2$ holds:

$$\frac{a_n}{a_{n-1}} = \frac{\left(\frac{n+1}{n}\right)^n}{\left(\frac{n}{n-1}\right)^{n-1}} = \left(\frac{\frac{n+1}{n}}{\frac{n}{n-1}}\right)^n \cdot \frac{n}{n-1} = \left(\frac{n^2-1}{n^2}\right)^n \cdot \frac{n}{n-1}$$
$$= \left(1 - \frac{1}{n^2}\right)^n \cdot \frac{n}{n-1} \stackrel{\text{Bernoulli}}{\geq} (1 - \frac{1}{n}) \frac{n}{n-1} = 1.$$

Thus $a_n \ge a_{n-1}$ holds.

Proof of b). The statement a) implies that $a_1 = 2 \le a_n$. Further:

$$a_n = (1 + \frac{1}{n})^n \stackrel{\text{Binom. Thm}}{=} \sum_{j=0}^n \binom{n}{j} \frac{1}{n^j} = 2 + \sum_{j=2}^n \binom{n}{j} \frac{1}{n^j}.$$

For $2 \le j \le n$ we also have

$$\binom{n}{j}\frac{1}{n^j} = \frac{n!}{j!(n-j)!}\frac{1}{n^j} = \frac{1 \cdot 2 \cdots n}{1 \cdots (n-j)\underbrace{n \cdots n}_{j \text{ times}}} \frac{1}{j!} \le \frac{1}{j!} \le \frac{1}{2^{j-1}}$$

and hence

$$a_n \le 1 + \sum_{j=1}^n \frac{1}{2^{j-1}} = 1 + \sum_{j=0}^{n-1} \frac{1}{2^j} \stackrel{\text{geom. series}}{\underset{\text{I 1.11 b)}}{=}} 1 + \frac{1 - \left(\frac{1}{2}\right)^n}{1 - \frac{1}{2}} < 3.$$

To conclude this section, we consider some further important limits. The proofs of the limits d) and e) are very instructive exercises which require a good understanding of the convergence concept.

1.16 Examples.

a) For $s \in \mathbb{Q}$, s > 0, we have

$$\lim_{n\to\infty} \frac{1}{n^s} = 0.$$

Given $\varepsilon > 0$, we choose $N_0 \in \mathbb{N}$ with $N_0 \geq \varepsilon^{-1/s}$. Then we have $\frac{1}{n^s} < \varepsilon$ for all $n > N_0$.

b) For a > 0, we have

$$\lim_{n \to \infty} \sqrt[n]{a} = 1.$$

We first consider the case $a \ge 1$. If we set $b_n := \sqrt[n]{a} - 1$, the Bernoulli inequality implies $a = (1 + b_n)^n \ge 1 + nb_n$. This implies in particular that $b_n < \frac{a}{n}$, and if we choose $N_0 > \frac{a}{\varepsilon}$, we have

$$|\sqrt[n]{a} - 1| = b_n < \varepsilon, \quad n > N_0.$$

If a < 1, then we have $a^{-1} > 1$ and the proposition follows from 1.8 c) and the above:

$$\lim_{n\to\infty} \sqrt[n]{a} = \left(\lim_{n\to\infty} \sqrt[n]{a^{-1}}\right)^{-1} = 1.$$

c) We have

$$\lim_{n\to\infty} \sqrt[n]{n} = 1.$$

For $b_n := \sqrt[n]{n} - 1 \ge 0$, the binomial theorem implies

$$n = (1 + b_n)^n \ge 1 + \frac{n(n-1)}{2}b_n^2$$
, hence $n - 1 \ge \frac{n(n-1)}{2}b_n^2$.

Therefore, $b_n^2 \leq \frac{2}{n}$ for all $n \in \mathbb{N}$, and if we choose for given $\varepsilon > 0$ an $N_0 \in \mathbb{N}$ such that $N_0 \geq \frac{2}{\varepsilon^2}$, then we have

$$|\sqrt[n]{n} - 1| = b_n < \varepsilon, \quad n > N_0.$$

d) For $a \in \mathbb{C}$ with |a| > 1 and $k \in \mathbb{N}$, we have

$$\lim_{n \to \infty} \frac{n^k}{a^n} = 0,$$

i.e. for a with |a| > 1, the function $n \mapsto a^n$ grows faster than any power $n \mapsto n^k$. In this situation, we observe two contrary effects: the numerator n^k exceeds any bound, while the term $\frac{1}{a^n}$ tends to zero. At first sight, it is not evident which tendency outweighs the other.

e) For $a \in \mathbb{C}$, we have

$$\lim_{n \to \infty} \frac{a^n}{n!} = 0,$$

i.e. the factorial function $n \mapsto n!$ grows faster than any of the functions $n \mapsto a^n$.

2 Bolzano-Weierstrass Theorem

In the previous chapter we have observed that all convergent sequences are bounded. In the following, we will examine the converse situation, i.e. we consider bounded sequences and ask if there exist convergent subsequences. If we consider for example the sequence $(a_n)_{n\in\mathbb{N}} = (-1)^n$, the above question is easy to answer: there are at least two convergent subsequences, namely $(a_{2n})_{n\in\mathbb{N}}$ and $(a_{2n+1})_{n\in\mathbb{N}}$. The following theorem of Bolzano-Weierstraß gives an affirmative answer to this question in a general context.

We begin this section with the formal definition of a subsequence of a given sequence.

2.1 Definition. Let (a_n) be a sequence and $\varphi : \mathbb{N} \to \mathbb{N}$ be a strictly increasing function (i.e. $\varphi(n+1) > \varphi(n) \ \forall \ n \in \mathbb{N}$). Then $(a_{\varphi(k)})_{k \in \mathbb{N}}$ is called a *subsequence* of (a_n) . If we put $\varphi(k) := n_k$, we write $(a_{n_k})_{k \in \mathbb{N}}$.

Example. Let $a_n := (-1)^n$. Take $\varphi(n) = 2n$, then $a_{2n} = 1 \ \forall \ n \in \mathbb{N}_0$. If we choose $\varphi(n) = 2n + 1$, then $a_{2n+1} = -1 \ \forall \ n \in \mathbb{N}_0$.

2.2 Lemma. Let $(a_n)_{n\in\mathbb{N}_0}$ be a real sequence. Then $(a_n)_{n\in\mathbb{N}_0}$ has a monotone subsequence.

Proof. Let $(a_n)_{n\in\mathbb{N}_0}$ be a sequence of real numbers. Consider

$$A := \{k \in \mathbb{N}_0 : a_k \ge a_m \text{ for all } m > k\}.$$

Now either A has only finitely many elements, or else it has infinitely many.

Case 1: Suppose A has infinitely many elements. Then define $n_0 := \min A$ and

$$n_{i+1} := \min(A \setminus (\bigcup_{j=0}^{i} \{n_j\})), \quad i \in \mathbb{N}_0.$$

Then $(a_{n_k})_{k\in\mathbb{N}_0}$ is decreasing.

Case 2: Suppose A has finitely many elements. If $A \neq \emptyset$ we let $n_0 := \max A + 1$. If $A = \emptyset$ we let $n_0 := 0$. Then since $n_0 \notin A$ there exist $m > n_0$ such that $a_m > a_{n_0}$. Let n_1 be the least such m. Since also $n_1 \notin A$ we can continue, and in general define an increasing subsequence $(a_{n_k})_{k \in \mathbb{N}_0}$ by

$$n_{i+1} := \min\{k : k > n_i \text{ and } a_k > a_{n_i}\}.$$

2.3 Theorem. (Bolzano-Weierstrass, 1st Version) Every bounded sequence $(a_n)_{n\in\mathbb{N}_0}\subset\mathbb{C}$ has a convergent subsequence.

Proof. a) Let $(a_n) \subset \mathbb{R}$. Then the claim follows from Lemma 2.2 and Theorem 1.12.

b) Let $(a_n) \subset \mathbb{C}$. Then $(\operatorname{Re} a_n)_{n \in \mathbb{N}_0}$ is a real and bounded sequence. According to a) it possesses a convergent subsequence $(\operatorname{Re} a_{\varphi_1(k)})_{n \in \mathbb{N}}$. Further, $(\operatorname{Im} a_{\varphi_1(k)})_{n \in \mathbb{N}}$ is a real and bounded sequence. Again from a), there exists a convergent subsequence $(\operatorname{Im} a_{\varphi_2(\varphi_1(k))})_{k \in \mathbb{N}}$. We put $\varphi = \varphi_2 \circ \varphi_1$. Then φ is strictly increasing and $(a_{\varphi(k)})_{k \in \mathbb{N}}$ is a convergent subsequence of $(a_n)_{n \in \mathbb{N}}$.

In order to formulate another version of the Bolzano-Weierstrass theorem, we consider next the following definition of a cluster point.

2.4 Definition. (Cluster point). A number $a \in \mathbb{C}$ is called a *cluster point* of a sequence $(a_n)_n \subset \mathbb{C}$, if for each $\varepsilon > 0$ there exist infinitely many $n \in \mathbb{N}$ such that $|a - a_n| < \varepsilon$.

- **2.5 Examples.** a) Let $a_n = (\frac{1}{2}, 2, \frac{1}{3}, 3, \frac{1}{4}, 4, \dots)$. Then a = 0 is a cluster point of (a_n) ; but the sequence (a_n) is divergent.
- b) The sequence $(a_n) = (i^n) = (1, i, -1, -i, 1, i, -1, ...)$ has 4 cluster points, namely 1, i, -1, -i and 4 convergent subsequences.
- c) Let $a_n = n$ for all $n \in \mathbb{N}$. Then (a_n) does not have cluster points and does not have a convergent subsequence.
- **2.6 Remarks.** In the following let $\mathbb{K} = \mathbb{R}$ or \mathbb{C} .
 - a) For $a \in \mathbb{K}$ and $\varepsilon > 0$ set $U_{\varepsilon}(a) := \{z \in \mathbb{K} : |a z| < \varepsilon\}$. Then $U_{\varepsilon}(a)$ is called an ε -neighborhood of a.
 - b) a is the limit of the sequence $(a_n)_n \subset \mathbb{K} \Leftrightarrow$ for each $\varepsilon > 0$, $U_{\varepsilon}(a)$ contains almost all a_n , i.e. $U_{\varepsilon}(a)$ contains a_n for all but finitely many n.
 - c) a is a cluster point of the sequence $(a_n) \subset \mathbb{K} \Leftrightarrow$ for each $\varepsilon > 0$, $U_{\varepsilon}(a)$ contains infinitely many members of the sequence $(a_n)_n$.
- **2.7 Lemma.** Let (a_n) be a sequence in \mathbb{K} and $a \in \mathbb{C}$. Then a is a cluster point of (a_n) if and only if there exists a subsequence $(a_{n_k})_{k \in \mathbb{N}_0}$ of $(a_n)_n$ with $\lim_{k \to \infty} a_{n_k} = a$.

Proof. " \Longrightarrow ": Remark 2.6 c) implies that for each $\varepsilon > 0$ infinitely many sequence members a_n lie in $U_{\varepsilon}(a)$. Let $n_0 := 0$ and for all $k \geq 1$ choose an $n_k > n_{k-1}$ with $a_{n_k} \in U_{\frac{1}{k}}(a)$. Then $(n_k)_{n \in \mathbb{N}}$ is strictly increasing and $|a - a_{n_k}| < \frac{1}{k}, k \geq 1$, i.e.

$$\lim_{k \to \infty} a_{n_k} = a.$$

" \Leftarrow ": Let $a := \lim_{k \to \infty} a_{n_k}$. Then for each $\varepsilon > 0$ we have that $U_{\varepsilon}(a)$ contains almost all members a_{n_k} of $(a_{n_k})_k$, and thus infinitely many of $(a_n)_n$, cf. Remark 2.6 b), c).

2.8 Theorem. (Bolzano-Weierstrass, 2nd Version). Every <u>real</u> and bounded sequence $(a_n)_{n\in\mathbb{N}}$ has a cluster point. Further, the set of cluster points of $(a_n)_{n\in\mathbb{N}}$ has a minimum r and a maximum s.

Remarks. In the situation above we set

(Limit Inferior)
$$\lim_{n\to\infty}\inf a_n := \underline{\lim} \ a_n := r \quad (=\lim_{n\to\infty}(\inf\{a_k:k\geq n\}), \text{ see (T5.2)})$$

(Limit Superior) $\lim_{n\to\infty}\sup a_n := \overline{\lim} \ a_n := s \quad (=\lim_{n\to\infty}(\sup\{a_k:k\geq n\}), \text{ see (T5.2)}).$

Proof. Let $H := \{h \in \mathbb{R} : h \text{ is a cluster point of } (a_n)\}$. Then

$$\inf a_n \le h \le \sup a_n \text{ for all } h \in H.$$

Further $H \neq \emptyset$, due to the first version of the Bolzano-Weierstrass Theorem 2.3. In addition, the Completeness Axiom implies that $s := \sup H$ exists. We still have to show that $s \in H$ holds. To this end, let $\varepsilon > 0$. By the characterisation of the supremum given in Theorem I,1.22, there exists $a \in H$ with

$$a \le s < a + \frac{\varepsilon}{2},$$

thus $|s-a|<\frac{\varepsilon}{2}$. For $x\in U_{\varepsilon/2}(a)$ we then have

$$|s-x| \le |s-a| + |a-x| < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon,$$

i.e. $U_{\varepsilon/2}(a) \subset U_{\varepsilon}(s)$. Now $U_{\varepsilon/2}(a)$ contains infinitely many a_n , and so does $U_{\varepsilon}(s)$. Remark 2.6 implies that $s \in H$. The proof for the limit inferior follows the same pattern.

- **2.9 Examples.** a) We again consider the sequence $(a_n)_{n\in\mathbb{N}} = ((-1)^n)_{n\in\mathbb{N}}$. Clearly, we have $\limsup_{n\to\infty} a_n = 1$ and $\liminf_{n\to\infty} a_n = -1$.
- b) Consider the sequence

$$1, \frac{1}{2}, \frac{2}{2}, \frac{3}{2}, \frac{1}{3}, \frac{2}{3}, \frac{3}{3}, \frac{4}{3}, \frac{5}{3}, \frac{1}{4}, \dots, \frac{7}{4}, \frac{1}{5}, \dots, \frac{9}{5}, \dots$$

which is formally defined as

$$a_n = \frac{j}{k+1}$$
 for $n = k^2 + j$, $j = 1, 2, \dots, 2k+1$, $k \in \mathbb{N}_0$.

Then every rational number q with 0 < q < 2 is contained in this sequence (even infinitely many times) and we have $\limsup_{n\to\infty} a_n = 2$ and $\liminf_{n\to\infty} a_n = 0$. Moreover, every x with $0 \le x \le 2$ is a cluster point of this sequence. In particular, the sequence has infinitely many cluster points.

So far we have studied the convergence of a sequence only for the case in which the limit was explicitly known. An exception to this is only Theorem 1.12. We consider now the so called "inner" criterion.

2.10 Definition. A sequence $(a_n) \subset \mathbb{K}$ is called *Cauchy sequence* if for each $\varepsilon > 0$ there exists an $n_0 \in \mathbb{N}$ such that

$$|a_n - a_m| < \varepsilon$$
 for all $n, m \ge n_0$.

The significance of this criterion is that it provides a necessary and sufficient condition for the convergence of $(a_n)_{n\in\mathbb{N}}$ without involving the limit a itself.

2.11 Theorem (Cauchy criterion for sequences). Let $(a_n) \subset \mathbb{K}$ be a sequence. Then (a_n) is convergent, if and only if (a_n) is a Cauchy sequence.

Proof. " \Longrightarrow ": Let $a = \lim a_n$ and $\varepsilon > 0$. Then there exists $n_0 \in \mathbb{N}$ with $|a - a_n| < \frac{\varepsilon}{2}$ for all $n > n_0$, thus

$$|a_n - a_m| \le |a_n - a| + |a - a_m| < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon, \quad n, m \ge n_0.$$

" \Leftarrow ": Let (a_n) be a Cauchy sequence. We divide the proof in 3 steps: a) The sequence (a_n) is bounded: For $\varepsilon = 1$ there exists an m_0 such that

$$|a_n| - |a_{m_0}| \le |a_n - a_{m_0}| < 1 \text{ for all } n \ge m_0.$$

Thus $|a_n| \le 1 + |a_{m_0}|$ for $n \ge m_0$. Hence $|a_n| \le \max\{|a_0|, |a_1|, \dots, |a_{m_0-1}|, |1 + a_{m_0}|\}, n \in \mathbb{N}$, and (a_n) is a bounded sequence.

- b) The first version of the Bolzano-Weierstrass theorem implies that (a_n) has a convergent subsequence $(a_{n_k})_{k\in\mathbb{N}}$ with $\lim_{k\to\infty} a_{n_k} = a$.
- c) Let $\varepsilon > 0$. The hypothesis implies that $m_1 \in \mathbb{N}$ exists with $|a_n a_m| < \frac{\varepsilon}{2}$ for all $n, m \ge m_1$. Step b) implies further that $|a a_{n_k}| < \frac{\varepsilon}{2}$, $n_k > m_1$. Thus

$$|a_n - a| \le \underbrace{|a_n - a_{n_k}|}_{\le \frac{\varepsilon}{2}} + \underbrace{|a_{n_k} - a|}_{\le \frac{\varepsilon}{2}} < \varepsilon \text{ for all } n \ge m_1,$$

i.e. $a_n \stackrel{n \to \infty}{\longrightarrow} a$.

- **2.12 Remarks.** a) The property that every Cauchy sequence converges in \mathbb{K} is also called the *completeness* of \mathbb{K} .
- b) The set of rational numbers $\mathbb{Q} = \{\frac{p}{q} : p \in \mathbb{Z}, q \in \mathbb{N}\}$ is not complete.
- c) We have

Completeness axiom \iff Archimedean property and completeness of \mathbb{R}

Archimedean property and theorem of Bolzano-

Weierstrass in \mathbb{R}

d) For $q \in \mathbb{C}$, $q \neq 1$ with |q| = 1 set $a_n := q^n$. Then

$$|a_{n+1} - a_n| = |q|^n |q - 1| = |q - 1| > 0$$
, for all $n \ge 1$,

i.e. (a_n) is not a Cauchy sequence. Thus (a_n) is divergent. Therefore, for $q \in \mathbb{C}, q \neq 1, |q| = 1$:

$$(q^n)_{n\in\mathbb{N}}$$
 is convergent \iff $|q|<1$ or $q=1$.

We introduce the following notation: for $a, b \in \mathbb{R}$ with $a \leq b$ let

$$[a,b] := \{x \in \mathbb{R} : a \le x \le b\}.$$

2.13 Theorem. (Banach fixed point theorem). Let $a, b \in \mathbb{R}$ with a < b, and let $f: [a,b] \to [a,b]$ be a mapping. Assume that there exists q, 0 < q < 1 such that for all $x, y \in [a,b]$ we have

$$|f(x) - f(y)| \le q|x - y|.$$
 (2.1)

Then there exists a unique $r \in [a,b]$ with f(r) = r. This means that r is the unique fixed point of f.

2.14 Remark. A mapping which satisfies the condition (2.1) is called a *strict* contraction.

Proof. For $x_0 \in [a, b]$ and $n \in \mathbb{N}_0$, define

$$x_{n+1} := f(x_n).$$

Then the following statements hold:

a) The sequence $(x_n)_{n\in\mathbb{N}}$ is convergent: We show first the inequality

$$A(m): |x_m - x_{m-1}| \le q^{m-1}|x_1 - x_0|, \quad m \ge 1$$

via induction. The basis step m=1 is clear. Let $m\in\mathbb{N}$, such that A(m) is true. Then

$$|x_{m+1} - x_m| = |f(x_m) - f(x_{m-1})|$$

$$\leq q|x_m - x_{m-1}|$$
I.H.
$$\leq qq^{m-1}|x_1 - x_0| = q^m|x_1 - x_0|.$$

Thus A(m+1) is true, and so the inequality holds for all $m \ge 1$. Next we estimate $|x_m - x_n|$ for m > n:

$$|x_{m} - x_{n}| \leq |x_{m} - x_{m-1}| + |x_{m-1} - x_{m-2}| + \dots + |x_{n+1} - x_{n}|$$

$$\leq (q^{m-1} + q^{m-2} + \dots + q^{n})|x_{1} - x_{0}|$$

$$\stackrel{\text{geom. series}}{=} q^{n} \frac{1 - q^{m-n}}{1 - q}|x_{1} - x_{0}| \leq \frac{q^{n}}{1 - q}|x_{1} - x_{0}|.$$

From Remark 2.12 d) it follows that $\lim_{n \to \infty} q^n = 0$, because 0 < q < 1. Thus (x_n) is a Cauchy sequence and Theorem 2.11 implies that (x_n) converges. We set $r := \lim_{n \to \infty} x_n$.

b) We show f(r) = r: Let $\varepsilon > 0$ be given. Then there exists $n_0 \in \mathbb{N}_0$ with $|r - x_n| < \frac{\varepsilon}{2}$ for all $n \ge n_0$, thus

$$|f(r) - r| \leq |f(r) - x_{n_0+1}| + |x_{n_0+1} - r|$$

$$\stackrel{\text{Def.}}{=} |f(r) - f(x_{n_0})| + |x_{n_0+1} - r|$$

$$\leq q|r - x_{n_0}| + |x_{n_0+1} - r| < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon.$$

The classical method of deduction in analysis from chapter I implies that f(r) = r.

c) We next show that the fixed point r is uniquely determined. Assume that there exists an $r' \in [a, b]$ with f(r') = r'. Then

$$|r - r'| = |f(r) - f(r')| \le q|r - r'|.$$

From this it follows that (1-q)|r-r'|=0, which implies that |r-r'|=0 and, therefore, that r=r'.

2.15 Remarks.

- a) The proof above is constructive, i.e. we build the fixed point r as $r = \lim_{n \to \infty} f^n(x_0)$ with $f^n = f \circ f \cdots \circ f$.
- b) The following error estimates hold:

$$|r - x_n| \le \frac{q^n}{1 - q} |x_1 - x_0|$$
 a-priori-estimate
 $|r - x_n| \le \frac{q}{1 - q} |x_n - x_{n-1}|$ a-posteriori-estimate

- c) The Banach fixed point theorem also holds if [a,b] is replaced by \mathbb{R} or by $M := \{a \in \mathbb{R} : a \leq x\}$.
- d) A generalization of this theorem to mappings on so-called complete metric spaces will be very important in the lecture "Ordinary Differential Equations".

To conclude this section, we discuss the concepts of *infinite limits*.

Often, it is convenient to write $\lim a_n = \infty$ if the terms of a sequence become large for large n, although strictly speaking, the sequence is *divergent*, and of course ∞ is not its limit, as it is not even a number. Nevertheless, this notation is often very natural and convenient and, therefore, we now make precise what we mean if we use it.

Let $(a_n)_{n\in\mathbb{N}}$ be a real sequence. We write

$$\lim a_n = \infty \ (-\infty),$$

if for arbitrary, fixed K > 0 there exists an $N_0 \in \mathbb{N}$ with $a_n \geq K$ $(a_n \leq -K)$ for all $n \geq N_0$. Furthermore, we write

$$\limsup a_n = \infty \qquad (\liminf a_n = -\infty),$$

if for each K > 0 there exists an $N_0 \in \mathbb{N}$ with $a_{N_0} \geq K$ $(a_{N_0} \leq -K)$. For a complex sequence $(c_n)_{n \in \mathbb{N}}$, we write

$$\lim c_n = \infty$$
,

if for each K > 0 there exists an $N_0 \in \mathbb{N}$ with $|c_n| \geq K$ for all $n \geq N_0$.

3 Infinite Series

Let (a_n) be a sequence in \mathbb{K} , where again $\mathbb{K} = \mathbb{R}$ or $\mathbb{K} = \mathbb{C}$. In this section we analyze the question, how the notation $\sum_{n=0}^{\infty} a_n$ has to be understood and under which conditions one can speak of a convergent/divergent infinite series.

3.1 Definition. a) Let $(a_n)_{n\in\mathbb{N}_0}$ be a sequence in \mathbb{K} . By the *(infinite) series with terms* a_n , notation

$$a_0 + a_1 + a_2 + \dots$$
 or $\sum_{j=0}^{\infty} a_j$,

we mean the sequence of partial sums $(s_n)_{n\in\mathbb{N}_0}$,

$$s_n := \sum_{j=0}^n a_j$$
, s_n being the *n-th partial sum* of the series.

That is, we use the symbol $\sum_{j=0}^{\infty} a_j$ to denote the sequence $(s_n)_{n \in \mathbb{N}_0}$.

b) If the sequence $(s_n)_{n\in\mathbb{N}_0}$ converges to $s\in\mathbb{K}$, then the series $\sum_{j=0}^{\infty}a_j$ is called convergent. In this case we use the symbol $\sum_{j=0}^{\infty}a_j$ also to denote the limit s of the sequence of partial sums. That is, we set $\sum_{j=0}^{\infty}a_j:=s$. Otherwise, the series is called divergent.

3.2 Examples. .

a) Geometric series. If
$$q \in \mathbb{C}$$
 with $|q| < 1$, then $\sum_{j=0}^{\infty} q^j = \frac{1}{1-q}$.
For consider $s_n = \sum_{j=0}^n q^j \stackrel{I,1.11 \text{ b}}{=} \stackrel{1}{\underset{1-q}{\longrightarrow}} \stackrel{n \to \infty}{\underset{1.7 \text{ b}}{\longrightarrow}} \frac{1}{1-q}$.

b) Harmonic series. The series

$$\sum_{n=1}^{\infty} \frac{1}{n}$$
 diverges.

For consider for $n \ge 1$ the difference $s_{2n} - s_n = \sum_{j=n+1}^{2n} \frac{1}{j} \ge n \cdot \frac{1}{2n} = \frac{1}{2}$, i.e., $(s_n)_{n \in \mathbb{N}}$ is not a Cauchy sequence, thus does not converge!

3. INFINITE SERIES 33

c) The series $\sum_{n=1}^{\infty} \frac{1}{n(n+1)}$ converges and $\sum_{n=1}^{\infty} \frac{1}{n(n+1)} = 1$. In fact $\frac{1}{j(j+1)} = \frac{1}{j} - \frac{1}{j+1}$, and

$$s_n = \sum_{j=1}^n (\frac{1}{j} - \frac{1}{j+1}) = 1 - \frac{1}{n+1} \xrightarrow{n \to \infty} 1.$$

Sums of type $\sum_{j=0}^{n} (c_j - c_{j+1})$ are called telescoping sums.

The Cauchy Criterion 2.11 is an *inner* criterion for the convergence of sequences. The following lemma gives an analogue criterion for series.

3.3 Lemma. (Cauchy's Convergence Criterion). The series $\sum_{j=0}^{\infty} a_j$ converges, if and only if for each $\varepsilon > 0$ there exists $N_0 \in \mathbb{N}$ with

$$|\sum_{j=n}^{m} a_j| < \varepsilon \quad for \ all \quad n, m \ge N_0.$$

Proof. Since $|\sum_{j=n}^m a_j| = |s_m - s_{n-1}|$, the claim follows from Cauchy's criterion for sequences, Theorem 2.11.

If we set n = m in the above lemma, we see that the summands of a convergent series always form a null sequence. We write down this important fact in the following corollary.

3.4 Corollary. Assume that $\sum_{j=0}^{\infty} a_j$ converges. Then $\lim_{j\to\infty} a_j = 0$.

Proof. Choose n = m in the above Lemma 3.3.

We note, that the example of the harmonic series shows that the converse of Corollary 3.4 does not hold.

3.5 Remark. Let (a_j) be a sequence with non-negative elements, i.e. $a_j \geq 0$ for all $j \in \mathbb{N}_0$. Then $\sum_{j=1}^{\infty} a_j$ converges, if and only if the sequence of partial sums $(s_n)_{n \in \mathbb{N}_0}$ is bounded.

Proof. Assume that $\sum_{j=0}^{\infty} a_j$ converges, i.e. the sequence of the partial sums $(s_n)_{n\in\mathbb{N}}$ converges. Theorem 1.6 implies now that $(s_n)_{n\in\mathbb{N}}$ is bounded.

Conversely, $(\sum_{j=0}^{n} a_j)_{n \in \mathbb{N}_0}$ is increasing, since $a_j \geq 0$. By assumption $(s_n)_{n \in \mathbb{N}}$ is bounded, which according to Theorem 1.12 means that $(s_n)_{n \in \mathbb{N}}$ converges.

3.6 Example. We consider the series $\sum_{n=0}^{\infty} \frac{1}{n!}$ and show in the following that we have

$$\sum_{n=0}^{\infty} \frac{1}{n!} = e$$

where the number e was defined as $e = \lim_{n \to \infty} (1 + \frac{1}{n})^n$ already in 1.15.

Let $a_n := (1 + \frac{1}{n})^n$ for $n \in \mathbb{N}$. The proof of Theorem 1.15 implies, that $a_n \leq \sum_{j=0}^n \frac{1}{j!} \leq 3$ for all $n \geq 1$. Thus $(\sum_{j=0}^n \frac{1}{j!})_{n \in \mathbb{N}}$ is bounded and Remark 3.5 implies that $\sum_{j=0}^\infty \frac{1}{j!}$ converges. Let $e' := \sum_{j=0}^\infty \frac{1}{j!}$ be the limit of the series. Then by Lemma 1.9 we have that $\lim a_n = e \leq \sum_{j=0}^\infty \frac{1}{j!} = e'$. Thus $e \leq e'$.

We now show the inverse inequality: $e \ge \sum_{j=0}^m \frac{1}{j!}$ for each fixed $m \in \mathbb{N}$. Indeed for $n > m \ge 1$

$$a_n \overset{\text{Bin.Thm.}}{=} \sum_{j=0}^n \binom{n}{j} \frac{1}{n^j} \ge \sum_{j=0}^m \binom{n}{j} \frac{1}{n^j} = \sum_{j=0}^m \frac{1}{j!} \underbrace{\underbrace{\frac{n}{n} \underbrace{n-1}_{j-1} \dots \underbrace{n-j+1}_{j-1}}_{-1(n \to \infty)}}_{j-\text{factors}}.$$

Thus according to Lemma 1.9, $\lim_{n\to\infty} a_n = e \ge \sum_{j=0}^m \frac{1}{j!}$ uniformly in m, thus $e \ge \lim_{m\to\infty} \sum_{j=0}^m \frac{1}{j!} = e'$. Hence, summarizing, we have e' = e.

To obtain estimates for Euler's number e, consider

$$d_{n,k} := s_{n+k} - s_n, \quad k, n \in \mathbb{N}, \quad \text{where } s_n = \sum_{j=0}^n \frac{1}{j!}.$$

We have for arbitrary $n, k \in \mathbb{N}$ that

$$\frac{1}{(n+1)!} \le d_{n,k} \le \frac{s_k - 1}{(n+1)!},$$

which yields for $k \to \infty$

$$\frac{1}{(n+1)!} \le e - s_n \le \frac{e-1}{(n+1)!} \,. \tag{3.1}$$

In addition to giving us 2,66 < e < 2,8 for n = 2, the above estimate is the basis for the following proof of the irrationality of e.

3.7 Theorem. Euler's number e is irrational.

3. INFINITE SERIES 35

Proof. Assume that e is rational. Then we can write e in the form e = p/q with $p, q \in \mathbb{N}$. Take the above estimate for n = q and multiply the inequality with q!. Then you get

$$0 < \frac{1}{q+1} \le p(q-1)! - q! s_q < \frac{2}{q+1} \le 1,$$

and therefore

$$0 < p(q-1)! - q! s_q < 1.$$

This is impossible, because $p(q-1)! - q! s_q \in \mathbb{Z}$.

In the following, we examine the convergence of series with alternating signs in the summands. We begin with Dirichlet's criterion.

3.8 Theorem. (Dirichlet's Convergence Criterion). Let $a_n \in \mathbb{C}$ for all $n \geq 1$ be such that the partial sums $(s_n)_{n \in \mathbb{N}} = (\sum_{j=1}^n a_j)_{n \in \mathbb{N}}$ are bounded. Let $(\varepsilon_n)_{n \in \mathbb{N}}$ be a decreasing null sequence. Then $\sum_{j=1}^{\infty} \varepsilon_j a_j$ converges.

An important consequence is the so-called Leibniz-Criterion.

- **3.9 Corollary.** (Leibniz Criterion). Let $(\varepsilon_n)_{n\in\mathbb{N}}$ be a decreasing (hence real) null sequence. Then $\sum_{j=1}^{\infty} (-1)^j \varepsilon_j$ converges.
- **3.10. Examples and Remarks**. a) The series

$$\sum_{j=0}^{\infty} (-1)^j \frac{1}{j+1} = 1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \frac{1}{5} - \dots$$

converges and is called alternating harmonic series. We show in Analysis II, that the limit value of the series $\sum_{j=0}^{\infty} (-1)^j \frac{1}{j+1}$ is equal to $\log 2$.

b) A series of the form $\sum_{j=0}^{\infty} (-1)^j a_j$ with $a_j \geq 0$ for all $j \in \mathbb{N}_0$ is called alternating.

Proof of Theorem 3.8 For $m, n \in \mathbb{N}$ with $m \geq n$ set

$$\sigma_{n,m} := \sum_{j=n}^{m} \varepsilon_j a_j.$$

The assumption says that $\lim_{j\to\infty} \varepsilon_j = 0$; thus according to Lemma 3.3 (Cauchy Criterion) it is enough to show that there exists a constant M > 0 with

$$|\sigma_{n,m}| \leq M\varepsilon_n$$
 for all $m, n \geq 1$.

We first transform $\sigma_{n,m}$ by Abel's summation by parts: Set $s_n := \sum_{j=1}^n a_j$ and $s_0 = 0$ to obtain for $m \ge n \ge 1$

$$\sigma_{n,m} = \sum_{j=n}^{m} \varepsilon_{j} a_{j} = \sum_{j=n}^{m} \varepsilon_{j} (s_{j} - s_{j-1}) = \sum_{j=n}^{m} \varepsilon_{j} s_{j} - \sum_{j=n}^{m} \varepsilon_{j} s_{j-1}$$

$$= \sum_{j=n}^{m} \varepsilon_{j} s_{j} - \sum_{j=n-1}^{m-1} \varepsilon_{j+1} s_{j} = \sum_{j=n}^{m-1} (\varepsilon_{j} - \varepsilon_{j+1}) s_{j} + \varepsilon_{m} s_{m} - \varepsilon_{n} s_{n-1}.$$

With $C := \sup\{|s_n|, n \in \mathbb{N}\}$ we get from the above that (recall $(\varepsilon_j)_j$ is decreasing)

$$|\sigma_{n,m}| \leq \sum_{j=n}^{m-1} \underbrace{(\varepsilon_{j} - \varepsilon_{j+1})}_{\geq 0} |s_{j}| + \varepsilon_{m} |s_{m}| + \varepsilon_{n} |s_{n-1}|$$

$$\leq \sum_{j=n}^{m-1} (\varepsilon_{j} - \varepsilon_{j+1}) C + \varepsilon_{m} C + \varepsilon_{n} C$$

$$= (\varepsilon_{n} - \varepsilon_{m}) C + \varepsilon_{m} C + \varepsilon_{n} C = 2\varepsilon_{n} C = \underbrace{2C}_{=:M} \varepsilon_{n}.$$

A very important concept in the topic of convergence of series is that of absolute convergence.

- **3.11 Definition.** (Absolute Convergence). A series $\sum_{j=0}^{\infty} a_j$ is called absolutely convergent, if $\sum_{j=0}^{\infty} |a_j|$ converges.
- **3.12 Remark.** Every series $\sum_{j=0}^{\infty} a_j$ which converges absolutely, converges. In fact $|\sum_{j=n}^{m} a_j| \leq \sum_{j=n}^{m} |a_j|$ for all $m \geq n$. Thus, the claim follows from the Cauchy criterion for series, Lemma 3.3.
- **3.13 Theorem.** (Comparison Test [Majorantenkriterium]). Let $(a_j)_{j\in\mathbb{N}_0}\subset\mathbb{C}$ and $(b_j)_{j\in\mathbb{N}_0}\subset\mathbb{R}$ be two sequences such that $|a_j|\leq b_j$ for almost all $j\in\mathbb{N}$. If $\sum_{j=0}^{\infty}b_j$ converges, then $\sum_{j=0}^{\infty}a_j$ converges absolutely.

In the situation above the series $\sum_{j=0}^{\infty} b_j$ is said to dominate or majorise $\sum_{j=0}^{\infty} a_j$.

Proof. Since $\sum_{j=n}^{m} |a_j| \leq \sum_{j=n}^{m} b_j$ for all $m \geq n$, the claim follows from the Cauchy criterion Lemma 3.3.

3. INFINITE SERIES 37

Example. In Example 3.2 c) we have shown that $\sum_{j=1}^{\infty} \frac{1}{j(j+1)}$ converges. Observing that $0 < \frac{1}{(j+1)^2} \le \frac{1}{j(j+1)}$ for $j \ge 1$, it follows that $\sum_{j=1}^{\infty} \frac{1}{(j+1)^2}$ converges and hence so does $\sum_{j=1}^{\infty} \frac{1}{j^2} = 1 + \sum_{j=1}^{\infty} \frac{1}{(j+1)^2}$.

In particular, if we choose as dominating series the geometric series, we get the so-called Root Test.

3.14 Theorem. (Root Test [Wurzelkriterium]). Let $(a_n)_n$ be a sequence in \mathbb{C} . a) Assume that there exists some q, 0 < q < 1, with

$$\sqrt[j]{|a_j|} \le q$$
 for almost all $j \in \mathbb{N}$.

Then $\sum_{j=0}^{\infty} a_j$ is absolutely convergent.

b) If we have $\sqrt[j]{|a_j|} \geq 1$ for infinitely many $j \in \mathbb{N}$, then $\sum a_j$ diverges.

Proof. a) By assumption, there exists $N_0 \in \mathbb{N}$ with $\sqrt[j]{|a_j|} \leq q$ for all $j \geq N_0$. Thus $|a_j| \leq q^j$ for all $j \geq N_0$, which implies that $\sum_{j=N_0}^{\infty} |a_j|$ is dominated by the geometric series $\sum_{j=1}^{\infty} q^j$. (Note: The finite sum $a_0 + \cdots + a_{N_0-1}$ is trivially convergent.)

b) The assumption says, that $\sqrt[j]{|a_j|} \ge 1$ for infinitely many $j \in \mathbb{N}$. Thus $|a_j| \ge 1$ for infinitely many $j \in \mathbb{N}$. In particular, the sequence $(a_j)_j$ is not a null sequence, which means that $\sum_{j=1}^{\infty} a_j$ diverges.

Example. The series $\sum_{j=0}^{\infty} \frac{j^l}{2^j}$ converges for each fixed $l \in \mathbb{N}$, because

$$\sqrt[n]{|a_n|} = \frac{\sqrt[n]{n^l}}{2} = \frac{(\sqrt[n]{n})^l}{2} \longrightarrow \frac{1}{2};$$

Thus $\sqrt[j]{|a_j|} \le \frac{2}{3} = q < 1$ for almost all $j \in \mathbb{N}$.

Often it is easier to implement the following test.

- **3.15 Theorem.** (Ratio Test [Quotientenkriterium]).
- a) Let $a_j \neq 0$ for almost all $j \in \mathbb{N}$ and assume that there exists 0 < q < 1 with

$$|\frac{a_{j+1}}{a_j}| \le q \quad \text{for almost all } j \in \mathbb{N}.$$

Then $\sum_{j=0}^{\infty} a_j$ converges absolutely. b) If $\left|\frac{a_j+1}{a_j}\right| \geq 1$ for almost all (not only for infinitely many) $j \in \mathbb{N}$, then $\sum_{j=0}^{\infty} a_j$

Proof. a) By assumption, there exists $N_0 \in \mathbb{N}$ with $\left|\frac{a_{j+1}}{a_j}\right| \leq q$ for all $j \geq N_0$. Thus for all $n \geq N_0 + 1$

$$\left|\frac{a_n}{a_{N_0}}\right| \stackrel{(*)}{=} \prod_{j=N_0}^{n-1} \left|\frac{a_{j+1}}{a_j}\right| = \left(\frac{a_{N_{0+1}}}{a_{N_0}} \frac{a_{N_{0+2}}}{a_{N_{0+1}}} \cdots \frac{a_n}{a_{n-1}}\right) \stackrel{Ass.}{\leq} q^{n-N_0}.$$

Thus $|a_n| \le |a_{N_0}| q^{n-N_0}$ for all $n \ge N_0 + 1$ and

$$\sum_{n=0}^{\infty} |a_n| \le \sum_{n=0}^{N_0} |a_n| + \frac{|a_{N_0}|}{q^{N_0}} \sum_{n=0}^{\infty} q^n.$$

Now, the Comparison Test implies the claim.

b) The assumption and the relation (*) imply, that $\left|\frac{a_n}{a_{N_0}}\right| \ge 1$ for all $n \ge N_0 + 1$. Hence (a_n) is not a null sequence and $\sum a_j$ diverges.

3.16 Example. The exponential series

$$\sum_{j=0}^{\infty} \frac{z^j}{j!}$$

converges for all $z \in \mathbb{C}$. This is clear for z = 0. Furthermore, for $z \neq 0$ we have

$$\left|\frac{a_{j+1}}{a_j}\right| = \frac{|z^{j+1}|}{(j+1)!} \frac{j!}{|z^j|} = \frac{|z|}{j+1} \xrightarrow{j \to \infty} 0$$

i.e. $\left|\frac{a_{j+1}}{a_j}\right| \leq \frac{1}{2}$ for almost all $j \in \mathbb{N}$.

Now consider variants of the above root and quotient tests, in which the existence of a number q with 0 < q < 1 is replaced by a condition concerning the limit inferior or the limit superior, respectively.

- **3.17 Theorem.** (Another formulation of the Root and Ratio Tests).
 - a) If $\overline{\lim}_{j\to\infty} \sqrt[j]{|a_j|} < 1$, then $\sum_{j=0}^{\infty} a_j$ converges absolutely.
 - b) If $\overline{\lim}_{j\to\infty} \sqrt[j]{|a_j|} > 1$, then $\sum_{j=0}^{\infty} a_j$ diverges.
 - c) Let $a_j \neq 0$ for almost all $j \in \mathbb{N}$ and $\overline{\lim}_{j \to \infty} \left| \frac{a_{j+1}}{a_j} \right| < 1$. Then $\sum_{j=0}^{\infty} a_j$ converges absolutely.
 - d) If $\underline{\lim}_{j\to\infty} \left| \frac{a_{j+1}}{a_i} \right| > 1$, then $\sum_{j=0}^{\infty} a_j$ diverges.

3. INFINITE SERIES

39

3.18 Remarks. a) If $\overline{\lim}_{j\to\infty} \sqrt[j]{|a_j|} = 1$, then *no* conclusion for convergence can be made! Indeed, consider for example $a_j = \frac{1}{j}$ and $b_j = \frac{1}{j^2}$. Then by Example 1.16 c) and Remark 1.14, we have

$$\sqrt[j]{|a_j|} = \sqrt[j]{\frac{1}{j}} = \frac{1}{\sqrt[j]{j}} \xrightarrow{j \to \infty} 1 \quad \text{and}$$

$$\sqrt[j]{|b_j|} = \sqrt[j]{\frac{1}{j}} = \frac{1}{\sqrt[j]{j^2}} \xrightarrow{j \to \infty} 1,$$

but $\sum_{j=1}^{\infty} a_j$ diverges, while $\sum_{j=1}^{\infty} b_j$ converges.

b) The Ratio Test is "weaker" than the Root Test, i.e.

$$\overline{\lim_{j\to\infty}}\sqrt[j]{|a_j|}\leq\overline{\lim_{j\to\infty}}|\frac{a_{j+1}}{a_j}|.$$

We conclude this first section about convergence of series with Cauchy's *Condensation Test*.

3.19 Theorem. (Cauchy's Condensation Test). Let (a_n) be a decreasing null sequence. Then:

$$\sum_{j=0}^{\infty} a_j \text{ converges} \iff \sum_{j=0}^{\infty} 2^j a_{2^j} \text{ converges.}$$

The above theorem says that we can completely read off the convergence behavior of a given sequence from the convergence behavior of the 'condensed' sequence which only has elements with indexes 2^{j} , and thus far less elements than the original series.

Proof. Let
$$s_n := \sum_{j=0}^n a_j$$
 and $t_n := \sum_{j=0}^n 2^j a_{2^j}$.

" \Longrightarrow ": For $n > 2^j$

$$s_n \geq a_1 + a_2 + (a_3 + a_4) + (a_5 + \dots + a_8) + \dots + (a_{2^{j-1}+1} + \dots + a_{2^j})$$

$$\geq \frac{a_1}{2} + a_2 + 2a_4 + 4a_8 + \dots + 2^{j-1}a_{2^j}$$

$$= \frac{1}{2}(a_1 + 2a_2 + 4a_4 + \dots + 2^j a_{2^j}) = \frac{1}{2}t_j$$

Let $\sum_{j=0}^{\infty} a_j =: s$. Then $t_j \leq 2s$ for all j and according to Remark 3.5 $\sum_{j=0}^{\infty} 2^j a_{2^j}$ converges.

" \Leftarrow ": Let $n \leq 2^{j+1} - 1$. Then

$$s_n \le a_0 + a_1 + (a_2 + a_3) + (a_4 \cdots + a_7) + \cdots + (a_{2^j} + \cdots + a_{2^{j+1}-1})$$

 $\le a_0 + a_1 + 2a_2 + 4a_4 + \cdots + 2^j a_{2^j} = a_0 + t_j$

Let $t = \sum_{j=0}^{\infty} 2^j a_{2^j}$. Then $s_n \leq a_0 + t$ for all $n \geq 0$ and Remark 3.5 implies that $\sum_{j=0}^{\infty} a_j$ converges.

The above theorem implies, that the series

$$\sum_{n=1}^{\infty} \frac{1}{n^{\alpha}},$$

with $\alpha \in \mathbb{Q}$, converges if and only if $\alpha > 1$. The corresponding condensed series

$$\sum_{j=0}^{\infty} 2^{j} 2^{-j\alpha} = \sum_{j=0}^{\infty} 2^{(1-\alpha)j} = \sum_{j=0}^{\infty} q^{j} \quad \text{with } q := 2^{1-\alpha}$$

is a geometric series and converges by 3.2 if and only if q < 1, or equivalently $\alpha > 1$. Bear in mind that at the moment, we have defined n^{α} only for $\alpha \in \mathbb{Q}$; we will define n^{α} for arbitrary $\alpha \in \mathbb{R}$ later.

The function given by the convergent series

$$\zeta(s) := \sum_{n=1}^{\infty} \frac{1}{n^s}, \quad s > 1$$

(at the moment only for $s \in \mathbb{Q}$), is the famous *Riemann zeta function*. It is an important tool to study the distribution of prime numbers. In the lecture 'Analysis II', we will prove $\zeta(2) = \frac{\pi^2}{6}$. The still unsolved *Riemann hypothesis* states that all nontrivial roots of the zeta function have real part $\frac{1}{2}$.

4 Rearrangement and Products of Series

If we add finitely many real or complex numbers, the result does not depend on the order of the summands, i.e. any arbitrary rearrangement of the summands yields the same result. For infinite series, the situation is completely different. We will see in the following section that it is possible to change the value of a series by rearranging its terms and that one can even achieve divergence of a former convergent series this way. However, this at first sight quite surprising effect does not appear for absolutely convergent series. This is a reason why the concept of absolute convergence is so important. Of course, for a precise description of the situation we must first define the concept of rearrangement. We start with an example.

Consider the alternating harmonic series

$$1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \ldots + \frac{1}{2j-1} - \frac{1}{2j} + \ldots,$$

as well as a rearrangement of it, which is given by

$$1 - \frac{1}{2} - \frac{1}{4} + \frac{1}{3} - \frac{1}{6} - \frac{1}{8} + \frac{1}{5} - \frac{1}{10} - \frac{1}{12} + \frac{1}{7} + \dots$$

We denote the n-th partial sum of the original and the rearranged series by s_n and t_n , respectively, and we define $s := \lim_{n \to \infty} s_n$. Then we have

$$s_{2} = \frac{1}{2}$$

$$s_{4} = \frac{1}{2} + \frac{1}{3} - \frac{1}{4}$$

$$2t_{3} = 2 \cdot \frac{1}{4} = \frac{1}{2}$$

$$2t_{6} = \frac{1}{2} + 2(\frac{1}{3} - \frac{1}{6} - \frac{1}{8})$$

$$s_{6} = \frac{1}{2} + (\frac{1}{3} - \frac{1}{4}) + (\frac{1}{5} - \frac{1}{6})$$

$$2t_{9} = \frac{1}{2} + (\frac{1}{3} - \frac{1}{4}) + 2(\frac{1}{5} - \frac{1}{10} - \frac{1}{12})$$

and because of $\frac{1}{2j-1} - \frac{1}{4j-2} - \frac{1}{4j} = \frac{1}{2}(\frac{1}{2j-1} - \frac{1}{2j})$, we can infer $2t_{3n} = s_{2n}$ for all $n \geq 1$. Because $(s_{2n})_{n \in \mathbb{N}}$ converges to s and the terms of the rearranged series converge to 0, there exists for each $\varepsilon > 0$ an $N_0 \in \mathbb{N}$ such that at the same time $|t_{3n} - \frac{s}{2}| < \frac{\varepsilon}{2}$, $|t_{3n+1} - t_{3n}| < \frac{\varepsilon}{2}$ and $|t_{3n+2} - t_{3n}| < \frac{\varepsilon}{2}$ for all $n \geq N_0$. This implies $|t_m - \frac{s}{2}| < \frac{\varepsilon}{2}$ for all $m > 3N_0 + 2$, which means that the rearranged sequence converges to s/2.

This example motivates the following definition.

4.1 Definition. Let $\sum_{n=0}^{\infty} a_n$ be a series of complex numbers and $\varphi : \mathbb{N}_0 \to \mathbb{N}_0$ a bijective mapping. Then $\sum_{n=0}^{\infty} a_{\varphi(n)}$ is called *rearrangement* of the series $\sum_{n=0}^{\infty} a_n$. Further the series $\sum_{n=0}^{\infty} a_n$ is called *unconditionally convergent*, if every rearrangement of the series $\sum_{n=0}^{\infty} a_n$ has the <u>same</u> limit value.

4.2 Theorem. Every absolutely convergent series $\sum_{n=0}^{\infty} a_n$ is unconditionally convergent.

Proof. Let $\varphi : \mathbb{N}_0 \to \mathbb{N}_0$ be a bijective mapping. Let

$$s_n := \sum_{j=0}^n a_j, \quad t_n := \sum_{j=0}^n a_{\varphi(j)}.$$

We show, that $(t_n)_n$ converges to s, where s denotes the limit value of the sequence s_n , i.e. $s := \lim_{n \to \infty} s_n$. According to the definition of the convergence of $\sum |a_n|$, for $\varepsilon > 0$ there exists an $N_0 \in \mathbb{N}$ with

$$\sum_{j=N_0}^{\infty} |a_j| < \frac{\varepsilon}{2}.$$

Hence

$$|s - \sum_{j=0}^{N_0 - 1} a_j| = |\sum_{j=N_0}^{\infty} a_j| \le \sum_{j=N_0}^{\infty} |a_j| < \frac{\varepsilon}{2}.$$

Now choose N_1 so large, that $\{0, 1, 2 \cdots N_0 - 1\} \subset \{\varphi(0), \varphi(1) \cdots \varphi(N_1)\}$. Then for all $m \geq N_1$ holds

$$\left| \sum_{j=0}^{m} a_{\varphi(j)} - s \right| \le \left| \sum_{j=0}^{m} a_{\varphi(j)} - \sum_{j=0}^{N_0 - 1} a_j \right| + \left| \sum_{j=0}^{N_0 - 1} a_j - s \right| \le \sum_{j=N_0}^{\infty} |a_j| + \frac{\varepsilon}{2} \le \varepsilon.$$

Thus (t_m) converges to s.

The following result (due to Riemann) is quite surprising.

4.3 Theorem. (Riemann Rearrangement Theorem). Let $\sum_{n=0}^{\infty} a_n$ be a convergent, but not absolutely convergent series of real numbers. Then there exists for every $b \in \mathbb{R}$ a rearrangement $\sum_{n=0}^{\infty} a_{\varphi(n)}$, which converges to b.

The Riemann Rearrangement Theorem has the remarkable consequence, that you may only rearrange finitely may terms in a convergent series which is not absolutely convergent — otherwise the concept of convergent series does not make sense any more! On the other hand, the above Theorem 4.2 says that the value of an absolutely convergent series is invariant under rearrangement.

We do not prove the Riemann Rearrangement Theorem here and instead refer to the book of Mangold/Knopp.

4. REARRANGEMENT AND PRODUCTS OF SERIES

43

In the following, we want to multiply two convergent series $\sum_{n=0}^{\infty} a_n$ and $\sum_{n=0}^{\infty} b_n$. For this, we consider the product

$$(a_0 + a_1 + a_2 + \cdots)(b_0 + b_1 + \cdots).$$

Expanding gives terms of the following form, which have to be summed up.

$$a_0b_0$$
 a_0b_1 a_0b_2 a_0b_3 \cdots a_1b_0 a_1b_1 a_2b_1 \cdots a_2b_0 a_2b_1 a_2b_2 \cdots

There is the question, in which order should the single terms be summed up. In particular, we ask when

$$(\sum_{j=0}^{\infty} a_j)(\sum_{j=0}^{\infty} b_j) = \sum_{j=0}^{\infty} p_j,$$

with $p_{\varphi(l,m)} = a_l b_m$ for $l, m \in \mathbb{N}_0$ and some bijection $\varphi : \mathbb{N}_0 \times \mathbb{N}_0 \to \mathbb{N}_0$. Possible orderings are

We call the series $\sum_{j=0}^{\infty} p_j$ a product series of $\sum a_j$ and $\sum b_j$ if $p_{\varphi(l,m)} = a_l b_m$ for all $l, m \in \mathbb{N}_0$ and $\varphi : \mathbb{N}_0 \times \mathbb{N}_0 \to \mathbb{N}_0$ is bijective.

4.4 Theorem. Let $\sum_{j=0}^{\infty} a_j$ and $\sum_{j=0}^{\infty} b_j$ be two absolutely convergent series. Then all their product series converge to

$$(\sum_{j=0}^{\infty} a_j) \cdot (\sum_{j=0}^{\infty} b_j)$$

.

Proof. Let $\sum_{j=0}^{\infty} p_j$ be an arbitrary product series of $\sum_{j=0}^{\infty} a_j$ and $\sum_{j=0}^{\infty} b_j$. Then there exists for all $n \in \mathbb{N}$ an $m \in \mathbb{N}$ with

$$\sum_{j=0}^{n} |p_j| \le \sum_{j=0}^{m} |a_j| \sum_{j=0}^{m} |b_j| \le \sum_{j=0}^{\infty} |a_j| \sum_{j=0}^{\infty} |b_j|.$$

Now Remark 3.5 implies that $\sum_{j=0}^{\infty} |p_j|$ converges. Further, from Remark 3.12 it follows that also $\sum_{j=0}^{\infty} p_j$ converges, and Theorem 4.2 implies that the convergence is unconditional (i.e. independent from the chosen order). This means that *every* product series converges to the same $s \in \mathbb{C}$.

Use now the special product series given by

Then we have

$$q_0 + q_1 + \cdots + q_{(n+1)^2 - 1} = \underbrace{(a_0 + \cdots + a_n)}_{\stackrel{n \to \infty}{\longrightarrow} \sum_{j=0}^{\infty} a_j} \underbrace{(b_0 + \cdots + b_n)}_{\stackrel{n \to \infty}{\longrightarrow} \sum_{j=0}^{\infty} b_j}.$$

From this, the claim follows.

If one chooses the following order for the summation

letting $c_0 := a_0b_0$, $c_1 := a_0b_1 + a_1b_0$ and generally

$$c_n := \sum_{j=0}^n a_j b_{n-j},$$

we obtain the following corollary.

4.5 Corollary. (Cauchy Product of Series). Let $\sum_{j=0}^{\infty} a_j$ and $\sum_{j=0}^{\infty} b_j$ be two absolutely convergent series and let

$$c_n := \sum_{j=0}^n a_j b_{n-j}, \qquad n \in \mathbb{N}_0.$$

Then $\sum_{n=0}^{\infty} c_n$ converges absolutely and

$$(\sum_{j=0}^{\infty} a_j)(\sum_{j=0}^{\infty} b_j) = \sum_{n=0}^{\infty} c_n.$$

We remark that Corollary 4.5 in general does not hold for series which are only convergent, but not absolutely convergent.

In particular, let us return to the exponential series given by

$$\exp(z) := \sum_{j=0}^{\infty} \frac{z^j}{j!}, \quad z \in \mathbb{C}.$$

From the Ratio Test Theorem 3.15 and Example 3.16 it follows, that $\exp(z)$ is absolutely convergent for all $z \in \mathbb{C}$. Further, we can now show the important functional equation of the exponential series.

4.6 Corollary. (Functional Equation of exp). For $z, w \in \mathbb{C}$

$$\exp(z)\exp(w) = \exp(z+w).$$

Proof. For $z, w \in \mathbb{C}$

$$\exp(z) \exp(w) \stackrel{\text{Def.}}{=} \left(\sum_{j=0}^{\infty} \frac{z^{j}}{j!}\right) \left(\sum_{j=0}^{\infty} \frac{w^{j}}{j!}\right) \stackrel{\text{Cauchy Product 4.5}}{=} \sum_{n=0}^{\infty} \sum_{j=0}^{n} \frac{z^{j}}{j!} \frac{w^{n-j}}{(n-j)!}$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} \sum_{j=0}^{n} \frac{n!}{j!(n-j)!} z^{j} w^{n-j} \stackrel{\text{Bin.Thm.}}{=} \sum_{n=0}^{\infty} \frac{1}{n!} (z+w)^{n}$$

$$\stackrel{\text{Def.}}{=} \exp(z+w).$$

4.7 Corollary.

- a) For all $z \in \mathbb{C}$ holds: $\exp(-z) = \frac{1}{\exp(z)}$. In particular, $\exp(z) \neq 0$ for all $z \in \mathbb{C}$.
- b) For all $x \in \mathbb{R}$ holds: $\exp(x) > 0$.
- c) For all $q \in \mathbb{Z}$ holds: $\exp(q) = e^q$.
- d) For all $q \in \mathbb{Q}$ holds: $\exp(q) = e^q$.

The proof is left as an exercise. Finally, if we let

$$e^z := \exp(z), \quad z \in \mathbb{C},$$

the above proposition d) implies that this definition extends the original definition of e^q for rational exponents $q \in \mathbb{Q}$ (compare remark II.1.14) to arbitrary exponents $z \in \mathbb{C}$.

5 Power Series

Power series have a long tradition in analysis. If one expresses a function f in the form $f(x) = \sum_{n=0}^{\infty} a_n(x-x_0)^n$, then this is called the *power series expansion of* f centered at x_0 . The general theory of such expansions will be presented in the course on Complex Analysis (Funktionentheorie). Only then, the full importance of power series will become visible.

Apart from these general properties, we are interested in power series because of the fact that their convergence behaviour can be described by the so-called *radius of* convergence. We start with the following definition.

5.1 Definition. Let $(a_n)_n \subset \mathbb{C}$ be a sequence of complex numbers and $z \in \mathbb{C}$. Then $\sum_{n=0}^{\infty} a_n z^n$ is called a *power series*.

In this section we will analyse the question, for which $z \in \mathbb{C}$ the series above converges.

5.2 Definition. Let $(a_n)_n \subset \mathbb{C}$. Then

$$\varrho := \frac{1}{\overline{\lim} \sqrt[n]{|a_n|}}$$

is called the radius of convergence of the series $\sum_{n=0}^{\infty} a_n z^n$ (we use the convention that $\frac{1}{0} = \infty$ and $\frac{1}{\infty} = 0$). This definition of the radius of convergence is also called Cauchy Hadamard formula.

We will in the following call the set

$$U_{\varrho}(0):=\{z\in\mathbb{C}:|z|<\varrho\}$$

the disc of convergence of the series $\sum_{n=0}^{\infty} a_n z^n$.

The following theorem is the main result of this section.

- **5.3 Theorem.** Let $\sum_{n=0}^{\infty} a_n z^n$ be a power series with radius of convergence ϱ . Then for $z \in \mathbb{C}$ we have:
 - a) If $|z| < \varrho$, then $\sum_{n=0}^{\infty} a_n z^n$ is absolutely convergent.
 - b) If $|z| > \varrho$, then $\sum_{n=0}^{\infty} a_n z^n$ diverges.
 - c) If $|z| = \varrho$, then in general no conclusion is possible.

5. POWER SERIES 47

Proof. The proof is an application of the root test. We have $\sqrt[n]{|a_n z^n|} = |z| \sqrt[n]{|a_n|}$. Since

$$\overline{\lim_{n\to\infty}} \sqrt[n]{|a_n z^n|} = |z| \overline{\lim_{n\to\infty}} \sqrt[n]{|a_n|} < 1 \Leftrightarrow |z| < \varrho,$$

the Root Test 3.14 implies the statement of the theorem, i.e. we have

 $|z| < \varrho \Longrightarrow \sum_{n=0}^{\infty} a_n z^n$ converges absolutely.

 $|z| > \varrho \Longrightarrow \sum_{n=0}^{\infty} a_n z^n$ diverges.

 $|z| = \varrho \Longrightarrow$ no conclusion possible.

5.4 Remark. In addition to the root test, one can also use the ratio test to determine the radius of convergence. In particular, let $\sum_{n=0}^{\infty} a_n z^n$ be a power series for which

$$\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| =: q.$$

exists. Then the power series $\sum_{n=0}^{\infty} a_n z^n$ has a radius of convergence $\varrho = \frac{1}{q}$. To prove this we note that

$$\left|\frac{a_{n+1}z^{n+1}}{a_nz^n}\right| \to q|z|, \quad (n \to \infty)$$

holds. If $0 < q < \infty$, we choose $z_1, z_2 \in \mathbb{C}$ with $|z_1| < 1/q$ and $|z_2| > 1/q$, and the ratio test implies that the series $\sum_{n=0}^{\infty} a_n z_1^n$ converges absolutely and the series $\sum_{n=0}^{\infty} a_n z_2^n$ diverges. By Theorem 5.3, we therefore have $\varrho = 1/q$. The cases q = 0 and $q = \infty$ are proved similarly.

5.5 Examples.

a) The exponential series $\sum_{n=0}^{\infty} \frac{z^n}{n!}$ has a radius of convergence of $\varrho = \infty$. Observe that

$$\left|\frac{a_{n+1}}{a_n}\right| = \left|\frac{n!}{(n+1)!}\right| = \frac{1}{n+1} \to 0,$$

so that Remark 5.4 now implies $\varrho = \frac{1}{q} = \infty$.

b) The series $\sum_{n=0}^{\infty} n^n z^n$ has a radius of convergence $\varrho = 0$, because

$$\overline{\lim_{n \to \infty}} \sqrt[n]{|a_n|} = \overline{\lim} \sqrt[n]{n^n} = \overline{\lim} \ n = \infty.$$

and hence $\varrho = \frac{1}{\infty} = 0$.

c) The series $\sum_{n=0}^{\infty} \frac{n!}{n^n} z^n$ has a radius of convergence $\varrho = e$. Proof as exercise.

Chapter III

Continuous Functions and the Basics of Topology

1 Continuous Functions

We begin this chapter by considering continuous functions and their properties. The notion of continuity that we use in the following is — like the notion of convergence — essentially due to Cauchy, who defined the continuity of a function in his *Cours d'Analyse* (1821) as follows:

En d'autres termes, la fonction f(x) restera continue par rapport à x entre les limites données, si, entre ces limites, un accroissement infiniment petit de la variable produit toujours un accroissement infiniment petit de la fonction elle-même.

Cauchy still used the then-common concept of 'infinitely small quantitiy' (quantité infiniment petite), however this was replaced over the years by the ε - δ formulation which is customary today. The latter was vitally influenced by Weierstraß.

We recall the definition of a function: Let X and Y be sets and $f: X \to Y$ a function, i.e. a rule that assigns a *unique* (eindeutig) element $y \in Y$ to every $x \in X$. The set graph $f := \{(x, f(x)), x \in X\} \subset X \times Y$ is called the graph of f.

We start with the definition of continuity of a function which builds on the concept of convergence.

1.1 Definition. (Continuity). A function $f: D \subset \mathbb{K} \to \mathbb{K}$ is called *continuous* (stetig) at $x_0 \in D$, if for every sequence $(x_n)_{n\geq 1} \subset D$ with $\lim_{n\to\infty} x_n = x_0$, it holds that

$$\lim_{n \to \infty} f(x_n) = f(x_0).$$

In other words:

$$(x_n) \subset D, \ x_n \to x_0 \implies f(x_n) \to f(x_0).$$

The function f is called *continuous in D*, if f is continuous at all points $x_0 \in D$.

The following theorem is a reformulation of the definition of continuity in ε - δ -language.

1.2 Theorem. (ε - δ criterion). A function $f:D\subset\mathbb{K}\longrightarrow\mathbb{K}$ is continuous at $x_0\in D$ if and only if

$$(\forall \varepsilon > 0) (\exists \delta > 0) (\forall x \in D, |x - x_0| < \delta) |f(x) - f(x_0)| < \varepsilon.$$

Proof. " \Longrightarrow ": We assume that the assertion is false. Then there exists an $\varepsilon_0 > 0$ such that for all $n \in \mathbb{N}$ there exists an $x_n \in D$ with

$$|x_0 - x_n| < 1/n \text{ and } |f(x_0) - f(x_n)| \ge \varepsilon_0.$$

Then $\lim_{n\to\infty} x_n = x_0$ but $f(x_n) \not\to f(x_0)$ for $n\to\infty$. Contradiction!

"\(\iff \)": By assumption, for every $\varepsilon > 0$, there exists a $\delta > 0$ with $|x - x_0| < \delta \Longrightarrow |f(x) - f(x_0)| < \varepsilon$. Let $x_n \to x_0$. Then there exists an $N_0 \in \mathbb{N}$ with $|x_n - x_0| < \delta$ for all $n \ge N_0$. Therefore, $|f(x_n) - f(x_0)| < \varepsilon$ for all $n \ge \mathbb{N}_0$, i.e. $\lim f(x_n) = f(x_0)$.

1.3 Examples. a) Let $f : \mathbb{R} \to \mathbb{R}$ be given by f(x) = ax + b with $a, b \in \mathbb{R}$. Then f is continuous, since $x_n \to x_0$ implies $f(x_n) = ax_n + b \to ax + b = f(x)$.

- b) The absolute value $f: \mathbb{R} \to \mathbb{R}, x \mapsto |x|$ is a continuous function.
- c) The *Heavyside function* $f : \mathbb{R} \to \mathbb{R}$, defined by

$$f(x) = \begin{cases} 0 & x \le 0 \\ 1 & x > 0 \end{cases}$$

is continuous for all $x \in \mathbb{R} \setminus \{0\}$, but not continuous in 0.

d) The function f, given by

$$f: \mathbb{R} \to \mathbb{R}, f(x) = \begin{cases} 1, & x \ge 1, \\ \frac{1}{n}, & \frac{1}{n} \le x < \frac{1}{n-1}, & n = 2, 3, \dots \\ 0, & x \le 0, \end{cases}$$

is continuous at 0, since we can choose e.g. $\delta = \varepsilon$ because of $|f(x) - f(0)| = |f(x)| \le |x|$.

e) The Dirichlet Function (Dirichletsche Sprungfunktion), given by

$$f: \mathbb{R} \to \mathbb{R}, f(x) = \left\{ \begin{array}{ll} 0, & x \in \mathbb{Q} \\ 1, & x \in \mathbb{R} \setminus \mathbb{Q} \end{array} \right.$$

is discontinuous at all points $x \in \mathbb{R}$. Proof as an exercise.

f) Consider the function given by

$$f: \mathbb{R} \to \mathbb{R}, f(x) = \left\{ \begin{array}{ll} \frac{1}{q}, & x = \frac{p}{q} \in \mathbb{Q} & \text{with } q > 0 \text{ minimal} \\ 0, & x \in \mathbb{R} \setminus \mathbb{Q} \end{array} \right.$$

Then f is continuous at all points $x_0 \in \mathbb{R} \setminus \mathbb{Q}$ but discontinuous at $x_0 \in \mathbb{Q}$! Proof as an exercise.

g) Let $f: D \subset \mathbb{R} \to \mathbb{R}$. Assume there exists an L > 0 with

$$|f(x) - f(y)| < L|x - y|, \quad x, y \in D.$$

Then f is continuous. Indeed, choose for $\varepsilon > 0$ a δ such that $\delta := \frac{\varepsilon}{L+1}$. A function that satisfies the above condition is called *Lipschitz continuous* and L is called the *Lipschitz constant* of f.

- h) Every Lipschitz-continuous function f is continuous. The converse does not hold. Consider, for example, $f:[0,1]\to\mathbb{R}$ given by $f(x)=\sqrt{x}$. Then f is continuous, but not Lipschitz-continuous (Exercise).
- i) Let the functions $f_1, \dots f_4 : \mathbb{C} \to \mathbb{C}$ be given by

$$f_1(z) = |z|, \quad f_2(z) = \bar{z}, \quad f_3(z) = \text{Re } z, \quad f_4(z) = \text{Im } z.$$

Then the functions $f_1, \dots f_4$ are Lipschitz-continuous with Lipschitz-constant 1, and therefore continuous.

The above definition of continuity via sequences allows us to apply our knowledge about convergent sequences to continuous functions. More precisely, we first define the sum, the product and the quotient of two functions. For this, let $f, g : D \subset \mathbb{K} \to \mathbb{K}$ be two functions, and $\alpha, \beta \in \mathbb{K}$. If we define

$$\alpha f + \beta g : D \to \mathbb{K}, \qquad (\alpha f + \beta g)(x) := \alpha f(x) + \beta g(x)$$

$$f \cdot g : D \to \mathbb{K}, \qquad (f \cdot g)(x) := f(x) \cdot g(x)$$

$$\frac{f}{g} : \{x \in D : g(x) \neq 0\} \to \mathbb{K}, \qquad (\frac{f}{g})(x) := \frac{f(x)}{g(x)},$$

we have the following theorem.

- **1.4 Theorem.** Let $f, g : D \subset \mathbb{K} \to \mathbb{K}$ be continuous at $x_0 \in D$. Then the following statements hold:
 - a) $\alpha f + \beta g : D \to \mathbb{K}$ is continuous at $x_0 \in D$ for all $\alpha, \beta \in \mathbb{K}$.
 - b) $f \cdot g : D \to \mathbb{K}$ is continuous at x_0 .

c) If $g(x_0) \neq 0$, then there exists $\delta > 0$ with $g(x) \neq 0$ for $x \in U_{\delta}(x_0) \cap D$ and $\frac{f}{g}: U_{\delta}(x_0) \cap D \to \mathbb{K}$ is continuous at x_0 .

Proof. The statements a) and b) follow from 1.1 and the calculation rules of convergent sequences.

c) By assumption $|g(x_0)| =: \gamma > 0$. Because g is continuous at x_0 it follows that there exists a $\delta > 0$ such that

$$|g(x_0)| - |g(x)| \le |g(x_0) - g(x)| < \frac{\gamma}{2}, \quad x \in U_\delta(x_0) \cap D.$$

Therefore, $|g(x)| > \frac{\gamma}{2}$ for $x \in U_{\delta}(x_0) \cap D$. The assertion then follows from the calculation rules of convergent sequences.

We now consider the composition of two functions $f: D_f \subset \mathbb{K} \to \mathbb{K}$ and $g: D_g \subset \mathbb{K} \to \mathbb{K}$ with $g(D_g) \subset D_f$. We define then $f \circ g: D_g \to \mathbb{K}$ as

$$(f \circ g)(x) := f(g(x)).$$

The following theorem says that the composition of two continuous functions is again continuous.

1.5 Theorem. Let $f: D_f \subset \mathbb{K} \to \mathbb{K}$ and $g: D_g \subset \mathbb{K} \to \mathbb{K}$ be functions with $g(D_g) \subset D_f$. If g is continuous at $x_0 \in D_g$ and f is continuous at $g(x_0) \in D_f$, then $f \circ g$ is continuous at x_0 .

Proof. Let $(x_n) \subset D_g$ be a sequence in D_g with $\lim_{n \to \infty} x_n = x_0$. By assumption g is continuous at x_0 ; therefore, $g(x_n) \to g(x_0)$. Then, because f is continuous at $g(x_0)$ it follows that $(f \circ g)(x_n) = f(g(x_n)) \to f(g(x)) = (f \circ g)(x)$, i.e. $f \circ g$ is continuous at x_0 .

1.6 Examples. a) Polynomials, i.e. functions of the form

$$x \mapsto a_n x^n + a_{n-1} x^{n-1} + \dots + a_0$$
, with $a_i \in \mathbb{K}$

for $j = 0, 1, 2, \dots, n$, are continuous.

b) If p and q are polynomials, then the function $\frac{p}{q}$ given by

$$\frac{p}{q}(z) := \frac{p(z)}{q(z)} \text{ with } D_{\frac{p}{q}} = \{z \in \mathbb{K} : q(z) \neq 0\}$$

is also continuous. Such functions are called rational functions (rationale Funktionen).

c) The sign function (Signumfunktion) sign : $\mathbb{C}\setminus\{0\}\to\mathbb{C}$, sign $(z):=\frac{z}{|z|}$ is continuous.

Power series are the natural generalisation of polynomials. In the following theorem, we show that power series are continuous functions inside their disc of convergence.

1.7 Theorem. Let $\sum_{n=0}^{\infty} a_n z^n$ be a power series with radius of convergence $\varrho > 0$. Then $f: B_{\varrho}(0) := \{z \in \mathbb{C} : |z| < \varrho\} \to \mathbb{C}, z \mapsto \sum_{n=0}^{\infty} a_n z^n$ is a continuous function.

Proof. Let $z_0 \in B_{\varrho}(0)$, $\varepsilon > 0$ and choose r > 0 such that $|z_0| < r < \varrho$. Theorem II, 5.3 implies that $\sum_{n=0}^{\infty} |a_n| r^n$ converges, i.e. that $N_0 \in \mathbb{N}$ exists with

$$\sum_{n=N_0+1}^{\infty} |a_n| \, r^n < \frac{\varepsilon}{4}.$$

Thus for $z \in \mathbb{C}$ with $|z| \leq r$

$$|f(z) - f(z_0)| \leq |\sum_{n=0}^{N_0} a_n z^n - \sum_{n=0}^{N_0} a_n z_0^n| + \sum_{n=N_0+1}^{\infty} |a_n| |z|^n + \sum_{n=N_0+1}^{\infty} |a_n| |z_0|^n$$

$$= |p(z) - p(z_0)| + 2 \sum_{n=N_0+1}^{\infty} |a_n| r^n$$

with $p(w) = \sum_{n=0}^{N_0} a_n w^n$. Since polynomials are continuous, there exists $\delta \in (0, r - |z_0|)$ with $|p(z) - p(z_0)| < \frac{\varepsilon}{2}$ if $|z - z_0| < \delta$. Therefore $|f(z) - f(z_0)| < \varepsilon$ if $|z - z_0| < \delta$.

When applied to the exponential function, the above theorem implies that the exponential function is continuous for all $z \in \mathbb{C}$.

1.8 Corollary. (Exponential Function (Exponential funktion)) The exponential function

$$\exp: \mathbb{C} \to \mathbb{C}, \qquad z \mapsto \exp(z)$$

is continuous.

Proof. By Example II.5.5a) the series $\sum_{n=0}^{\infty} \frac{z^n}{n!}$ has radius of convergence $\varrho = \infty$. Theorem 1.7 implies the assertion.

Many existence statements in analysis depend on the so-called *intermediate value the-orem*. Bolzano was the first to realise the necessity of proving this apparently 'self-evident' statement. From the modern point of view, the following theorem is a variation of the completeness of \mathbb{R} . In the following, we again set $[a,b] := \{x \in \mathbb{R} : a \leq x \leq b\}$ for $a,b \in \mathbb{R}$, a < b.

1.9 Theorem. (Intermediate Value Theorem (Zwischenwertsatz)) Let $a, b \in \mathbb{R}$ with a < b. Further, let $f : [a, b] \to \mathbb{R}$ be a continuous function with f(a) < 0 and f(b) > 0 (or f(a) > 0 and f(b) < 0). Then there exists an $x_0 \in [a, b]$ with $f(x_0) = 0$.

Though the above theorem is intuitively obvious, caution is required: for example, let $D = \{x \in \mathbb{Q} : 1 \le x \le 2\}$ and $f : D \to \mathbb{R}$ be given by $x \mapsto x^2 - 2$. Then f(1) = -1 < 0 and f(2) = 2 > 0, but there exists $no \ x_0 \in D$ with $f(x_0) = 0$.

Proof. Consider the set $M := \{x \in [a,b] : f(x) \leq 0\}$. Then $a \in M$ and hence $M \neq \emptyset$. Additionally M is bounded from above by b. The completeness axiom implies $x_0 := \sup M$ exists. Now we show that $f(x_0) = 0$.

We assume that $f(x_0) < 0$. By hypothesis, f is continuous; thus for $\varepsilon := \frac{-f(x_0)}{2} > 0$, there exists a $\delta > 0$ with $\delta < b - x_0$ and

$$f(x) - f(x_0) < \varepsilon$$
, whenever $x \in (x_0 - \delta, x_0 + \delta) \cap [a, b]$.

Therefore, $f(x) < \frac{f(x_0)}{2} < 0$ for all $x \in (x_0 - \delta, x_0 + \delta) \cap [a, b]$ and, therefore,

$$(x_0 - \delta, x_0 + \delta) \cap [a, b] \subset M.$$

Then $x_0 + \frac{\delta}{2} \in M$ in contradiction to the definition of x_0 .

We now assume that $f(x_0) > 0$. Analogously to the above, the hypothesis f being continuous implies that to $\varepsilon := \frac{f(x_0)}{2} > 0$ there exists a $\delta > 0$ with $\delta < x_0 - a$ and

$$f(x_0) - f(x) < \varepsilon$$
 $x \in (x_0 - \delta, x_0 + \delta) \cap [a, b].$

Therefore $0 < \frac{f(x_0)}{2} < f(x)$ for all $x \in (x_0 - \delta, x_0 + \delta) \cap [a, b]$ and, therefore,

$$(x_0 - \delta, x_0 + \delta) \cap [a, b] \cap M = \emptyset.$$

This implies that $x_0 - \delta/2$ is an upper bound of M in contradiction to the definition of x_0 . Summarizing, we have that $f(x_0) = 0$.

1.10 Remarks.

- a) Let $f : [a, b] \to \mathbb{R}$ be a continuous function. Then f takes every value between f(a) and f(b). In other words, let (without loss of generality) f(a) < c < f(b). Then there exists an $x_0 \in [a, b]$ with $f(x_0) = c$. Proof as exercise.
- b) Every polynomial of odd degree with real coefficients has at least one root.
- c) For all y > 0 there exists exactly one $x \in \mathbb{R}$ with $\exp(x) = y$. We denote x by

$$x := \log y$$

and call it the natural logarithm (natürlichen Logarithmus) of y.

In order to see this property, observe that for $n \in \mathbb{N}$,

$$\exp(n) = 1 + n + \frac{n^2}{2!} + \dots \ge 1 + n \to \infty.$$

The functional equation of the exponential function implies that $\exp(-n) = \frac{1}{\exp(n)} \to 0$. Thus, there exists an $N_0 \in \mathbb{N}$ with $\exp(-N_0) < y < \exp(N_0)$. Because $\exp(-N_0, N_0) \to \mathbb{R}$ is continuous (see Corollary 1.8), by the intermediate value theorem, there exists an $x \in [-N_0, N_0]$ with $\exp(x) = y$.

In order to prove the uniqueness, we assume that there exists a z, x < z, with $\exp x = y = \exp z$. The functional equation of the exponential function then implies that $\exp(z) = \exp(h) \exp(x)$ for h = z - x. Since h > 0 and

$$\exp h = 1 + h + \ldots > 1$$

we get $\exp(x) < \exp(z)$. This is a contradiction.

The function $\log : (0, \infty) \to \mathbb{R}$ is called *logarithm function*.

As a further application of the intermediate value theorem, we now consider the image of an interval under a continuous function. Here the following subsets of \mathbb{R} are called *intervals* (Intervalle):

$$(a,b) := \{x \in \mathbb{R} : a < x < b\}$$

$$[a,b) := \{x \in \mathbb{R} : a \le x < b\}$$

$$(a,b] := \{x \in \mathbb{R} : a < x \le b\}$$

$$[a,b] := \{x \in \mathbb{R} : a \le x \le b\}$$

$$(-\infty,b) := \{x \in \mathbb{R} : x < b\}$$

$$(-\infty,b] := \{x \in \mathbb{R} : x \le b\}$$

$$(a,\infty) := \{x \in \mathbb{R} : x \ge a\}$$

$$[a,\infty) := \{x \in \mathbb{R} : x \ge a\}$$

$$[a,\infty) := \mathbb{R}$$

1.11 Theorem. (Continuous Images of Intervals) Let I be an interval and $f: I \to \mathbb{R}$ be a continuous function. Then f(I) is an interval.

Proof. First let I = [a, b] be a <u>closed and bounded interval</u>.

We first show that f(I) is bounded: Assume f(I) is not bounded. Then there exists a sequence $(y_n)_n$ of elements of f(I) such that $|y_n| > n$ for all $n \in \mathbb{N}$. On the other hand, there exists a sequence $(x_n)_n$ in I with $f(x_n) = y_n$ for all $n \in \mathbb{N}$. The sequence

 $(x_n)_n$ is bounded since I is bounded by assumption. By Bolzano-Weierstraß, $(x_n)_n$ has therefore a convergent subsequence $(x_{n_k})_k$ with $x_{n_k} \stackrel{k \to \infty}{\longrightarrow} x_0 \in [a, b]$. By the continuity of f, we have $f(x_{n_k}) \stackrel{k \to \infty}{\longrightarrow} f(x_0)$. On the other hand, we have $|f(x_{n_k})| > n_k$, and this is a contradiction.

Next we show that f(I) is closed: Since f(I) is bounded, inf f(I) and $\sup f(I)$ exist (as finite numbers). We show that infimum and supremum are in fact minimum and maximum, respectively, and we carry out the proof for the maximum.

By the characterisation of the supremum we know that there exists a sequence $(x_n)_n$ in I such that $f(x_n) \xrightarrow{n \to \infty} \sup f(I)$, and again by Bolzano-Weierstraß, this sequence has a convergent subsequence $(x_{n_k})_k$, and its limit p is contained in I, because we assumed I to be closed. By continuity, we have $f(x_{n_k}) \xrightarrow{k \to \infty} f(p)$ and because the limit of a sequence is unique, this implies $f(p) = \sup f(I)$, whence $\sup f(I)$ is an element of f(I). Analogously, we can show that there exists $q \in [a,b]$ with $f(q) = \inf f(I)$.

By the intermediate value theorem, we can infer that f takes any value between f(q) and f(p) on I, hence f(I) = [f(p), f(q)] is an interval.

Next let I be a bounded and open interval, i.e. I is of the form I = (a, b). Then we can express I as the following infinite union.

$$I = \bigcup_{\substack{n \in \mathbb{N} \\ 1/n < (b-a)/2}} [a + 1/n, b - 1/n]$$

By the argument above, each f([a+1/n,b-1/n]) is an interval, and hence

$$f(\bigcup_{\substack{n \in \mathbb{N} \\ 1/n < (b-a)/2}} [a+1/n, b-1/n]) \stackrel{\text{see ex. T 4.1}}{=} \bigcup_{\substack{n \in \mathbb{N} \\ 1/n < (b-a)/2}} f([a+1/n, b-1/n])$$

is an ascending union of intervals, which is again an interval.

If the interval is of the form [a, b) or (a, b] or unbounded in one or both directions, we can apply essentially the same argument and express the interval as an ascending union of closed and bounded intervals.

Below we give a list of possible representations for the remaining forms of I.

$$\begin{aligned} [a,b) &= \bigcup [a,b-1/n] & [a,\infty) &= \bigcup [a,n] & (-\infty,b] &= \bigcup (-n,b] \\ (a,b] &= \bigcup [a+1/n,b] & (a,\infty) &= \bigcup [a+1/n,n] & (-\infty,b) &= \bigcup [-n,b-1/n] \\ (-\infty,\infty) &= \bigcup [-n,n] & \end{aligned}$$

Our next task is to check the continuity of the inverse function of a given continuous function (so long as it exists). We introduce the following concepts:

1.12 Definition. A function $f: D \subset \mathbb{R} \to \mathbb{R}$ is called (monotone) increasing, if $x, y \in D, x < y \Rightarrow f(x) \leq f(y)$ strictly (monotone) increasing, if $x, y \in D, x < y \Rightarrow f(x) < f(y)$ (monotone) decreasing, if $x, y \in D, x < y \Rightarrow f(x) \geq f(y)$ strictly (monotone) decreasing, if $x, y \in D, x < y \Rightarrow f(x) \geq f(y)$ monotone, if f is increasing or decreasing. strictly monotone, if f is strictly increasing or strictly decreasing.

At this point we recall the definition of injectivity: A function $f: D \subset \mathbb{R} \to \mathbb{R}$ is called injective (injektiv), if $f(x_1) = f(x_2) \Rightarrow x_1 = x_2$. A strictly monotone function $f: D \subset \mathbb{R} \to \mathbb{R}$ is injective and it is possible to define the inverse function (Umkehrfunktion) $f^{-1}: f(D) \to D$ via the following:

$$f^{-1}: f(D) \to D, f^{-1}(y) = x :\Leftrightarrow y = f(x).$$

The graph of f^{-1} is simply the reflection of the graph of f around the line x = y, i.e.

$$\operatorname{graph}(f^{-1}) = \{(y, f^{-1}(y)) : y \in f^{-1}(D)\} = \{(f(x), x) : x \in D\}.$$

We now consider the question whether or not the inverse function of a continuous function is also continuous.

1.13 Theorem. Let I be an interval and $f: I \to \mathbb{R}$ be a continuous, strictly monotone function. Then the inverse function $f^{-1}: f(I) \to \mathbb{R}$ is continuous.

Proof. W.l.o.g. let f be strictly increasing. We divide the proof into three steps:

- 1) By Theorem 1.11, f(I) =: J is an interval. We set $g := f^{-1}: J \to I$.
- 2) The function g is strictly increasing: If $s_1 < s_2$ in J then $g(s_1) < g(s_2)$. Otherwise $g(s_1) \ge g(s_2)$ and the monotonicity of f would give

$$s_1 = f(g(s_1)) \ge f(g(s_2)) = s_2$$
 – a contradiction.

3) The inverse function q is continuous:

Consider first the case of a closed bounded interval I := [a, b]. Then by the proof of Theorem 1.11, f(I) =: J is a closed bounded interval. Now assume that g is discontinuous at $s_0 \in J$. Then there exists an $\varepsilon_0 > 0$ and a sequence $(s_n)_n \subset J$ with

$$|s_n - s_0| < \frac{1}{n}$$
 and $|g(s_n) - g(s_0)| \ge \varepsilon_0$ for all $n \in \mathbb{N}$.

Set $t_n := g(s_n) \in [a, b]$. By the theorem of Bolzano-Weierstraß the sequence $(t_n)_n$ contains a convergent subsequence $(t_{n_k})_{k \in \mathbb{N}}$ with limit $t_0 \in [a, b]$. Because f is continuous, it follows that $f(t_{n_k}) \stackrel{k \to \infty}{\longrightarrow} f(t_0)$.

On the other hand, $f(t_{n_k}) = s_{n_k} \xrightarrow{k \to \infty} s_0$ and the uniqueness of the limit implies that $s_0 = f(t_0)$. Therefore,

$$g(s_{n_k}) = t_{n_k} \stackrel{k \to \infty}{\longrightarrow} t_0 = g(s_0)$$

in contradiction to the above property of the sequence $(g(s_n))_n$.

Next let I=(a,b) be an open bounded interval and $s_0 \in J$ arbitrary. Then to $g(s_0)=:t_0\in(a,b)$ one can find a closed bounded interval $[c,d]\subset(a,b)$ with $t_0\in(c,d)$. Thus, by the [a,b]-case, the continuity of g in s_0 , hence on J. As in the proof of Theorem 1.11 the remaining cases of intervals can be reduced to the above two cases.

We conclude this chapter with some examples.

1.14 Examples. a) For $n \in \mathbb{N}$, the *n*-th root function

$$f:[0,\infty)\to[0,\infty),\quad x\mapsto\sqrt[n]{x}$$

is continuous and strictly increasing. To see this, consider the function

$$g:[0,\infty)\to[0,\infty),\quad t\mapsto t^n.$$

Then g is continuous and strictly monotone, because for $0 \le s < t$, we have

$$g(t) - g(s) = t^n - s^n = t^n (1 - (\frac{s}{t})^n) > 0.$$

The claim then follows from 1.13.

b) The exponential function exp : $\mathbb{R} \to \mathbb{R}$ is strictly increasing. We repeat the argument from Remark 1.10 c). Because we have $e^{x+h} = e^h e^x$ for all $x \in \mathbb{R}$ and h > 0, the strict monotonicity of the exponential function follows from the estimate

$$e^h = 1 + h + \frac{h^2}{2!} + \dots > 1, \quad h > 0.$$

Furthermore, the exponential function $\exp : \mathbb{R} \to (0, \infty)$ is continuous by Corollary 1.8. The above theorem about inverse functions then states that the logarithm function $\log : (0, \infty) \to \mathbb{R}, x \mapsto \log x$, which was defined in 1.10 c) as the inverse function of the exponential function, is continuous as well.

c) For x > 0 and $\alpha \in \mathbb{R}$, we define the general power by

$$x^{\alpha} := \exp(\alpha \log x).$$

Then, the two functions

$$f_x: \mathbb{R} \to \mathbb{R}, \quad f_x(\alpha) := x^{\alpha} \quad \text{for fixed } x > 0 \text{ and}$$

 $g_{\alpha}: (0, \infty) \to \mathbb{R}, \quad g_{\alpha}(x) := x^{\alpha} \quad \text{for fixed } \alpha \in \mathbb{R}$

are continuous.

At this point, we note that the above definition extends the previous definition of powers with rational exponents from Remark II.1.14 to arbitrary exponents $\alpha \in \mathbb{R}$. To see this, for given x > 0 and $\alpha = \frac{p}{q} \in \mathbb{Q}$, $p \in \mathbb{Z}$, $q \in \mathbb{N}$, we deduce from the uniqueness of the root that

$$\exp(\frac{p}{q}\log x) = \left(\exp(\frac{\log x}{q})\right)^p = \left(\sqrt[q]{\exp(\log x)}\right)^p = (\sqrt[q]{x})^p.$$

d) If $f:D\subseteq\mathbb{R}\to\mathbb{R}$ is continuous and strictly monotone, then f^{-1} is not continuous in general if D is not an interval. Consider for example the function $f:D=[0,1)\cup\{2\}$, given by

$$f(x) = \begin{cases} x, & \text{for } x \in [0, 1) \\ 1, & \text{for } x = 2. \end{cases}$$

Then f is continuous and strictly monotone, but $f^{-1}: f(D) = [0,1] \to \mathbb{R}$, given by

$$f^{-1}(y) = \begin{cases} y, & \text{for } y \in [0, 1) \\ 2, & \text{for } y = 1 \end{cases}$$

is not continuous at y = 1.

2 Basics of Topology

We begin this section with the concept of vector spaces, which play an important role in modern analysis. Throughout the section we let the scalar field be $\mathbb{K} = \mathbb{R}$ or $\mathbb{K} = \mathbb{C}$.

We start by recalling the definition of a vector space, as known from linear algebra.

- **2.1 Definition.** A vector space (Vektorraum) over \mathbb{K} , or a \mathbb{K} -VS is a triple $(V, +, \cdot)$ consisting of a set $V \neq \emptyset$, an addition $+: V \times V \to V$, $(u, v) \mapsto u + v$, and a multiplication by scalars $\cdot: \mathbb{K} \times V \to V$, $(\lambda, v) \mapsto \lambda \cdot v$, are defined in accordance with the following rules:
- (VR1) (V, +) is an abelian group
- (VR2) Distributivity:

$$\lambda(v+w) = \lambda v + \lambda w, \qquad (\lambda + \mu)v = \lambda v + \mu v, \quad \lambda, \mu \in \mathbb{K}, \quad v, w \in V$$

(VR3)
$$\lambda \cdot (\mu v) = (\lambda \mu) \cdot v, \quad 1 \cdot v = v, \quad \lambda, \mu \in \mathbb{K}, \ v \in V$$

The vector space is called *real* if $\mathbb{K} = \mathbb{R}$, and *complex* if $\mathbb{K} = \mathbb{C}$.

The elements of V are called *vectors* (*Vektoren*), while the elements of \mathbb{K} are called *scalars* (*Skalare*). More information about the concept of vector spaces will be given in the Linear Algebra lectures.

2.2 Examples.

a) Let $n \in \mathbb{N}$, $x = (x_1, x_2, \dots, x_n) \in \mathbb{K}^n$ and $y = (y_1, y_2, \dots, y_n) \in \mathbb{K}^n$. Then \mathbb{K}^n is a \mathbb{K} -VS equipped with

$$x + y := (x_1 + y_1, \dots, x_n + y_n)$$

 $\lambda \cdot x := (\lambda x_1, \dots, \lambda x_n), \quad \lambda \in \mathbb{K}.$

In particular, \mathbb{R}^n and \mathbb{C}^n are vector spaces.

b) Let X be a set. Then $V^X := \{f: X \longrightarrow V: f \text{ is a map}\}$ is a vector space with

$$(f+g)(x): = f(x) + g(x), x \in X$$

 $(\lambda f)(x): = \lambda f(x), x \in X, \lambda \in \mathbb{K}$

c) The set $c_0 := \{(x_n)_{n \geq 1} \subset \mathbb{K} : (x_n) \text{ is a null sequence} \}$ is a \mathbb{K} -vector space with coordinate-wise addition and scalar multiplication

$$(x_n)_n + (y_n)_n := (x_1 + y_1, x_2 + y_2, \cdots) = (x_n + y_n)_n,$$

 $\lambda(x_n)_n := (\lambda x_1, \lambda x_2, \cdots) = (\lambda x_n)_n.$

This follows from the calculation rules for convergent sequences.

We now want to equip the vector space \mathbb{R}^n with a *Euclidean structure* and, therefore, introduce the idea of a distance between two elements $x, y \in \mathbb{R}^n$. We call

$$|x-y| := d(x,y) := \sqrt{(x_1 - y_1)^2 + \dots + (x_n - y_n)^2}$$

the Euclidean distance (euklidischer Abstand) between x and y. In particular, the Euclidean distance of x to the origin is $|x| = d(x,0) = \sqrt{\sum_{i=1}^{n} x_i^2}$. We sometimes write ||x-y|| instead of |x-y|. We call

$$B_r(x) := \{ y \in \mathbb{R}^n : d(y, x) = |y - x| < r \}, \quad x \in \mathbb{R}^n, \ r > 0,$$

the open ball (offene Kugel) with center x and radius r with respect to d.

In the following, we transfer the concept of convergence for sequences and series of real numbers, which we introduced earlier, to sequences and series in the Euclidean space \mathbb{R}^n . For this, it proves useful to introduce some basic topological concepts for subsets of \mathbb{R}^n . These concepts are mostly due to Felix Hausdorff.

- **2.3 Definition.** a) A subset $U \subset \mathbb{R}^n$ is called a *neighborhood (Umgebung)* of $x \in \mathbb{R}^n$, if there exists an $\varepsilon > 0$ with $B_{\varepsilon}(x) \subset U$. The set $B_{\varepsilon}(x)$ is also called an ε -neighborhood of x.
- b) A set $A \subset \mathbb{R}^n$ is called *open (offen)*, if for every $x \in A$ there exists an $\varepsilon > 0$ such that $B_{\varepsilon}(x) \subset A$.

Examples. Let $a, b \in \mathbb{R}$ with a < b. Then:

- a) The set U=(a,b) is open. In fact, let $x \in (a,b)$; set $\varepsilon := \min(|a-x|,|b-x|)$, then $B_{\varepsilon}(x) \subset (a,b)$.
- b) The intervals (a, ∞) and $(-\infty, a)$ are both open.
- c) The inverval [a, b] is not open, since $B_{\varepsilon}(a) \not\subset [a, b]$ for every $\varepsilon > 0$.
- d) $B_r(x)$ is an open subset of \mathbb{R}^n . (Exercise).
- **2.4 Definition.** A set $A \subset \mathbb{R}^n$ is called *closed (abgeschlossen)*, if $\mathbb{R}^n \setminus A$ is open in \mathbb{R}^n . Here, $\mathbb{R}^n \setminus A := \{x \in \mathbb{R}^n : x \notin A\}$.

Examples. Let $a, b \in \mathbb{R}$ with a < b. Then:

- a) (a,b) is not closed in \mathbb{R} ,
- b) [a, b] is closed in \mathbb{R} ,
- c) [0,1) is not open and not closed in \mathbb{R} ,
- d) Q given by $Q := \{(x_1, \dots x_n) \in \mathbb{R}^n : a_i \leq x_i \leq b_i, 1 \leq i \leq n\}$ where $a_i, b_i \in \mathbb{R}$ with $a_i \leq b_i$ is closed in \mathbb{R}^n .

62CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

In the following two theorems, we examine unions and intersections of open respectively closed sets.

2.5 Theorem. The following statements hold:

- a) The empty set \emptyset and also \mathbb{R}^n are open in \mathbb{R}^n . (Thus the property open is <u>not</u> a negation of the property closed.)
- b) Let $O_{\alpha} \subset \mathbb{R}^n$, $\alpha \in I$ be open sets. Then $\bigcup_{\alpha \in I} O_{\alpha}$ is open in \mathbb{R}^n , i.e. a union of arbitrarily many open sets is open.
- c) Let $U_1, U_2 \cdots U_N$ be open sets. Then $\bigcap_{i=1}^N U_i$ is open in \mathbb{R}^n , i.e. a finite intersection of open sets is open.

Proof as exercise. The example of the open intervals $\left(-\frac{1}{n}, 1 + \frac{1}{n}\right) = I_n$ with $[0, 1] = \bigcap_{n=1}^{\infty} I_n$ shows that in general, arbitrary intersections of open sets are not open.

2.6 Theorem. (analogous to Theorem 2.5)

- a) The empty set \emptyset and \mathbb{R}^n are closed.
- b) Intersections of arbitrarily many closed sets are closed.
- c) Finite unions of closed sets are closed.

The proof follows from Theorem 2.5 and de Morgan's Rule. (Exercise).

Observe that the statement from Theorem 2.6 c) does not hold for arbitrary unions of closed sets. In fact, $B_{\frac{1}{n}}(0)^C$ is closed for all n, but $\bigcup_{n=1}^{\infty} [B_{\frac{1}{n}}(0)^c] = \mathbb{R}^n \setminus \{0\}$ is not closed.

In the following, we continue to introduce basic topological concepts.

- **2.7 Definition.** a) Let $A \subset \mathbb{R}^n$ and $x \in \mathbb{R}^n$. Then x is called a boundary point (Randpunkt) of A, if every neighborhood U of x contains both a point from A and from $\mathbb{R}^n \setminus A$.
- b) The set

$$\partial A := \{x \in \mathbb{R}^n : x \text{ is a boundary point of } A\}$$

is called the *boundary* (Rand) of A and

$$A := A \backslash \partial A$$

is called the interior (Inneres) of A. An element $a \in \mathring{A}$ is called an interior point (innerer Punkt) of A.

- 63
- c) Additionally, $x \in \mathbb{R}^n$ is called an accumulation point (Häufungspunkt) of $A \subset \mathbb{R}^n$, if every neighborhood of x contains infinitely many elements of A.
- d) We call

$$\overline{A} := \{x \in \mathbb{R}^n : x \in A \text{ or } x \text{ is an accumulation point of } A\}$$

the closure (Abschlu β) of A.

e) Finally, $A \subset \mathbb{R}^n$ is called *bounded (beschränkt)*, if there exists an $x \in \mathbb{R}^n$ and an r > 0 with $A \subset B_r(x)$.

As an example, we consider the closed unit ball $A = \{x \in \mathbb{R}^n : |x| \leq 1\}$. Its interior is the *open* unit ball $\mathring{A} = \{x \in \mathbb{R}^n : |x| < 1\}$, and its boundary is the *unit sphere* $\partial A = \{x \in \mathbb{R}^n : |x| = 1\}$.

The following properties of open respectively closed sets often prove useful.

2.8 Remarks. (Interior, Boundary, Closure) Let $M \subset \mathbb{R}^n$. Then:

a)

$$\mathring{M} = \bigcup_{O \subseteq M, O \text{ open}}$$

is open. i.e. \mathring{M} is the largest open set that is contained in M.

b)

$$\overline{M} = \mathring{M} \cup \partial M = \bigcap_{M \subseteq A, A \text{ closed}} A,$$

i.e. \overline{M} is the smallest closed set in which M is contained.

- c) $\partial M = \overline{M} \cap \overline{\mathbb{R}^n \backslash M}$ is closed.
- **2.9 Theorem.** (Hausdorff's Separation Axiom) Let $x, y \in \mathbb{R}^n$ with $x \neq y$. Then there exist neighborhoods U_x of x and U_y of y with $U_x \cap U_y = \emptyset$.

The proof is not difficult: set $U_x := U_{\varepsilon}(x), U_y := U_{\varepsilon}(y)$ with $\varepsilon := \frac{|x-y|}{2}$. We assume that a $z \in \mathbb{R}^n$ exists with $z \in U_x \cap U_y$. However, we then have $2\varepsilon = |x-y| \le |x-z| + |z-y| < 2\varepsilon$. Contradiction!

After the analysis of the convergence of real or complex sequences $(a_j)_j$ in Chapter 2, we now consider the convergence of sequences $(a_j)_j \subset \mathbb{R}^n$.

2.10 Definition. Let $(a_j)_{j\in\mathbb{N}}\subset\mathbb{R}^n$ be a sequence. Then $(a_j)_j$ is called *convergent to* (konvergent gegen) $a\in\mathbb{R}^n$, if for each neighborhood U of a there exists an $N_0\in\mathbb{N}$ with $a_j\in U$ for all $j\geq N_0$. In this case, we write $\lim_{j\to\infty}a_j=a$.

The following result says that a sequence in \mathbb{R}^n is convergent if an only if each of its coordinate sequences converges.

2.11 Lemma. A sequence $(a_j)_{j\in\mathbb{N}}\subset\mathbb{R}^n$ converges to $a=(a_1,a_2,\cdots,a_n)\in\mathbb{R}^n$ if and only if

$$\lim_{j \to \infty} a_{l,j} = a_l, \qquad l = 1, \dots, n,$$

i.e. if and only if the l-th coordinate of a_i converges to a_l for all $l=1,\dots n$.

Proof. \Longrightarrow : By assumption, there exists to each $\varepsilon > 0$ an $N_0 \in \mathbb{N}$ with $||a_j - a|| = (\sum_{l=1}^{n} |a_{l,j} - a_l|^2)^{\frac{1}{2}} < \varepsilon$ for all $j \geq N_0$. Therefore $|a_{j,l} - a_l| \leq ||a_j - a|| < \varepsilon$ for all $l = 1, \ldots, n, j \geq N_0$.

 \Leftarrow : For $\varepsilon > 0$ there exists an $N_l \in \mathbb{N}$ with $|a_{l,j} - a_l| < \frac{\varepsilon}{\sqrt{n}}$ for all $j \geq N_l$. Thus, for $j \geq N_0 := \max(N_1, \dots, N_n)$

$$||a_j - a|| = (\sum_{l=1}^n |a_{l,j} - a_l|^2)^{\frac{1}{2}} < (\frac{\varepsilon^2}{n}n)^{\frac{1}{2}} = \varepsilon.$$

2.12 Definition. A sequence $(a_j)_j \subset \mathbb{R}^n$ is called a *Cauchy sequence (Cauchyfolge)*, if for all $\varepsilon > 0$ there exists an $N_0 \in \mathbb{N}$ with

$$||a_n - a_m|| < \varepsilon, \quad n, m \ge N.$$

The following theorem about the convergence of Cauchy sequences in \mathbb{R}^n again relies ultimately on the the completeness of the real numbers.

2.13 Theorem. In \mathbb{R}^n every Cauchy sequence is convergent.

Proof. Let $(a_j)_j \subset \mathbb{R}^n$ with $a_j = (a_{1,j}, a_{2,j}, \cdots a_{n,j}), j \in \mathbb{N}$, be a Cauchy sequence in \mathbb{R}^n . Since

$$|a_{\nu,\ell} - a_{\nu,m}| \le \left(\sum_{\nu=1}^n |a_{\nu,\ell} - a_{\nu,m}|^2\right)^{\frac{1}{2}}, \qquad \nu = 1, \dots, n$$

every coordinate $(a_{\nu,j})_{j\geq 1}$ of $(a_j)_j$ is a Cauchy sequence in \mathbb{R} . Because \mathbb{R} is complete, $(a_{\nu,j})_{j\geq 1}$ converges for each $\nu=1,\cdots,n$. Lemma 2.11 now implies the assertion.

The following theorem describes closedness of a set in terms of convergent sequences.

2.14 Theorem. (Characterization of closed sets via sequences) Let $A \subset \mathbb{R}^n$. Then A is closed if and only if for every sequence $(a_j)_j \subset A$ with $\lim_{j\to\infty} a_j = a \in \mathbb{R}^n$ it holds that $a \in A$.

Proof. \Longrightarrow : Let $a_j \in A$ for all $j \in \mathbb{N}$ with $\lim_{j \to \infty} a_j = a \in \mathbb{R}^n$. We assume that $a \notin A$, i.e. that $a \in \mathbb{R}^n \backslash A$. Because $A^c := \mathbb{R}^n \backslash A$ is open, A^c is a neighborhood of a. By the definition of convergence (see 2.10) there exists an $N_0 \in \mathbb{N}$ with $a_j \in A^c$ for all $j \geq N_0$. Contradiction!

 \Leftarrow : We again assume that the assertion is false, i.e. that A^c is not open. Then there exists an $a \in \mathbb{R}^n \backslash A$ such that for all $\varepsilon > 0$ the neighborhood $U_{\varepsilon}(a)$ is not contained in $\mathbb{R}^n \backslash A$, i.e. $U_{\varepsilon}(a) \cap A \neq \emptyset$. For $j \in \mathbb{N}$ now choose $a_j \in U_{\frac{1}{j}}(a) \cap A$. Then $\lim_{j \to \infty} a_j = a \notin A$. Contradiction!

For a set $M \subset \mathbb{R}^n$ we define its diameter diam M as

$$\mathrm{diam}\ M:=\sup\{\|x-y\|:x,y\in M\}.$$

Then we have the following theorem.

2.15 Theorem. Let $(A_j)_{j\geq 0}$ be a sequence of non-empty, closed subsets of \mathbb{R}^n with

$$A_0 \supset A_1 \supset A_2 \supset \cdots$$

and $\lim_{j\to\infty}$ diam $(A_j)=0$. Then there exists exactly one $x\in\mathbb{R}^n$ with $x\in\bigcap_{j=0}^\infty A_j$.

Proof. We begin with the existence of an element x with the desired properties. Here, choose for each $j \in \mathbb{N}$ an $x_j \in A_j$. Then for given $\varepsilon > 0$ there exists an $N \in \mathbb{N}$ with

$$||x_j - x_k|| \le \text{diam } (A_N) < \varepsilon, \qquad j, k \ge N.$$

Therefore, $(x_j)_j$ is a Cauchy sequence in \mathbb{R}^n and Theorem 2.13 implies that $(x_j)_j$ converges to some $x \in \mathbb{R}^n$. Because $x_j \in A_k$ for $j \geq k$ and A_k is closed, it follows from Theorem 2.14 that $x \in A_k$ for all $k \in \mathbb{N}$. The uniqueness is clear.

Finally, we extend the definition of continuity of real functions of one varible to those of n real variables.

2.16 Definition. Let $M \subset \mathbb{R}^n$ and $f: M \to \mathbb{R}$ be a function. Then f is called continuous (stetig) at $x_0 \in M$, if for every sequence $(x_j)_j \subset M$ with $\lim_{j\to\infty} x_j = x_0$, there holds that $\lim_{j\to\infty} f(x_j) = f(x_0)$. If f is continuous for all $x_0 \in M$, then f is called continuous.

Analogously to Theorem 1.2 one shows: $f: M \to \mathbb{R}$ is continuous at $x_0 \in M$ if to each $\varepsilon > 0$ there exists a $\delta > 0$ (which depends upon ε and x_0) such that

$$|f(x) - f(x_0)| < \varepsilon$$
 for all $x \in M$, $||x - x_0|| < \delta$.

If $f: \mathbb{R}^n \to \mathbb{R}$ we can thus reformulate its continuity property at $x_0 \in \mathbb{R}^n$ in the form: $f: \mathbb{R}^n \to \mathbb{R}$ is continuous at $x_0 \in \mathbb{R}^n$ if and only if for every neighborhood V of $f(x_0)$ in \mathbb{R} (in particular for $V_{\varepsilon}(f(x_0) \subset \mathbb{R})$ there exists a neighborhood U of $x_0 \in \mathbb{R}^n$ (in particular $U_{\delta}(x_0) \subset \mathbb{R}^n$) with $f(U) \subset V$.

For the following theorem, which is a fundamental characterization of continuous functions, we need the notion of a *pre-image*. Let $f: \mathbb{R}^n \to \mathbb{R}$ and $B \subset \mathbb{R}$. Then

$$f^{-1}(B) := \{ x \in \mathbb{R}^n : f(x) \in B \}$$

is called pre-image of B w.r.t. f or inverse image of B under the function f.

- **2.17 Theorem.** For a function $f: \mathbb{R}^n \to \mathbb{R}$ the following are equivalent:
 - i) f is continuous.
 - ii) $f^{-1}(O)$ is open in \mathbb{R}^n for every open set O in \mathbb{R} , i.e. pre-images of open sets are open.
 - iii) $f^{-1}(A)$ is closed in \mathbb{R}^n for every closed set A in \mathbb{R} , i.e. pre-images of closed sets are closed.

Proof. i) \Rightarrow ii): Let $O \subset \mathbb{R}$ be open. If $f^{-1}(O) = \emptyset$, then the assertion follows from Theorem 2.5 a). Let $f^{-1}(O) \neq \emptyset$. Because f is continuous, there exists to each $x \in f^{-1}(O)$ an open neighborhood $U_x \subset \mathbb{R}^n$ of x with $f(U_x) \subset O$, i.e. $x \in U_x \subset f^{-1}(O)$ for all $x \in f^{-1}(O)$. Therefore

$$\bigcup_{x \in f^{-1}(O)} U_x = f^{-1}(O),$$

and then, by Theorem 2.5, $f^{-1}(O)$ is open as a union of open sets.

- ii) \Leftrightarrow iii): $A \subset \mathbb{R}$ is closed if and only if A^c is open in \mathbb{R} . Since $f^{-1}(A^c) = (f^{-1}(A))^c$ we have $f^{-1}(A)$ is closed if and only if $(f^{-1}(A))^c$ is open in \mathbb{R}^n .
- ii) \Rightarrow i): Let $x \in \mathbb{R}^n$ and V be an open neighborhood of f(x) in \mathbb{R} . By the definition

of an open neighborhood, there exists an $\varepsilon > 0$ such that $V_{\varepsilon}(f(x)) \subset V$. Then by assumption $U := f^{-1}(V_{\varepsilon}(f(x)))$ is open in \mathbb{R}^n . Since $x \in U$ there exists some $\delta > 0$ such that $U_{\delta}(x) \subset U$, i.e., $f(U_{\delta}(x)) \subset V_{\varepsilon}(f(x))$ and f is continuous at $x \in \mathbb{R}^n$.

Before we now consider examples with the aim to exemplify the statement of the above theorem, we remark that Theorem 2.17 implies that a function $f: \mathbb{R}^n \to \mathbb{R}$ is continuous iff inverse images of open sets are open, or alternatively iff inverse images of closed sets are closed.

2.18 Examples.

- a) Let $f: \mathbb{R}^n \to \mathbb{R}$ be a continuous function and $y \in \mathbb{R}$. Then $f^{-1}(y)$ is closed in \mathbb{R}^n . This is obvious, since $\{y\}$ is closed in \mathbb{R} .
- b) Let $f: \mathbb{R}^n \to \mathbb{R}$ be a continuous function. Then

$$\{x \in \mathbb{R}^n : f(x) \le r\}$$
 is closed and $\{x \in \mathbb{R}^n : f(x) < r\}$ is open.

This is clear, since $\{x \in \mathbb{R}^n : f(x) \le r\} = f^{-1}((-\infty, r])$ and $(-\infty, r]$ is closed, resp. $\{x \in \mathbb{R}^n : f(x) < r\} = f^{-1}((-\infty, r))$ and $(-\infty, r)$ is open.

c) The closed n-dimensional unit cube

$$Q := \{ x \in \mathbb{R}^n : 0 \le x_i \le 1, 1 \le j \le n \}$$

is closed in \mathbb{R}^n . In fact, the projection $p_j: \mathbb{R}^n \to \mathbb{R}, (x_1 \cdots x_n) \mapsto x_j$ on the j-th coordinate is continuous. Because

$$Q = \bigcap_{j=1}^{n} (\underbrace{\{x \in \mathbb{R}^n : p_j(x) \le 1\}}_{\text{closed by (iii)}} \cap \underbrace{\{x \in \mathbb{R}^n : p_j(x) \ge 0\}}_{\text{closed by (iii)}})$$

and finite intersections of closed sets are closed (Satz 2.5), the assertion follows from Theorem 2.17.

68CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

d) Continuous images of open sets are, in general, *not* open:

Consider the interval O = (-1, 1) and the continuous function $f : \mathbb{R} \to \mathbb{R}$, $x \mapsto x^2$. Then f(O) = [0, 1) which is not open in \mathbb{R} .

Continuous images of closed sets are, in general, not closed:

Consider the set $A := \{(x,y) \in \mathbb{R}^2 : xy = 1\} \subset \mathbb{R}^2$ and the continuous function $f : \mathbb{R}^2 \to \mathbb{R}, (x,y) \mapsto xy$. Then $A = f^{-1}(\{1\})$ and by statment (iii) A is closed in \mathbb{R}^2 . Now $p_1 : \mathbb{R}^2 \to \mathbb{R}, (x,y) \mapsto x$ is continuous, but $p_1(A) = \mathbb{R} \setminus \{0\}$ is not closed.

3. COMPACTNESS 69

3 Compactness

The notion of compactness is of central importance in analysis. In particular, important existence statements of analysis depend on properties of continuous functions on compact sets. Exemplary, we mention the fact that a real-valued function on a compact set attains a minimum and a maximum value.

We define the concept of compactness of a subset of \mathbb{R}^n by means of open covers and we show that this definition is equivalent to the later introduced 'compactness by sequences'. Furthermore, the Theorem of Heine-Borel states that a subset of \mathbb{R}^n is compact iff it is closed and bounded.

The reason to introduce compactness via open covers is that this concept can be straightforwardly generalized to normed and metric spaces to be defined in Analysis II, while the characterisation of Heine-Borel only works in finite dimensions.

In this section, K is always a compact subset of \mathbb{R}^n . We start with the definitions of 'open cover' and compactness.

3.1 Definition.

a) Let I be an index set. Then $(O_i)_{i \in I}$ is called an open cover (offene Überdeckung) of K, if O_i are open sets for all $i \in I$ and

$$K \subset \bigcup_{i \in I} O_i$$
.

b) The set $K \subset \mathbb{R}^n$ is called *compact (kompakt)*, if *every* open cover $(O_i)_{i \in I}$ of K contains a finite subcover, i.e. if there exist i_1, \dots, i_N with

$$K \subset \bigcup_{l=1}^N O_{i_l}$$
.

3.2 Examples.

- a) The set of real numbers \mathbb{R} is not compact, because $\mathbb{R} \subseteq \bigcup_{n \in \mathbb{N}} (-n, n)$.
- b) The interval (0,1] is not compact in \mathbb{R} , because $(0,1] \subseteq \bigcup_{j>1} (\frac{1}{j},2)$.
- c) Let (a_j) be a convergent sequence in \mathbb{R}^n with $\lim_{j\to\infty} a_j = a$. Then

$$K := \{a_j, j \in \mathbb{N}\} \cup \{a\}$$

is compact. To see this, let $(O_i)_{i\in I}$ be an open cover of K. Then there exists $j\in I$ with $a\in O_j$. Since O_j is a neighborhood of a, there exists $N_0\in\mathbb{N}$ with $x_n\in O_j$ for all $n\geq N_0$. Choose now i_0,\dots,i_{N_0} such that $x_n\in O_{i_n}, n=1\dots N_0$. Then

$$K \subset (\bigcup_{n=0}^{N_0} O_{i_n}) \cup O_j.$$

70CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

d) The statement of c) does not hold in general, if we remove a from \mathbb{K} . To realize this, consider the sequence $(1/n)_n$ and let

$$M = \{\frac{1}{j} : j \in \mathbb{N}\} \subset \mathbb{R},$$

$$O_1 = (\frac{1}{2}, 2), \text{ and}$$

$$O_j = (\frac{1}{j+1}, \frac{1}{j-1}) \text{ for } j \ge 2.$$

Then we have

$$M \subset \bigcup_{j \ge 1} O_j$$

and each O_j contains exactly one element of M. Therefore, the open cover $(O_j)_{j\in\mathbb{N}}$ does not contain a finite subcover.

3.3 Theorem. Let $K \subset \mathbb{R}^n$ be a compact set. Then K is closed and bounded.

Proof. First we show that K is bounded: Let $x \in \mathbb{R}^n$ be arbitrary, then fixed. Then $\mathbb{R}^n = \bigcup_{k=1}^{\infty} B_k(x)$ and since K is assumed to be compact, there exists $N \in \mathbb{N}$ with

$$K \subset \bigcup_{j=1}^{N} B_{k_j}(x).$$

For $R := \max\{k_1, \dots, k_N\}$, we have $K \subset B_R(x)$, therefore, K is bounded.

Next we show that K is closed or, equivalently, that $\mathbb{R}^n \setminus K$ is open: To this end consider $x \in \mathbb{R}^n \setminus K$ and set $U_n := \{y \in \mathbb{R}^n : ||y - x|| > \frac{1}{n}\}$. Then U_n is open and

$$K \subset \mathbb{R}^n \backslash \{x\} = \bigcup_{n=1}^{\infty} U_n.$$

Since K is compact, there exists $N \in \mathbb{N}$ with $K \subset \bigcup_{j=1}^{N} U_{n_j}$. For $R := \max\{n_1, \dots, n_N\}$, we have $B_{\frac{1}{R}}(x) \subset \mathbb{R}^n \backslash K$, i.e. $\mathbb{R}^n \backslash K$ is open, and therefore K is closed.

3.4 Lemma. Let $A \subset K \subset \mathbb{R}^n$, where A is closed and K is compact. Then A is compact.

3. COMPACTNESS 71

Proof. Let $(O_i)_{i\in I}$ be an open cover of A. By assumption $\mathbb{R}^n\setminus A$ is open and

$$K \subset \mathbb{R}^n = \bigcup_{i \in I} O_i \cup \mathbb{R}^n \backslash A.$$

Since K is compact, there exists a finite subcover of K, i.e., there exist $i_1, \dots, i_N \in I$ with

$$K \subset (O_{i_1} \cup \cdots \cup O_{i_N}) \cup \mathbb{R}^n \backslash A.$$

Therefore $A \subset O_{i_1} \cup \cdots O_{i_N}$.

3.5 Theorem. (Heine-Borel)

A set $K \subset \mathbb{R}^n$ is compact if and only if K is closed and bounded.

Proof. \Longrightarrow : This is Theorem 3.3.

 $\stackrel{\longleftarrow}{}$: Conversely, let K be closed and bounded. Then K is contained in a cuboid of the form:

$$Q = \{(x_1, \dots, x_n) \in \mathbb{R}^n : a_l \le x_l \le b_l, \ l = 1, \dots, n\}$$

with $a_l, b_l \in \mathbb{R}, a_l \leq b_l$. If we can show that Q is compact, the assertion follows from Lemma 3.4. This, however, is exactly the statement of the following lemma.

3.6 Lemma. Let $Q \subset \mathbb{R}^n$ be as above. Then Q is compact.

Proof. Let $(O_i)_{i \in I}$ be an open cover of Q. We assume that there does not exist an open subcover of Q. Now we construct a sequence of closed sub-cuboids

$$Q_0 \supset Q_1 \supset Q_2 \supset \dots$$

with the properties

- i) each Q_m has no finite subcover
- ii) diam $(Q_m) = 2^{-m}$ diam (Q)

by the following procedure: Set $Q_0 = Q$ and assume Q_m is already constructed. Then $Q_m = I_1 \times I_2 \times \cdots \times I_n$ where $I_l \subset \mathbb{R}$ are closed intervals. Now halve I_l , $I_l = I_l^1 \cup I_l^2$ and set

$$Q_m^{s_1,\dots,s_n} := I_1^{s_1} \times I_2^{s_2} \times \dots \times I_n^{s_n}, \quad s_i = 1, 2.$$

Then

$$Q_m = \bigcup_{s_1, \dots, s_n} Q_m^{s_1, \dots, s_n}.$$

Since Q_m does not have a finite subcover and is represented by a finite union of sub-

cuboids, there must exist at least one sub-cuboid $Q_m^{s_1\cdots s_n}$ which has not a finite subcover. We denote this by Q_{m+1} . Then

$$\operatorname{diam}(Q_{m+1}) = \frac{1}{2}\operatorname{diam}(Q_m) = 2^{-m-1}\operatorname{diam}(Q)$$

and therefore Q_{m+1} has properties i) and ii). By Theorem 2.15 there exists exactly one a with $a \in \bigcap_{m \ge 1} Q_m$. Additionally, since $(O_i)_{i \in I}$ is a cover of Q, a is an element of O_{i_0}

for some i_0 . Since O_{i_0} is open there exists some $\varepsilon > 0$ such that $B_{\varepsilon}(a) \subset O_{i_0}$. Choose now m so big that diam $Q_m < \frac{\varepsilon}{2}$. Since $a \in Q_m$, we have

$$Q_m \subset B_{\varepsilon}(a) \subset O_{i_0}$$

in contradiction to property i).

The notion of compactness, in particular the Theorem of Heine-Borel, has many important consequences in analysis. First of all, we consider basic properties of continuous images of compact sets.

3.7 Theorem. Let $f: D \subset \mathbb{R}^n \to \mathbb{R}$ be a continuous map. If $K \subset D$ is compact, then $f(K) \subset \mathbb{R}$ is also compact. In other words: Continuous images of compact sets are compact.

Proof. Let $(O_i)_{i\in I}$ be an open cover of f(K). For any point $x \in K$ we have $f(x) \in O_{i_0}$ for some $i_0 \in I$. Since O_{i_0} is open, there exists an open interval $B_{\varepsilon}^{\mathbb{R}}(f(x)) \subset O_{i_0}$, where $B_{\varepsilon}^{\mathbb{R}}(f(x)) := \{s \in \mathbb{R} : |s - f(x)| < \varepsilon\}$, for some $\varepsilon = \varepsilon(f(x)) > 0$. By the continuity of f there exists some $\delta = \delta(\varepsilon, x) > 0$ such that $f(B_{\delta}^{\mathbb{R}^n}(x) \cap D) \subset B_{\varepsilon}^{\mathbb{R}}(f(x))$; here $B_{\delta}^{\mathbb{R}^n}(x) := \{y \in \mathbb{R}^n : \|y - x\| < \delta\}$. Clearly, $K \subset \bigcup_{x \in K} B_{\delta}^{\mathbb{R}^n}(x)$. Since K is compact, there are finitely many x_j such that $K \subset \bigcup_{j=1}^N B_{\delta_j}^{\mathbb{R}^n}(x_j)$ and $f(B_{\delta_j}^{\mathbb{R}^n}(x_j) \cap D) \subset B_{\varepsilon_j}^{\mathbb{R}}(f(x_j)) \subset O_{i_j}$. Hence $f(K) \subset \bigcup_{j=1}^N O_{i_j}$.

The following corollary is a direct consequence of Theorem 3.7 and Theorem 3.3.

3.8 Corollary. Let $f: D \subset \mathbb{R}^n \to \mathbb{R}$ be continuous and $K \subset D$ a compact set. Then f(K) is bounded, i.e. there exists M > 0 with $|f(x)| \leq M$ for all $x \in K$.

In fact, f(K) is compact by the above Theorem 3.7 and Theorem 3.3 implies that f(K) is bounded.

3.9 Theorem. (Minimum and Maximum). Let $f: K \subset \mathbb{R}^n \to \mathbb{R}$ be a continuous function and K compact. Then the function f has a maximum and a minimum, i.e. there exist $x_0, x_1 \in K$ with

$$f(x_0) = \min_{x \in K} f(x)$$
 and $f(x_1) = \max_{x \in K} f(x)$.

3. COMPACTNESS 73

The proof is as follows: By Theorem 3.7 f(K) is compact and, therefore, by Theorem 3.3 closed and bounded. Thus

$$m := \inf f(K) > -\infty$$
 and $M := \sup f(K) < \infty$.

Then there exist sequences $(y_j)_j$, $(z_j)_j \subset f(K)$ with $y_j \to m$ and $z_j \to M$. Since f(K) is closed, it follows from Theorem 2.14 that m and M are in f(K). Therefore, there exist $x_0, x_1 \in K$ with $f(x_0) = m$ and $f(x_1) = M$.

The above theorem implies that a closed set and a compact set whose intersection is empty always have a strictly positive distance.

Here the distance between two sets is defined as follows:

Let $M_1, M_2 \subset \mathbb{R}^n$ and $x \in \mathbb{R}^n$. Then

$$d(x, M_1) := \inf\{||x - y|| : y \in M_1\}$$

is called the distance (Abstand) of x from M_1 and

$$d(M_1, M_2) := \inf\{||x - y|| : x \in M_1, y \in M_2\}$$

is the distance between the two sets M_1 and M_2 .

3.10 Corollary.

Let $A \subset \mathbb{R}^n$ be closed and $K \subset \mathbb{R}^n$ a compact set with $A \cap K = \emptyset$. Then d(A, K) > 0.

Proof. The function $d(\cdot, A) : \mathbb{R}^n \to \mathbb{R}$, $x \mapsto d(x, A)$ is continuous (Exercise) and K is compact by assumption. By Theorem 3.9 there exists an $x_0 \in K$ with $d(x_0, A) = d(K, A)$. If we had $d(x_0, A) = 0$, there would exist a sequence $(a_j)_j \subset A$ with $a_j \to x_0$. A being closed implies that $x_0 \in A$, i.e., $x_0 \in A \cap K$ in contradiction to $A \cap K = \emptyset$.

3.11 Theorem. (Sequential compactness) For a set $K \subset \mathbb{R}^n$ the following statements are equivalent:

- i) K is compact. (cover compactness)
- ii) Every sequence in K has a subsequence that converges to an element $a \in K$. (sequential compactness)

Proof. (i) \Longrightarrow (ii): We assume that the assertion is false. Then there exists a sequence $(a_n)_{n\in\mathbb{N}}\in K$ that does not have any convergent subsequence with limit in K. Therefore, for every $x\in K$ there exists a neighborhood U_x of x that contains only finitely many

terms of the sequence. Since clearly $K \subset \bigcup_{x \in K} U_x$ and K is compact, there exists a finite subcover of K. Then K contains only finitely many terms of the sequence. Contradiction!

 $(\mathbf{ii}) \Longrightarrow (\mathbf{i})$: By assumption K is bounded, because otherwise, there would exist a sequence $(a_j)_j \subset K$ with $|a_j| \geq j$ for all $j \in \mathbb{N}$, which would then, however, contain no convergent subsequences.

By the Theorem of Heine-Borel we now only have to show that K is closed. Here, let $(a_j)_j \subset K$ be a sequence with $\lim_{j\to\infty} a_j = a \in \mathbb{R}^n$. By assumption, there exists a subsequence $(a_{j_l})_{l\in\mathbb{N}}$ with $\lim_{l\to\infty} a_{j_l} = a' \in K$. From the uniqueness of the limit, it follows that a=a' and therefore $a\in K$. Theorem 2.14 implies that K is closed. By the above it is also bounded, therefore, by the Theorem of Heine-Borel K is compact.

We now consider the concept of uniform continuity of a function defined on a set $M \subset \mathbb{R}^n$. The continuity of the function $f: M \subset \mathbb{R}^n \to \mathbb{R}$ at a point $x_0 \in M$ means the following:

$$(\forall \varepsilon > 0) \ (\exists \delta = \delta(\varepsilon, x_0) > 0) \ (\forall x \in M, ||x - x_0|| < \delta) \ |f(x) - f(x_0)| < \varepsilon.$$

Here, δ depends on ε and ! x_0 . If we can choose δ independent of x_0 , then f is called uniformly continuous on M.

3.12 Definition. Let $f: M \subset \mathbb{R}^n \to \mathbb{R}$ be a function. Then f is called *uniformly continuous (gleichmässig stetig)*, if to each $\varepsilon > 0$ there exists a (universal) $\delta(\varepsilon) > 0$ with

$$x, y \in M, ||x - y|| < \delta \implies |f(x) - f(y)| < \varepsilon.$$

or in short notation

$$(\forall \varepsilon > 0) \ (\exists \delta > 0) \ (\forall x, y \in M, ||x - y|| < \delta) \ |f(x) - f(y)| < \varepsilon.$$

We easily verify that $f:(0,1)\to\mathbb{R},\,x\mapsto 1/x$, is continuous, but not uniformly continuous. However, $f:[0,\infty)\to[0,\infty),\,x\mapsto\sqrt{x}$, is uniformly continuous.

The following theorem says that a continuous function on a compact set is uniformly continuous.

3.13 Theorem.

Let $f: K \subset \mathbb{R}^n \to \mathbb{R}$ be a continuous function and K a compact set. Then f is uniformly continuous, i.e., continuous functions on compact sets are uniformly continuous.

3. COMPACTNESS 75

Proof. Let $\varepsilon > 0$. The continuity of f says that for all $y \in K$, there exists a radius r(y) > 0 with

$$|f(y) - f(z)| < \frac{\varepsilon}{2}$$
 if $z \in B_{r_y}(y) \cap K$.

Since $K \subseteq \bigcup_{y \in K} B_{\frac{r_y}{2}}(y)$ and K is compact, there exist finitely many y_1, \dots, y_n with

$$K \subseteq \bigcup_{j=1}^{N} B_{\frac{ry_i}{2}}(y_j).$$

Let $\delta := \frac{1}{2} \min(r(y_1), \dots, r(y_N))$ and $x, x' \in K$ with $||x - x'|| \le \delta$. Then there exists a $j \in \{1 \dots N\}$ with $x \in B_{\frac{r_{y_j}}{2}}(y_j)$ and $x' \in B_{r_{y_j}}(y_j)$ and

$$|f(x) - f(x')| \le \underbrace{|f(x) - f(y_j)|}_{<\frac{\varepsilon}{2}} + \underbrace{|f(y_j) - f(x')|}_{<\frac{\varepsilon}{2}} < \varepsilon.$$

The extension of a given continuous function $f: M \subset \mathbb{R}^n \to \mathbb{C}$ to a continuous function on \overline{M} is closely related to the concept of uniform continuity. More precisely, let $x_0 \in \mathbb{R}^n \backslash M$ be an accumulation point of M. We want to examine the question under which circumstances there exists a continuous extension of f to $M \cup \{x_0\}$.

At first, we introduce the concept of limit of a function (as opposed to sequence).

3.14 Definition. A function $f: M \subset \mathbb{R}^n \to \mathbb{C}$ has a limit a in the accumulation point x_0 of M, if for each sequence $(x_j)_j \subset M \setminus \{x_0\}$ with $x_j \to x_0$, we have

$$\lim_{j \to \infty} f(x_j) = a.$$

In this case, we also say that f(x) converges to a for $x_i \to x_0$, and we write

$$\lim_{x \to x_0} f(x) = a \quad \text{or} \quad f(x) \to a \quad \text{for} \quad x \to x_0.$$

If $x_0 \in M$ and f is continuous at x_0 , then the value of the function at x_0 is equal to the limit, i.e. we have $\lim_{x\to x_0} f(x) = f(x_0)$. Furthermore, we call the function

$$F: M \cup \{x_0\} \to \mathbb{R},$$
$$x \mapsto \begin{cases} f(x) & x \in M \\ y_0 & x = x_0 \end{cases}$$

a continuous extension if $\lim_{x\to x_0} f(x) = y_0$ exists.

For the special case $M \subset \mathbb{R}$, we furthermore define the *limit from the left* (links-seitiger Grenzwert) of f in x_0 to be y_0 , in symbols

$$\lim_{x \to x_0 - 0} f(x) := y_0 \quad \text{(or in short } \lim_{x \to x_0 -} f(x) := y_0),$$

76CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

if for all sequences $(x_j)_j \subset M \cap (-\infty, x_0)$ with $x_j \to x_0$, we have $\lim_{j\to\infty} f(x_j) = y_0$. Analogously, we call

$$\lim_{x \to x_0 + 0} f(x) := \lim_{x \to x_0 + 1} f(x) := y_0,$$

the limit from the right (rechtsseitiger Grenzwert) of f in x_0 , if for all sequences $(x_j)_j \subset M \cap (x_0, \infty)$ with $x_j \to x_0$, we have $\lim_{j \to \infty} f(x_j) = y_0$.

If $M \subset \mathbb{R}$ is not bounded from above and we are given a function $f: M \to \mathbb{C}$, we call $a \in \mathbb{C}$ the limit of f in ∞ , if for each $\varepsilon > 0$ there exists $N_0 \in \mathbb{N}$ such that

$$|f(x) - a| < \varepsilon$$
 for all $x \in M$ with $x > N_0$.

Analogously, one defines the limit in $-\infty$.

3.15 Examples.

a) Let $M = \mathbb{R} \setminus \{1\}$ and $f: M \to \mathbb{R}$ be defined by $f(x) = \frac{x^n - 1}{x - 1}$. Then

$$\lim_{x \to 1} f(x) = \lim_{x \to 1} \frac{x^n - 1}{x - 1} = n,$$

because $\frac{x^{n}-1}{x-1} = 1 + x + x^{2} + \cdots + x^{n-1}$.

b)

$$\lim_{z \to 0} \frac{e^z - 1}{z} = 1,$$

because

$$\frac{e^z - 1}{z} = \frac{z + \frac{z^2}{2!} + \frac{z^3}{3!} + \dots}{z} = 1 + \frac{z}{2!} + \frac{z^2}{3!} + \frac{z^3}{4!} + \dots$$

Therefore $\left|\frac{e^z-1}{z}-1\right| \leq \left|\frac{z}{2}\right|(1+|z|+|z^2|+\ldots) = \frac{|z|}{2(1-|z|)} \to 0$ for $z \to 0$ if |z| < 1. (geometric sum)

c) The limit

$$\lim_{x \to 0} \frac{x}{|x|}$$

does not exist: Define the function

$$f: \mathbb{R} \setminus \{0\} \to \mathbb{R}, \quad x \mapsto \left\{ \begin{array}{ll} 1 & : & x > 0 \\ -1 & : & x < 0 \end{array} \right.$$

Then the limit from the left $\lim_{x\to 0^-} = -1$ does not coincide with the limit from the right $\lim_{x\to 0^+} = 1$.

The following theorem characterizes when a function can be continuously extended in terms of uniform continuity.

3. COMPACTNESS 77

3.16 Theorem. Let $M \subset \mathbb{R}$ be a bounded set and $f: M \to \mathbb{R}$ be a function. Then the following are equivalent:

- i) There exists a unique continuous extension $F: \overline{M} \subset \mathbb{R} \to \mathbb{R}$ of f on \overline{M} , i.e. F(x) = f(x) for $x \in M$.
- ii) f is uniformly continuous.

Proof. (i) \Rightarrow (ii): Because \overline{M} is bounded and closed, it is compact by the Heine-Borel Theorem, and the claim follows from Theorem 3.13.

 $(ii) \Rightarrow (i)$: See the Exercises.

To conclude this section, we consider a function g (see below) constructed via the so-called 'saw tooth function' f, which is defined by

$$f: \mathbb{R} \to \mathbb{R}, \quad f(x) = \left| x - [x] - \frac{1}{2} \right|.$$

Clearly f is continuous on \mathbb{R} . Now define

$$g:(0,1] \to \mathbb{R}, \quad g(x) = f(\frac{1}{x}),$$

which as a composition of two continuous functions is continuous on (0,1]. But g is not uniformly continuous since

$$g(\frac{1}{n}) - g(\frac{1}{n+1/2}) = f(n) - f(n+1/2) = 1/2, \quad n \in \mathbb{N}.$$

Therefore, by the above theorem, we cannot extend g continuously to the closed interval [0,1]; in particular the limit $\lim_{x\to 0+} g(x)$ does not exist.

4 The exponential function and related functions

Central for this section is the *exponential function*, one of the most important functions of all mathematics. With its help, we will firstly introduce the trigonometric functions *sine* and *cosine*, and secondly we will examine the already known power and logarithm functions more closely.

Many of the following definitions and arguments can be traced back directly to LEONHARD EULER (1707-1783), one of the all-time greatest mathematicians. Born in Basel in 1707, he enrolled at the university of Basel at the age of 13 where he was a student of Johann Bernoulli. In 1727, he went to the Academy of St. Petersburg where he was appointed a professorship in 1733. During this time, the academies were the center of scientific research, and Euler spent his whole life at the academies of St. Petersburg and Berlin (1741-1766).

Euler was most influential in mathematics through his textbooks. His "Introductio in analysin infinitorum" of 1748 paved the way for analysis as a branch of mathematics on a par with geometry and algebra. Our contemporary mathematical notation is due to Euler in great parts.

Before we — following Euler — define sine and cosine as power series, we recall the *exponential series*, already known from Chapter II,

$$e^z = \exp z = \sum_{n=0}^{\infty} \frac{z^n}{n!} = 1 + z + \frac{z^2}{2} + \dots, \quad z \in \mathbb{C},$$

with infinite radius of convergence. The power series of sine and cosine, which we will examine thoroughly in the following, have a close relationship to the exponential series. Here it is essential to work with complex numbers. Only then the connection between the exponential and the trigonometric functions becomes fully apparent. Retrospectively, from considering the trigonometric functions, we will also gain new insights concerning the exponential function; e.g. that the exponential function is periodic with a complex period.

4.1 Definition. The sine series and cosine series are defined as

$$\sin z := \sum_{n=0}^{\infty} (-1)^n \frac{z^{2n+1}}{(2n+1)!} = z - \frac{z^3}{3!} + \frac{z^5}{5!} - \dots, \quad z \in \mathbb{C},$$

$$\cos z := \sum_{n=0}^{\infty} (-1)^n \frac{z^{2n}}{(2n)!} = 1 - \frac{z^2}{2!} + \frac{z^4}{4!} - \dots, \quad z \in \mathbb{C}.$$

These series have the following elementary properties:

4.2 Theorem. a) The sine and cosine series have an infinite radius of convergence.

b) Euler's formula

$$e^{iz} = \cos z + i \sin z, \quad z \in \mathbb{C}.$$

holds.

c) The functions $z \mapsto \sin z$ and $z \mapsto \cos z$ are continuous on \mathbb{C} .

The claim about the radius of convergence follows from the Cauchy-Hadamard formula II.5.2. Euler's formula is a direct consequence of the presentation

$$e^{iz} = \sum_{n=0}^{\infty} \frac{(iz)^n}{n!} = \sum_{n=0}^{\infty} \frac{(iz)^{2n}}{(2n)!} + \sum_{n=0}^{\infty} \frac{(iz)^{2n+1}}{(2n+1)!} = \cos z + i \sin z, \quad z \in \mathbb{C}.$$

The continuity of $z \mapsto \sin z$ and $z \mapsto \cos z$ follows from Theorem 1.7.

Further properties of sine and cosine can be deduced directly from the definition likewise.

4.3 Corollary. a) The cosine function $\cos : \mathbb{C} \to \mathbb{C}, z \mapsto \cos z$ is an even function, and the sine function $\sin : \mathbb{C} \to \mathbb{C}, z \mapsto \sin z$ is an odd function, , i.e. we have

$$\cos z = \cos(-z)$$
 and $\sin z = -\sin(-z)$, $z \in \mathbb{C}$.

b) For all $z \in \mathbb{C}$ we have

$$\cos z = \frac{e^{iz} + e^{-iz}}{2} \quad and \quad \sin z = \frac{e^{iz} - e^{-iz}}{2i}, \quad z \in \mathbb{C}.$$

- c) For $x \in \mathbb{R}$ we have $\cos x = Re(e^{ix})$ and $\sin x = Im(e^{ix})$.
- d) For all $x \in \mathbb{R}$ we have $|e^{ix}| = 1$.

The functional equation of the exponential function implies the addition theorems for the sine and cosine functions which express how we can rewrite these functions applied to sums of angles.

4.4 Theorem. (Angle sum and difference identities). The following equations hold for all $z, w \in \mathbb{C}$.

$$\cos(z \pm w) = \cos z \cos w \mp \sin z \sin w,$$

$$\sin(z \pm w) = \sin z \cos w \pm \cos z \sin w,$$

$$\sin z - \sin w = 2\cos(\frac{z+w}{2})\sin(\frac{z-w}{2}),$$

$$\cos z - \cos w = -2\sin(\frac{z+w}{2})\sin(\frac{z-w}{2}).$$

80CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

Proof. For all $z, w \in \mathbb{C}$, we have

$$\cos z \cos w - \sin z \sin w = \frac{1}{4} [(e^{iz} + e^{-iz})(e^{iw} + e^{-iw}) + (e^{iz} - e^{-iz})(e^{iw} - e^{-iw})]$$

$$= \frac{1}{4} [e^{i(z+w)} + e^{-i(z+w)} + e^{i(z+w)} + e^{-i(z+w)}]$$

$$= \frac{1}{2} [e^{i(z+w)} + e^{-i(z+w)}] = \cos(z+w).$$

by Corollary 4.3 b). The proof of the remaining identities is similar and left to the reader.

From the first of the above identities we infer (take z = w)

$$\cos^2 z + \sin^2 z \stackrel{4.4}{=} \cos(z - z) = \cos 0 = 1, \quad z \in \mathbb{C}.$$

We write down this important relation explicitly in the following corollary.

4.5 Corollary. For all $z \in \mathbb{C}$ we have

$$\cos^2 z + \sin^2 z = 1.$$

In the following we examine the exponential function specifically for real arguments. The proof of the following properties is left to the reader as an exercise.

4.6 Theorem. The following statements hold:

- a) $e^x < 1$ if x < 0 and $e^x > 1$ if x > 0.
- b) The function $\exp : \mathbb{R} \to \mathbb{R}_+$ is strictly monotone increasing.
- c) For each (fixed) $\alpha \in \mathbb{R}$ we have

$$\lim_{x \to \infty} \frac{e^x}{x^\alpha} = \infty;$$

in other words, the exponential function grows faster for $x \to \infty$ than every power x^{α} .

d) For every $\alpha \in \mathbb{R}$ we have

$$\lim_{x \to \infty} x^{\alpha} e^{-x} = \lim_{x \to \infty} \frac{x^{\alpha}}{e^x} = 0;$$

in other words, e^{-x} decreases faster than every power x^{α} .

Since the exponential function $\exp : \mathbb{R} \to (0, \infty)$ is continuous, surjective, and strictly monotone increasing, by III.1, there exists an inverse function

$$\log:(0,\infty)\to\mathbb{R}$$

of the exponential function. As in Chapter II, this function will be called *logarithm* function. In particular, we have

$$\log 1 = 0$$
 and $\log e = 1$.

Furthermore, the logarithm function has the properties

$$\log(xy) = \log x + \log y, \quad x, y \in (0, \infty)$$
$$\log(\frac{x}{y}) = \log x - \log y, \quad x, y \in (0, \infty).$$

This follows directly from the functional equation of the exponential function, because if we let $a := \log x$ and $b := \log y$, we have $x = e^a$ and $y = e^b$ and it follows that $xy = e^a \cdot e^b = e^{a+b}$; hence $\log(xy) = \log x + \log y$.

The exponential function also allows to define general powers a^z for a>0 and $z\in\mathbb{C}$ in accordance with the previous definition of powers, compare Example 1.14 c). If we define

$$a^z := e^{z \log a}, \quad z \in \mathbb{C}, a > 0,$$

then we have the following calculation rules for $z,w\in\mathbb{C}$ and a,b>0:

$$a^z a^w = a^{z+w}, \quad a^w b^w = (ab)^w, \qquad z, w \in \mathbb{C},$$

$$\log(a^x) = x \log a, \quad (a^x)^y = a^{xy}, \qquad x, y \in \mathbb{R}.$$

To prove the first rule observe $a^z a^w = e^{z \log a} e^{w \log a} = e^{(z+w) \log a} = a^{(z+w)}$. The others follow analogously.

We also verify that for each $\alpha > 0$ there holds

$$\lim_{x \to \infty} \frac{\log x}{x^{\alpha}} = 0 \quad \text{and} \quad \lim_{x \to 0+} x^{\alpha} \log x = 0$$

In other words, the logarithm function grows slower than any (positive) power x^{α} for $x \to \infty$, and its singularity at the origin is controlled by any (tiny) positive x-power.

Let us now discuss the sine and cosine functions for real arguments; in particular, we are interested in their roots.

4.7 Lemma. For $x \in (0, 2]$ we have:

$$x - \frac{x^3}{6} < \sin x < x$$
 and $1 - \frac{x^2}{2} < \cos x < 1 - \frac{x^2}{2} + \frac{x^4}{24}$.

In particular, $\sin x > 0$ for $x \in (0, 2]$.

82CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

Proof. For $x \in (0,2]$ we have

$$\sin x = x - \frac{x^3}{3!} + \underbrace{\frac{x^5}{5!} - \frac{x^7}{7!}}_{>0} + \underbrace{\frac{x^9}{9!} - \frac{x^{11}}{11!}}_{>0} + \dots > x - \frac{x^3}{3!},$$

because

$$\frac{x^n}{n!} - \frac{x^{n+2}}{(n+2)!} = \frac{x^n[(n+1)(n+2) - x^2]}{(n+2)!} > 0.$$

On the other hand,

$$\sin x = x - \underbrace{\left(\frac{x^3}{3!} - \frac{x^5}{5!}\right)}_{>0} - \underbrace{\left(\frac{x^7}{7!} - \frac{x^9}{9!}\right)}_{>0} + \dots < x,$$

and this implies the proposition for the sine function. The estimate for cos is analogous.

We also note that the cosine is a strictly decreasing function on the interval [0,2]: For, if x > y, we have

$$\cos x - \cos y \stackrel{4.4}{=} -2 \underbrace{\sin(\frac{x+y}{2})}_{>0} \underbrace{\sin(\frac{x-y}{2})}_{>0} < 0, \quad x, y \in [0, 2].$$

We can now show that the cosine function has exactly one root in the interval [0,2].

4.8. Theorem and definition of the number π . The cosine function has exactly one root x_0 in the interval [0,2]. We define

$$\pi := 2x_0$$
.

Proof. We have cos(0) = 1 and the above Lemma 4.7 implies that

$$\cos(2) < 1 - \frac{2^2}{2} + \frac{2^4}{24} = -\frac{1}{3} < 0.$$

Because cos is continuous, the intermediate value theorem implies that cos has at least one root x_0 in [0,2]. The uniqueness follows from the strict monotonicity of cos in [0,2].

The term π became popular through the textbook of Euler that was mentioned above, and is possibly derived from the Greek word $\pi \varepsilon \varrho \iota \varphi \varepsilon \varrho \varepsilon \iota \alpha$ for circumference. If we try to compute π numerically, we obtain

 $\pi = 3.14159265358979323846...$

With the following mnemonic these digits of π can be reproduced, if one assigns to each single word the number of its letters:

"Sir, I send a rhyme excelling in sacred truth and rigid spelling numerical sprites elucidate for me the lexicon's dull weight"

4.9 Remark. A real number is called *algebraic* if it is a root of a non-trivial polynomial with integer coefficients. For example, every rational number p/q is algebraic as a root of the polynomial $x \mapsto qx - p$. Real numbers which are not algebraic are called transcendental. In particular, they are irrational.

Already in 1761, H. J. Lambert proved that π is irrational. The transcendence proof of π was given 1882 by F. Lindemann. This theorem also decided the more than 2000 years old and still famous problem of squaring the circle: it is *impossible* to give a ruler-and-compass construction of a square that has the same area as a given circle.

The above definition of the number π implies in particular that

$$\cos(\frac{\pi}{2}) = 0$$
 and $\sin(\frac{\pi}{2}) = 1$.

This identity holds because $\cos^2(\frac{\pi}{2}) + \sin^2(\frac{\pi}{2}) = 1$ implies firstly $\sin \frac{\pi}{2} = \pm 1$, and the positivity of the sine in (0,2] then yields $\sin \frac{\pi}{2} = 1$.

If we combine these formulas with Euler's formula of Theorem 4.2 b), we obtain $e^{i\pi/2} = \cos(\pi/2) + i\sin(\pi/2) = i$. More generally we have the following table of values of $\cos x$, $\sin x$ and e^{ix} :

x	0	$\frac{\pi}{2}$	π	$\frac{3}{2}\pi$
$\cos x$	1	0	-1	0
$\sin x$	0	1	0	-1
e^{ix}	1	i	-1	-i

If we combine the above function values with the functional equation of the exponential function, we can deduce the important *periodicity* of the exponential function.

4.10 Theorem. For all $z \in \mathbb{C}$ and $n \in \mathbb{Z}$ we have

$$e^{z+i\frac{n}{2}\pi} = e^z i^n$$
, and in particular $e^{z+2in\pi} = e^z$.

This means that the exponential function has the purely imaginary period $2\pi i$.

This result transferred to the trigonometric functions gives the following corollary.

4.11 Corollary. a) For $z \in \mathbb{C}$ we have

i)
$$\cos(z + \frac{\pi}{2}) = -\sin z$$
, $\cos(z + \pi) = -\cos z$, $\cos(z + 2\pi) = \cos z$,

84CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

ii)
$$\sin(z + \frac{\pi}{2}) = \cos z$$
, $\sin(z + \pi) = -\sin z$, $\sin(z + 2\pi) = \sin z$.

In particular, the functions sin and cos are periodic functions with real period 2π .

b) We have

$$\cos z = 0 \iff z = \frac{\pi}{2} + n\pi \text{ for an } n \in \mathbb{Z},$$

$$\sin z = 0 \iff z = n\pi \text{ for an } n \in \mathbb{Z},$$

$$e^{z} = 1 \iff z = 2ni\pi \text{ for an } n \in \mathbb{Z}.$$

We conclude our discussion of the trigonometric functions for the time being by introducing the tangent and cotangent functions. We define the *tangent* and the *cotangent* functions by

$$\tan : \mathbb{C} \setminus \{\pi/2 + n\pi : n \in \mathbb{Z}\} \to \mathbb{C}, \qquad z \mapsto \frac{\sin z}{\cos z},$$
$$\cot : \mathbb{C} \setminus \{n\pi : n \in \mathbb{Z}\} \to \mathbb{C}, \qquad z \mapsto \frac{\cos z}{\sin z}.$$

To conclude this section, we consider the inverse functions of the trigonometric and the hyperbolic functions. We begin with the following properties of sin, cos and tan.

- **4.12 Lemma.** a) The function $\cos : [0, \pi] \to [-1, 1]$ is continuous, surjective and strictly decreasing.
- b) The function $\sin: \left[-\frac{\pi}{2}, \frac{\pi}{2}\right] \to \left[-1, 1\right]$ is continuous, surjective and strictly increasing.
- c) The function $\tan:(-\frac{\pi}{2},\frac{\pi}{2})\to\mathbb{R}$ is continuous, surjective and strictly increasing.
- *Proof.* (a) Since $\cos 0 = 1$, $\cos \pi = -1$, and the cosine is continuous by Theorem 2.4, we have surjectivity on account of the intermediate value theorem. Furthermore, since the cosine is in particular strictly decreasing on $[0, \pi/2]$ and $\cos x = -\cos(\pi x)$ the cosine is also strictly decreasing on $[\pi/2, \pi]$, i.e., injectivity.
- (b) Since $\sin x = \cos(\pi/2 x)$ the assertions follow from (a).
- (c) Since sine is strictly increasing and cosine strictly decreasing on $[0, \pi/2)$ and $\tan(-x) = -\tan x$ the tangent is strictly increasing and continuous on $(-\pi/2, \pi/2)$. Also $\lim_{x\to\pi/2-}\tan x = \infty$ and, therefore, surjectivity follows.

The above lemma therefore implies that the inverse functions

$$\begin{aligned} & \arccos: & & [-1,1] \rightarrow [0,\pi] \\ & \arcsin: & & [-1,1] \rightarrow [-\frac{\pi}{2},\frac{\pi}{2}] \\ & \arctan: & & \mathbb{R} \rightarrow (-\frac{\pi}{2},\frac{\pi}{2}) \end{aligned}$$

of sin, cos, and tan, resp., exist on the respective intervals. These are called *inverse* trigonometric functions or cyclometric functions and they are all continuous by Theorem 1.13.

Our current state of knowledge now allows to treat the polar form of complex numbers. We have the following theorem.

4.13 Theorem. (Polar form of complex numbers). Every $z \in \mathbb{C} \setminus \{0\}$ has a representation of the form

$$z = re^{i\varphi}$$
.

where r = |z| and $\varphi \in \mathbb{R}$ is determined up to addition of an integer multiple of 2π .

In the above representation, r is called the *absolute value* (or *modulus*) and φ the argument (or angle) of the complex number z.

Proof. For $z \in \mathbb{C} \setminus \{0\}$ there exist $x, y \in \mathbb{R}$ with $\frac{z}{|z|} = x + iy$. Then we have $x^2 + y^2 = 1$ and therefore $x, y \in [-1, 1]$. Therefore, $\alpha := \arccos x$ is well defined. Now $x = \cos \alpha$ implies $\sin \alpha = \pm \sqrt{1 - x^2} = \pm y$. We set

$$\varphi := \left\{ \begin{array}{ll} \alpha & : & \sin \alpha = y \\ -\alpha & : & \sin \alpha = -y \end{array} \right. = \left\{ \begin{array}{ll} \arccos x, & y \geq 0, \\ -\arccos x, & y < 0, \end{array} \right.$$

In either case we have that φ is well defined and $\varphi \in [0, \pi]$ provided $y \geq 0$: By Lemma 4.7, we have $\sin \varphi \geq 0$ for all $\varphi \in [0, 2]$ and because $\sin \varphi = \sin(\pi - \varphi)$ (cf. 4.11 b)), we deduce $\sin \varphi \geq 0$ for all $\varphi \in [0, \pi]$. Furthermore, because $\sin^2 \varphi = 1 - \cos^2 \varphi = y^2$, it follows that $\sin \varphi = y$. Therefore we obtain

$$e^{i\varphi} = \cos \varphi + i \sin \varphi = x + iy = \frac{z}{|z|},$$

and thus $z = re^{i\varphi}$ for r = |z|. The case y < 0 is treated analogously.

4.14 Remarks. a) The polar form gives us a nice geometric way to visualize the product of complex numbers in the complex plane. For $z = |z|e^{i\varphi}$ and $w = |w|e^{i\psi}$, we have

$$z \cdot w = |zw|e^{i(\varphi + \psi)}.$$

b) Furthermore, for each $z \in \mathbb{C} \setminus \{0\}$ and each $n \in \mathbb{N}$, there exist exactly n different numbers $z_1, \ldots, z_n \in \mathbb{C}$ with $(z_k)^n = z$ for all $k = 1, \ldots, n$. These numbers are called n-th roots of z. In particular, for z = 1 there exist exactly n different roots of unity $\xi_1, \xi_2, \ldots, \xi_n$, i.e., complex numbers ξ_k with $\xi_k^n = 1$ for all $k = 1, \ldots, n$. The n-th roots of a complex number $z = re^{i\varphi}$ are given explicitly by

$$z_k := \sqrt[n]{r} \, \xi_k$$
 with $\xi_k = e^{i(\frac{\varphi + 2\pi k}{n})}$ for all $k = 1, \dots, n$.

86CHAPTER III. CONTINUOUS FUNCTIONS AND THE BASICS OF TOPOLOGY

In many concrete problems, the exponential function appears in the form $(e^z + e^{-z})/2$ or $(e^z - e^{-z})/2$. Based on this, we define the hyperbolic functions as follows:

$$\cosh z := \frac{1}{2}(e^z + e^{-z})$$
 hyperbolic cosine,
 $\sinh z := \frac{1}{2}(e^z - e^{-z})$ hyperbolic sine,
 $\tanh z := \frac{\sinh z}{\cosh z}$ hyperbolic tangent,
 $\coth z := \frac{\cosh z}{\sinh z}$ hyperbolic cotangent.

The relations

$$\cosh z = \cos iz$$
, $\sinh z = -i\sin iz$, $z \in \mathbb{C}$

and

$$\cosh^2 z - \sinh^2 z = 1, \quad z \in \mathbb{C}$$

are easily verified as well as their power series representation

$$\cosh z = \sum_{j=0}^\infty \frac{z^{2j}}{(2j)!}, \quad \text{ and } \quad \sinh z = \sum_{j=0}^\infty \frac{z^{2j+1}}{(2j+1)!}, \quad z \in \mathbb{C}.$$

Chapter IV

Differential Calculus in one Variable

1 Differentiable Functions

The differential and integral calculus, which dates back to Leibniz and Newton, builds the core of all basic lectures on analysis. In this section, we restrict our attention to the differential calculus of functions in one *real variable*, however we do admit that the functions may have *complex values*.

We begin with the problem to approximate a given function $f: D \subset \mathbb{R} \to \mathbb{K}$ at the point $x_0 \in D$ by an affine function. If we have $\mathbb{K} = \mathbb{R}$, we can interpret this geometrically as the problem to find the tangent line of the graph of f at the point $(x_0, f(x_0))$.

The basic idea to solve the above problem is to approximate the tangent lines by the lines through the points $(x_0, f(x_0))$ and $(x_0 + h, f(x_0 + h))$ for small h. The slope of these lines is given by $\frac{f(x_0+h)-f(x_0)}{h}$. This motivates the following definition.

1.1 Definition. Let $D \subset \mathbb{R}$ and assume that $x_0 \in D$ is an accumulation point of D. We call a function $f: D \to \mathbb{K}$ differentiable (differentiable) at $x_0 \in D$, if the limit

$$\lim_{\substack{x \to x_0 \\ x \in D \setminus \{x_0\}}} \frac{f(x) - f(x_0)}{x - x_0} = \lim_{\substack{h \to 0, h \neq 0 \\ x_0 + h \in D}} \frac{f(x_0 + h) - f(x_0)}{h}$$

exists. This limit is called derivative (Ableitung) of f at x_0 and is denoted by $f'(x_0)$ or $\frac{df}{dx}(x_0)$. If f is differentiable at every $x \in D$, we say that f is differentiable on D and we call the function $f': D \to \mathbb{K}$, $x \mapsto f'(x)$ the derivative of f.

1.2 Examples. a) The function $f: \mathbb{R} \to \mathbb{R}, f(x) = x^n$ is differentiable for each $n \in \mathbb{N}$ and one has $f'(x) = nx^{n-1}$ for all $x \in \mathbb{R}$. Just observe that

$$\frac{x^n - x_0^n}{x - x_0} = x_0^{n-1} + xx_0^{n-2} + x^2x_0^{n-3} + \ldots + x^{n-1} \xrightarrow{x \to x_0} x_0^{n-1} + x_0^{n-1} + \ldots + x_0^{n-1} = nx_0^{n-1}.$$

b) The function $f: \mathbb{R} \to \mathbb{C}$, $f(x) = e^{\alpha x}$ is differentiable for all $\alpha \in \mathbb{C}$ and we have $f'(x) = \alpha e^{\alpha x}$, because we have

$$\frac{e^{\alpha(x_0+h)} - e^{\alpha x_0}}{h} = e^{\alpha x_0} \left(\frac{e^{\alpha h} - 1}{h}\right) \xrightarrow{h \to 0} \alpha e^{\alpha x_0},$$

in analogy to Example 3.15 b).

In the following theorem, we give an equivalent reformulation of the concept of differentiability. For this, we require that $x_0 \in D$ is an accumulation point of D.

- **1.3 Theorem.** Let $f: D \subset \mathbb{R} \to \mathbb{K}$ be a map and $x_0 \in D$ an accumulation point. The following statements are equivalent.
 - i) The function f is differentiable at x_0 .
 - ii) There exists a function $\varphi: D \to \mathbb{K}$ which is continuous at x_0 , such that

$$f(x) = f(x_0) + (x - x_0)\varphi(x), \quad x \in D.$$

In this case, we have $f'(x_0) = \varphi(x_0)$.

iii) There exists a linear mapping $L: \mathbb{R} \to \mathbb{K}$ such that

$$\lim_{h \to 0} \frac{f(x_0 + h) - f(x_0) - Lh}{h} = 0.$$

In this case, we have $f'(x_0)h = Lh$ for all $h \in \mathbb{R}$.

Proof. $i) \Longrightarrow ii$: By assumption, the function $x \mapsto \frac{f(x) - f(x_0)}{x - x_0}$ for $x \in D \setminus \{x_0\}$ has an extension φ which is continuous at x_0 . In x_0 we then have $\varphi(x_0) = f'(x_0)$.

- $ii) \Longrightarrow iii)$: The linear mapping $Lh := \varphi(x_0)h = f'(x_0)h$ has the properties which are required in statement iii).
- $iii) \Longrightarrow i$): Let L be a linear mapping for which statement iii) holds. If we have $Lh = \alpha h, h \in \mathbb{R}$, for some $\alpha \in \mathbb{C}$, it follows that

$$\lim_{h \to 0} \frac{f(x_0 + h) - f(x_0)}{h} - \alpha = \lim_{h \to 0} \frac{f(x_0 + h) - f(x_0) - \alpha h}{h} = 0;$$

This means that f is differentiable in x_0 and we have $f'(x_0) = \alpha$.

89

The statement iii) of the above theorem says that for a differentiable function f the increment $f(x_0 + h) - f(x_0)$ is approximated so well by Lh, that the difference $f(x_0 + h) - f(x_0) - Lh$ tends to 0 faster for $h \to 0$ than h itself. This formulation aims at approximating functions locally by linear functions and will be further extended later by the theorem of Taylor (Taylor formula). Also, this formulation is the starting point for the generalization of the notion of differentiability to functions of several variables.

In particular, Theorem 1.3 immediately implies that a function, differentiable at x_0 , is continuous at this point.

1.4 Corollary. A function $f: D \to \mathbb{K}$, which is differentiable in $x_0 \in D \subset \mathbb{R}$, is also continuous at x_0 .

We note that the converse of Corollary 1.4 does *not* hold in general. For this, consider for example the absolute value function f(x) = |x| in the point 0. We further remark that there exist continuous functions on \mathbb{R} which are differentiable in *no* point of their domain of definition.

- **1.5 Theorem.** (Calculation rules for differentiable functions) Let $f, g : D \subset \mathbb{R} \to \mathbb{K}$ be functions differentiable in $x_0 \in D$. Then the following statements hold:
- a) The function $\alpha f + \beta g : D \subset \mathbb{R} \to \mathbb{K}$ is differentiable in x_0 for all $\alpha, \beta \in \mathbb{K}$ and

$$(\alpha f + \beta g)'(x_0) = \alpha f'(x_0) + \beta g'(x_0).$$

Thus, differentiation is a linear mapping; here differentiation is interpreted as an operation acting from some set of functions into another set of functions.

b) (Product rule). The product $f \cdot g$ is differentiable at x_0 and we have

$$(f \cdot g)'(x_0) = f'(x_0)g(x_0) + f(x_0)g'(x_0).$$

c) (Quotient rule). If $g(x_0) \neq 0$, then there exists a $\delta > 0$ such that $g(x) \neq 0$ for all $x \in D \cap (x_0 - \delta, x_0 + \delta)$ and $\frac{f}{g} : D \cap (x_0 - \delta, x_0 + \delta) \to \mathbb{K}$ is differentiable in x_0 and

$$\left(\frac{f}{g}\right)'(x_0) = \frac{f'(x_0)g(x_0) - f(x_0)g'(x_0)}{g^2(x_0)}.$$

Proof. The statement a) follows directly from the calculation rules for limits. To prove b), let $h \neq 0$ and $x_0 + h \in D$. Then we have

$$\frac{f(x_0 + h)g(x_0 + h) - f(x_0)g(x_0)}{h}$$

$$= \frac{f(x_0 + h) - f(x_0)}{h}g(x_0 + h) + \frac{g(x_0 + h) - g(x_0)}{h}f(x_0)$$

$$\xrightarrow{h \to 0} f'(x_0)g(x_0) + g'(x_0)f(x_0).$$

To prove c) we note that $\frac{f}{g} = f \cdot \frac{1}{g}$, thus by (b) it is sufficient to discuss 1/g.

$$\frac{1}{h} \left(\frac{1}{g(x_0 + h)} - \frac{1}{g(x_0)} \right) = \frac{1}{g(x_0 + h)g(x_0)} \cdot \frac{g(x_0) - g(x_0 + h)}{h} \xrightarrow{h \to 0} - \frac{g'(x_0)}{g^2(x_0)}.$$

- **1.6 Examples.** a) A polynomial p of the form $p(x) = 5x^3 + 7x^2 + 3x$ is differentiable with derivative $p'(x) = 15x^2 + 14x + 3$. This follows from Example 1.2 a) and Theorem 1.5 a).
- b) The sine as well as the cosine functions are differentiable for all $x \in \mathbb{R}$ and we have

$$\sin'(x) = \cos x, \qquad \cos'(x) = -\sin x, \quad x \in \mathbb{R},$$

because $\sin x = \frac{1}{2i}(e^{ix} - e^{-ix})$ and Example 1.2 b) and Theorem 1.5 a) imply

$$(\sin x)' = \frac{1}{2i}(ie^{ix} + ie^{-ix}) = \cos x.$$

c) The quotient rule implies that the derivative of the tangent function is given by

$$(\tan x)' = \frac{\cos^2 x + \sin^2 x}{\cos^2 x} \stackrel{\text{III.4.3}}{=} \frac{1}{\cos^2 x} = 1 + \tan^2 x, \quad x \in \mathbb{R} \setminus \{\frac{\pi}{2} + k\pi : k \in \mathbb{Z}\}.$$

- d) For $n \in \mathbb{N}$ let $f : \mathbb{R} \setminus \{0\} \to \mathbb{R}$ be given by $x \mapsto x^{-n}$. Then we have $f'(x) = -nx^{-n-1}$, because if we define $h(x) = x^n$, then we have $f = \frac{1}{h}$, and by the quotient rule we can deduce $f'(x) = \frac{-nx^{n-1}}{x^{2n}} = -nx^{-n-1}$ for all $x \in \mathbb{R} \setminus \{0\}$.
- **1.7 Theorem.** (Chain rule) Let $f: D_f \subset \mathbb{R} \to \mathbb{K}$ and $g: D_g \subset \mathbb{R} \to \mathbb{R}$ be two functions with $g(D_g) \subset D_f$. If g is differentiable in $x_0 \in D_g$ and f is differentiable in $y_0 := g(x_0) \in D_f$, then $f \circ g: D_g \subset \mathbb{R} \to \mathbb{K}$ is differentiable in x_0 and we have

$$(f \circ g)'(x_0) = g'(x_0) \cdot f'(y_0)\Big|_{y_0 = g(x_0)} = f'(g(x_0)) \cdot g'(x_0).$$

Proof. By Theorem 1.3, there exist functions φ_g and φ_f which are continuous at x_0 and $y_0 := g(x_0)$, resp., such that

$$f(y) - f(y_0) = (y - y_0)\varphi_f(y), \quad \varphi_f(y_0) = f'(y_0), \ y \in D_f$$

$$g(x) - g(x_0) = (x - x_0)\varphi_g(x), \quad \varphi_g(x_0) = g'(x_0), \ x \in D_g.$$

Therefore, we have

efore, we have
$$(f \circ g)(x) - (f \circ g)(x_0) = (g(x) - g(x_0))\varphi_f(g(x)) = (x - x_0)\underbrace{\varphi_g(x)\varphi_f(g(x))}_{=:\varphi(x)}$$

with a function $\varphi := \varphi_g \cdot (\varphi_f \circ g)$, which is continuous at x_0 . Now, Theorem 1.3 implies that $f \circ g$ is differentiable at x_0 and, by the preceding formula,

$$(f \circ g)'(x_0) = \varphi(x_0) = \varphi_g(x_0)\varphi_f(g(x_0)) = f'(g(x_0)) \cdot g'(x_0).$$

To conclude this section, we examine the derivative of the inverse of a given differentiable function.

1.8 Theorem. (Derivative of the inverse function). Let $J \subset \mathbb{R}$ be an interval and let g be the inverse function of a continuous and strictly monotone function $f: J \to \mathbb{R}$. If f is differentiable at $x_0 \in J$ and $f'(x_0) \neq 0$, then $g: f(J) \to \mathbb{R}$ is differentiable at $y_0 := f(x_0)$ and we have

$$g'(y_0) = g'(f(x_0)) = \frac{1}{f'(x_0)} = \frac{1}{f'(g(y_0))}.$$

Proof. By assumption and Theorem 1.3, there exists a function φ which is continuous at x_0 such that $f(x) - f(x_0) = (x - x_0)\varphi(x)$ for all $x \in J$. Because we have $\varphi(x_0) = f'(x_0) \neq 0$, there exists a $\delta > 0$ such that $\varphi(x) \neq 0$ for all $x \in J_\delta := J \cap [x_0 - \delta, x_0 + \delta]$. If we let x = g(y) for $y \in f(J_\delta)$, we have

$$y - y_0 = f(g(y)) - f(g(y_0)) = (g(y) - g(y_0))\varphi(g(y)), \quad y \in f(J_\delta).$$

Therefore, $g(y)-g(y_0)=(y-y_0)\frac{1}{\varphi(g(y))}$ holds, and $\varphi\circ g$ is continuous at x_0 by Section III.1. Theorem 1.3 now implies that g is differentiable at y_0 and that we have

$$g'(y_0) = \frac{1}{\varphi(g(y_0))} = \frac{1}{\varphi(x_0)} = \frac{1}{f'(x_0)} = \frac{1}{f'(g(y_0))}.$$

1.9 Example. The function $\tan : (-\pi/2, \pi/2) \to \mathbb{R}$ is differentiable by 1.6 c) and we have $\tan'(x) = 1 + \tan^2 x$ for all $x \in (-\pi/2, \pi/2)$. Therefore, $\arctan : \mathbb{R} \to \mathbb{R}$ is also differentiable and we have

$$\arctan'(y) = \frac{1}{1 + \tan^2(\arctan y)} = \frac{1}{1 + y^2}.$$

2 The Mean Value Theorem and Applications

In Section III.3, we saw that a continuous real valued function f on a compact set has a global maximum and a global minimum. We shall now see that if the function is furthermore differentiable, the derivative gives an additional information on the location of the extrema. More precisely, we have the following (necessary) criterion for extremal values; as an application of the mean value theorem, we will later also give a sufficient criterion.

2.1 Definition. If $f: D \subset \mathbb{R} \to \mathbb{R}$ is a function, we call $x_0 \in D$ a local maximum (minimum) (lokales Maximum (Minimum)) of f, if there exists a $\delta > 0$ such that

$$f(x) \le f(x_0)$$
 $(f(x) \ge f(x_0))$ for all $x \in D \cap (x_0 - \delta, x_0 + \delta)$.

Local minima and maxima are also called *local extrema* (*lokale Extrema*) of a given function f. In the following, we will give criteria which allow to examine a given function for local extrema. Firstly, we begin with a necessary criterion.

2.2 Theorem. Let $a, b \in \mathbb{R}$ with a < b and let $f : (a, b) \to \mathbb{R}$ be a function which has a local extremum at $x_0 \in (a, b)$. If f is differentiable in x_0 , then $f'(x_0) = 0$.

Proof. Let x_0 be a local minimum of f. Then there exists a $\delta > 0$ with

$$f(x) - f(x_0) \ge 0$$
, for all $x \in (x_0 - \delta, x_0 + \delta)$.

Therefore we have, when we let x tend to x_0 from the left hand side,

$$f'(x_0) = \lim_{x \to x_0 -} \frac{f(x) - f(x_0)}{x - x_0} \le 0.$$

For the right sided limit we obtain

$$f'(x_0) = \lim_{x \to x_0 +} \frac{f(x) - f(x_0)}{x - x_0} \ge 0.$$

This implies $f'(x_0) = 0$. The proof for a local maximum is analogous.

At this point we remark that the converse of the above theorem does not hold in general, and that a function f that is defined on a closed interval [a, b] can attain an extremum at a or b even if $f'(a) \neq 0$ and $f'(b) \neq 0$.

The following theorem is an easy consequence of the above theorem.

2.3 Corollary (Rolle's Theorem (Satz von Rolle)). Let $f : [a,b] \to \mathbb{R}$ be a continuous function which is differentiable on (a,b). If f(a) = f(b), then there exists $\xi \in (a,b)$ with $f'(\xi) = 0$.

Proof. If f is a constant function, then we have f' = 0 and, therefore, the proposition holds. Let us now assume that f is not constant. By Theorem III.3.9, f attains its maximum max f and minimum min f on the compact interval [a, b]. Then $\max f \neq f(a) = f(b)$ or $\min f \neq f(a) = f(b)$. Thus, there is a $\xi \in (a, b)$ which is an extremum of f. By Theorem 2.2 above, we thus have $f'(\xi) = 0$.

The following *mean value theorem* is the central theorem of this section. It has far reaching consequences for the analysis in one real variable.

2.4 Theorem (Mean value theorem (Mittelwertsatz)). If $f : [a,b] \to \mathbb{R}$ is a continuous, real-valued function which is differentiable on (a,b), then there exists a $\xi \in (a,b)$ with

$$f(b) - f(a) = f'(\xi)(b - a).$$

Proof. We define a function $F:[a,b]\to\mathbb{R}$ by

$$F(x) := f(x) - \frac{f(b) - f(a)}{b - a}(x - a).$$

Then F is continuous on [a, b] and differentiable on (a, b). We have F(a) = f(a) = F(b). Therefore, by Rolle's Theorem 2.3, there exists a $\xi \in (a, b)$ with

$$F'(\xi) = 0 = f'(\xi) - \frac{f(b) - f(a)}{b - a}.$$

At this point, we remark that the mean value theorem does *not* hold for complexvalued differentiable functions $f:[a,b]\to\mathbb{C}$. A counterexample is given by the function $f:[0,2\pi]\to\mathbb{C}$, defined by $f(x)=e^{ix}$. We have $f(0)=1=f(2\pi)$, but $f'(x)=ie^{ix}\neq 0$ for all $x\in[0,2\pi]$.

The mean value theorem has many important consequences. Some of these are assembled in the following corollary.

- **2.5 Corollary.** Let $f:[a,b] \to \mathbb{R}$ be a continuous function which is differentiable on (a,b). Then the following propositions hold.
- (a) f is constant \Leftrightarrow f'(x) = 0 for all $x \in (a, b)$.

(b)

$$f'(x) \ge 0$$
 for all $x \in (a,b)$ \Leftrightarrow f is increasing on $[a,b]$.

$$f'(x) \le 0$$
 for all $x \in (a,b)$ \Leftrightarrow f is decreasing on $[a,b]$.

$$f'(x) > 0$$
 for all $x \in (a,b)$ \Rightarrow f is strictly increasing on $[a,b]$.

$$f'(x) < 0$$
 for all $x \in (a,b)$ \Rightarrow f is strictly decreasing on $[a,b]$.

- (c) If $f'(x_0) = 0$ for an $x_0 \in (a, b)$ then, for a sufficiently small $\delta > 0$, x_0 is a
 - i) local minimum, if $f' \leq 0$ in $(x_0 \delta, x_0)$ and $f' \geq 0$ on $(x_0, x_0 + \delta)$;
 - ii) local maximum, if $f' \ge 0$ in $(x_0 \delta, x_0)$ and $f' \le 0$ on $(x_0, x_0 + \delta)$.
- (d) If $|f'(x)| \leq L$ for all $x \in [a, b]$, we have

$$|f(x) - f(y)| \le L|x - y|$$
, for all $x, y \in [a, b]$,

i.e., f is Lipschitz continuous with Lipschitz constant L.

(e) The function f' has the intermediate value property even though it is not continuous in general. More precisely, let $f'(a) \neq f'(b)$ and $\min\{f'(a), f'(b)\} < \alpha < \max\{f'(a), f'(b)\}$. Then, there exists $\xi \in (a, b)$ with $f'(\xi) = \alpha$.

Proof. a) If f is constant, it is clear that f'(x) = 0 for all $x \in (a, b)$. Conversely, let $x \in (a, b]$. By the mean value theorem and the assumption, there exists $\xi \in (a, x)$ with $f(x) - f(a) = f'(\xi)(x - a) = 0$. Therefore, f(x) = f(a).

b) The definition of differentiability immediately implies that $f'(x) \ge 0$ for all $x \in (a, b)$, given that f is increasing. Conversely, let $a \le x < y \le b$. Again, by the mean value theorem, there exists a $\xi \in (x, y)$ with

$$f(y) - f(x) = \underbrace{f'(\xi)}_{\geq 0} \underbrace{(y - x)}_{> 0} \geq 0,$$

if $f' \geq 0$.

The propositions c), d) and e) are left as exercises.

A further corollary of the mean value theorem is the following characterization of the exponential function on \mathbb{R} .

2.6 Corollary. The exponential function exp is the only differentiable function f: $\mathbb{R} \to \mathbb{C}$ with f' = f and f(0) = 1.

As proof, consider the function $g(x) := f(x)e^{-x}$ for $x \in \mathbb{R}$. We have $g'(x) = [f'(x) - f(x)]e^{-x} = 0$ for all $x \in \mathbb{R}$ and, therefore, g is a constant with the value g(0) = 1.

2.7 Theorem (Generalized mean value theorem¹). Let $f, g : [a, b] \to \mathbb{R}$ be continuous functions which are differentiable in (a, b) and assume that $g'(x) \neq 0$ for all $x \in (a, b)$. Then we have $g(a) \neq g(b)$ and there exists $a \notin (a, b)$ with

$$\frac{f(b) - f(a)}{g(b) - g(a)} = \frac{f'(\xi)}{g'(\xi)}.$$

¹also known as Cauchy mean value theorem

Proof. Firstly, we have $g(a) \neq g(b)$, because otherwise, by Rolle's Theorem 2.3, there would exist a $x \in (a, b)$ with g'(x) = 0, contradicting the assumption. To prove the theorem, we define $F : [a, b] \to \mathbb{R}$ by

$$F(x) := f(x) - \frac{f(b) - f(a)}{g(b) - g(a)}(g(x) - g(a)).$$

Then F(a) = f(a) = F(b) and by Rolle's theorem, there exists a $\xi \in (a, b)$ with

$$0 = F'(\xi) = f'(\xi) - \frac{f(b) - f(a)}{g(b) - g(a)}g'(\xi).$$

Making use of the generalized mean value theorem, we also prove the rules of l'Hospital. They allow to compute limits of the form $\lim_{x\to x_0} \frac{f(x)}{g(x)}$ where f(x) as well as g(x) tend to ∞ for $x\to x_0$.

2.8 Corollary (L'Hospital's Rules (l'Hospitalsche Regeln)). Let $-\infty < a < b < \infty$ and let $f, g : (a, b) \to \mathbb{R}$ be two differentiable functions with $g'(x) \neq 0$ for all $x \in (a, b)$. If

- a) $\lim_{x\to a+} f(x) = 0 = \lim_{x\to a+} g(x)$ or
- b) $\lim_{x\to a+} f(x) = \infty = \lim_{x\to a+} g(x)$,

and $\lim_{x\to a+} \frac{f'(x)}{g'(x)}$ exists, then $\lim_{x\to a+} \frac{f(x)}{g(x)}$ exists as well, and we have

$$\lim_{x \to a+} \frac{f(x)}{g(x)} = \lim_{x \to a+} \frac{f'(x)}{g'(x)}.$$

The corresponding result does also hold for $x \to b-$, $x \to \infty$ or $x \to -\infty$.

Proof. To prove proposition a), we view f and g as continuous in a by setting f(a) = g(a) = 0. By the generalized mean value theorem, for each $x \in (a, b)$ there exists a $\xi \in (a, x)$ with

$$\frac{f(x)}{g(x)} = \frac{f(x) - f(a)}{g(x) - g(a)} = \frac{f'(\xi)}{g'(\xi)}.$$

If $x \to a$, it follows that $\xi \to a$, which in turn entails the proposition.

For the case b) let $q := \lim_{x \to a} \frac{f'(x)}{g'(x)}$. Then for each $\varepsilon > 0$ there exists a $c \in (a, b)$ with

$$\left| \frac{f'(x)}{g'(x)} - q \right| \le \varepsilon$$
, for all $x \in (a, c)$.

Then, by the generalized mean value theorem,

$$\left| \frac{f(x) - f(y)}{g(x) - g(y)} - q \right| \le \varepsilon, \quad x, y \in (a, c), \ x \ne y.$$

Now fix $y \in (a, c)$. Because $\lim_{x\to a} g(x) = \infty$ by assumption, there exists a $c' \in (a, c)$ with

$$\left|\frac{g(y)}{g(x)}\right| \le \varepsilon \text{ and } \left|\frac{f(y)}{g(x)}\right| \le \varepsilon \text{ for all } x \in (a, c').$$

Thus, we have

$$\left| \frac{f(x)}{g(x)} - q \right| = \left| \left(1 - \frac{g(y)}{g(x)} \right) \left(\frac{f(x) - f(y)}{g(x) - g(y)} - q \right) + \frac{f(y)}{g(x)} - q \frac{g(y)}{g(x)} \right|$$

$$\leq \varepsilon (2 + |q| + \varepsilon)$$

for all $x \in (a, c')$, i.e. we have $\lim_{x \to a} \frac{f(x)}{g(x)} = q = \lim_{x \to a} \frac{f'(x)}{g'(x)}$. The remaining cases are proved analogously.

L'Hospital's rules are often very convenient to calculate limits.

2.9 Examples. The following propositions hold.

a)
$$\lim_{x \to 0} \frac{\log(1+x)}{x} \stackrel{2.8}{=} \lim_{x \to 0} \frac{\frac{1}{1+x}}{1} = 1.$$

$$\mathrm{b)}\ \lim_{x\to\infty} \tfrac{\log x}{x^\alpha} \stackrel{2.8}{=} \lim_{x\to\infty} \tfrac{1}{x} \tfrac{1}{\alpha x^{\alpha-1}} = \lim_{x\to\infty} \tfrac{1}{\alpha x^\alpha} = 0, \quad \alpha > 0.$$

c)
$$\lim_{x \to 0} \left(\frac{1}{\sin x} - \frac{1}{x} \right) = \lim_{x \to 0} \frac{x - \sin x}{x \sin x} \stackrel{2.8}{=} \lim_{x \to 0} \frac{1 - \cos x}{\sin x + x \cos x} \stackrel{2.8}{=} \lim_{x \to 0} \frac{\sin x}{\cos x + \cos x - x \sin x} = 0.$$

We now consider derivatives of higher order. More precisely, let $f: D \subset \mathbb{R} \to \mathbb{K}$ be a differentiable function. If f' is also differentiable, then f is called two times differentiable and we call f'' := (f')' the second derivative of f. More generally, one defines the n-th derivative $f^{(n)}$ recursively as the derivative of $f^{(n-1)}$. For $f^{(n)}$, we also write $\frac{d^n f}{dx^n}$ or $D^n f$.

2.10 Definition. A function $f: D \subset \mathbb{R} \to \mathbb{K}$ is called *n times continuously differentiable* if f is n times differentiable and the n-th derivative is still continuous. Notation: $f \in C^n(D, \mathbb{K})$.

The second derivative of a function can also be interpreted geometrically. For this, we introduce the notion of a convex function.

2.11 Definition. If $J \subset \mathbb{R}$ is an interval, $f: J \to \mathbb{R}$ a function, we call f convex (konvex), if for all $x_1, x_2 \in J$ and all $\lambda \in (0, 1)$ we have

$$f((1-\lambda)x_1 + \lambda x_2) \le (1-\lambda)f(x_1) + \lambda f(x_2).$$

The following theorem describes the relation between convex functions f and properties of f'.

2.12 Theorem. Let $f: J \subset \mathbb{R} \to \mathbb{R}$ be a differentiable function. Then f is convex if and only if f' is monotone increasing.

Proof. \Longrightarrow : Let $x, x_1, x_2 \in J$ with $x_1 < x < x_2$. We choose $\lambda \in (0, 1)$ such that $x = (1 - \lambda)x_1 + \lambda x_2$. Because f is convex by assumption, we have $f(x) \leq (1 - \lambda)f(x_1) + \lambda f(x_2)$. Therefore,

$$f(x) - f(x_1) \le \lambda [f(x_2) - f(x_1)]$$

 $f(x_2) - f(x) \ge (1 - \lambda) [f(x_2) - f(x_1)]$

and because of $x - x_1 = \lambda(x_2 - x_1) > 0$ and $x_2 - x = (1 - \lambda)(x_2 - x_1) > 0$, it follows for all $x, x_1 < x < x_2$, that

$$\frac{f(x) - f(x_1)}{x - x_1} \le \frac{f(x_2) - f(x_1)}{x_2 - x_1} \le \frac{f(x_2) - f(x)}{x_2 - x}, \quad x_1 < x < x_2.$$

Therefore, we have

$$f'(x_1) = \lim_{x \to x_1 +} \frac{f(x) - f(x_1)}{x - x_1} \le \frac{f(x_2) - f(x_1)}{x_2 - x_1} \le \lim_{x \to x_2 -} \frac{f(x_2) - f(x)}{x_2 - x} = f'(x_2),$$

thus f is increasing.

: The proof is similar to the preceding one and is left to the reader as an exercise.

2.13 Corollary. If $f:(a,b) \to \mathbb{R}$ is a two times differentiable function, we have f is convex $\iff f'' \ge 0$ in (a,b).

2.14 Example. The function $-\log$ is convex on \mathbb{R}_+ , because we have $(\log x)'' = -\frac{1}{x^2} \le 0$ for all x > 0. Functions f with the property "-f is convex" are called *concave* (*konkav*). In particular, log is a concave function on \mathbb{R}_+ .

Convex and concave functions are important notions in analysis and have interesting applications. We consider in particular Young's and Hölder's inequalities. For $p \in (1, \infty)$, we call $q \in (1, \infty)$ with

$$\frac{1}{p} + \frac{1}{q} = 1$$

the Hölder conjugate of p (zu p konjugierter Index).

2.15 Theorem (Young's inequality). For $1 < p, q < \infty$ with 1/p + 1/q = 1, we have

$$ab \le \frac{1}{p}a^p + \frac{1}{q}b^q, \quad a, b \ge 0.$$

Proof. Let a > 0 and b > 0, otherwise the statement is trivial. Since log is a concave function, it follows from the definition of convexity with $\lambda = 1/p$ and $(1 - \lambda) = 1/q$, that

$$\log(\frac{a^p}{p} + \frac{b^p}{q}) \ge \frac{1}{p}\log a^p + \frac{1}{q}\log b^q = \log a + \log b = \log(ab).$$

Because the exponential function is increasing, the proposition follows by applying the exponential function on both sides of the above inequality.

For a vector $x = (x_1, x_2, \dots, x_n) \in \mathbb{K}^n$ and p with 1 , we define

$$||x||_p := \left(\sum_{j=1}^n |x_j|^p\right)^{\frac{1}{p}}.$$

2.16 Corollary (Hölder's Inequality). For $1 < p, q < \infty$ with 1/p + 1/q = 1 and $x, y \in \mathbb{K}^n$, we have

$$\sum_{j=1}^{n} |x_j y_j| \le ||x||_p ||y||_q.$$

We observe that the special case p=q=2 is precisely the Cauchy-Schwarz inequality known from linear algebra.

Proof. W.l.o.g. let $x, y \neq 0$. Young's equality above implies

$$\frac{|x_j|}{||x||_p} \frac{|y_j|}{||y||_q} \le \frac{1}{p} \frac{|x_j|^p}{||x||_p^p} + \frac{1}{q} \frac{|y_j|^q}{||y||_q^q}.$$

Summing up yields

$$\sum_{j=1}^{n} \frac{|x_j y_j|}{||x||_p ||y||_q} \le \frac{1}{p} + \frac{1}{q} = 1,$$

which is equivalent to the assertion.

3 Taylor's theorem

The differential calculus, as presented previously, approximates a function, which is differentiable at a, by an affine function, i.e., we have the representation

$$f(x) = f(a) + f'(a)(x - a) + R(x)$$

of f as a sum of an affine function and an error term R(x) for which

$$\lim_{x \to a} R(x)(x - a) = 0$$

holds. Now, we want to use polynomials instead of affine functions to get even more accurate approximations. More precisely, for a given n times differentiable function f, we seek a polynomial p of degree at most n such that

$$p(a) = f(a), p'(a) = f'(a), \dots, p^{(n)}(a) = f^{(n)}(a).$$
 (3.1)

Considering such a polynomial $p(x) = \sum_{j=0}^{n} a_j (x-a)^j$ we get for its coefficients a_0, \ldots, a_n , since $p^{(k)}(a) = k! a_k$,

$$a_k = \frac{f^k(a)}{k!}, \quad k = 0, \dots, n.$$

That means that there exists exactly one polynomial of degree at most n for which (3.1) holds, namely

$$(T_n f)(x,a) = f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(x-a)^n.$$

This motivates the following definition.

3.1 Definition. Let $I \subset \mathbb{R}$ be an interval, and $f: I \to \mathbb{R}$ an n times differentiable function and $a \in I$. Then we call $T_n f$ the n-th Taylor polynomial (n-tes Taylorpolynom) of f near a.

The question of how good f is approximated of course depends on the remainder term

$$(R_n f)(x, a) := f(x) - (T_n f)(x, a).$$

Taylor's theorem provides a conclusive answer to this question.

3.2 Theorem (Taylor's Theorem). Let $I \subset \mathbb{R}$ be an interval, $a, x \in I$ with $a \neq x$. Let $k \in \mathbb{N}$ and $f: I \to \mathbb{R}$ be an (n+1) times continuously differentiable function. Then there exists $a \notin (\min\{a, x\}, \max\{a, x\})$ such that

$$f(x) = \sum_{j=0}^{n} \frac{f^{(j)}(a)}{j!} (x-a)^{j} + \frac{f^{(n+1)}(\xi)}{kn!} \left(\frac{x-\xi}{x-a}\right)^{n-k+1} (x-a)^{n+1}.$$

Proof. In the following, we will show that the remainder term of the approximation is given by

$$(R_n f)(x, a) = \frac{f^{(n+1)}(\xi)}{kn!} \left(\frac{x-\xi}{x-a}\right)^{n-k+1} (x-a)^{n+1}$$

To this end we define functions $g: J \to \mathbb{R}$ and $h: J \to \mathbb{R}$ by

$$g(t) := \sum_{j=0}^{n} \frac{f^{(j)}(t)}{j!} (x-t)^{j}, \qquad h(t) := (x-t)^{k},$$

where J denotes the interval $J := (\min\{a, x\}, \max\{a, x\})$. Then we have

$$g'(t) = \sum_{j=0}^{n} \left(\frac{f^{(j+1)}(t)}{j!} (x-t)^{j} - \frac{f^{(j)}(t)}{j!} j(x-t)^{j-1} \right) = f^{(n+1)}(t) \frac{(x-t)^{n}}{n!}$$

and $h'(t) = -k(x-t)^{k-1}$ for all $t \in J$. By the generalized mean value theorem, there exists a $\xi \in J$ with

$$\frac{g(x) - g(a)}{h(x) - h(a)} = \frac{g'(\xi)}{h'(\xi)}.$$

Further, we have $g(x) - g(a) = R_n f(x, a)$ and $h(x) - h(a) = -(x - a)^k$ and, therefore,

$$R_n f(x, a) = \frac{f^{(n+1)}(\xi)}{kn!} \left(\frac{x-\xi}{x-a}\right)^{n-k+1} (x-a)^{n+1}.$$

If we let k = n + 1 or k = 1 in the above theorem, we obtain the Lagrange form and the Cauchy form of the remainder term, respectively.

3.3 Corollary. With the assumptions of the theorem, we have

$$R_n f(x,a) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-a)^{n+1} \quad (Lagrange form of the remainder term)$$

and

$$R_n f(x,a) = \frac{f^{(n+1)}(\xi)}{n!} \left(\frac{x-\xi}{x-a}\right)^n (x-a)^{n+1} \quad (Cauchy form of the remainder term).$$

In the following, we consider an arbitrarily often differentiable function f on an interval $J \subset \mathbb{R}$. For $a \in J$ we call

$$(Tf)(x,a) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n = \lim_{n \to \infty} (T_n f)(x,a)$$

the Taylor series (Taylorreihe) of f in a.

3. TAYLOR'S THEOREM

101

It is now natural to ask the following questions:

- a) Does the Taylor series converge, and if yes, to which value?
- b) Does the Taylor series converge to f at least in a neighbourhood of a?

A first answer to question b) is given by the following Theorem:

3.4 Theorem. Let $f: J \to \mathbb{R}$ be an arbitrarily often differentiable function and $x, a \in J$. Then we have

$$(Tf)(x,a) = f(x) \iff \lim_{n \to \infty} R_n f(x,a) = 0.$$

Of course, this theorem follows directly from Taylor's theorem (3.2) and the definition of convergence of a series. At first sight, the statement of this theorem seems quite banal; however there exist functions f for which $\lim_{n\to\infty} R_n f(x,a)$ exists, but is not equal to 0. In this case, the Taylor series converges at the point x, but not to f(x)! In the following example, we explicitly state such a function.

3.5 Example. Consider the function $f: \mathbb{R} \to \mathbb{R}$, given by

$$f(x) := \begin{cases} e^{-\frac{1}{x^2}}, & x \neq 0 \\ 0, & x = 0. \end{cases}$$

Then f is arbitrarily often differentiable on \mathbb{R} and we have $f^{(n)}(0) = 0$ for all $n \in \mathbb{N}_0$ (compare with the exercises). Therefore, we have

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n = 0 \text{ for all } x \in \mathbb{R}, \text{ but } f(x) \neq 0 \text{ for } x \neq 0.$$

A sufficient criterion for the convergence of the Taylor series to f is given by the following corollary.

3.6 Corollary. Let $f: J \to \mathbb{R}$ be an arbitrarily often differentiable function and $x, a \in J$. Assume there exists an M > 0 with

$$\sup_{n\in\mathbb{N}_0} \max_{\xi\in[a,x]} |f^{(n)}(\xi)| \le M \quad or \quad \sup_{n\in\mathbb{N}_0} \max_{\xi\in[x,a]} |f^{(n)}(\xi)| \le M.$$

Then we have

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x - a)^n.$$

The proof is easy. Since we have

$$|(R_n f)(x, a)| = \left| \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - a)^{n+1} \right| \le \frac{M|x - a|^{n+1}}{(n+1)!} \xrightarrow{n \to \infty} 0,$$

the claim follows from 3.4.

We further exemplify the theorem using some examples.

3.7 Examples. a) We have

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}, \quad x \in \mathbb{R},$$

because the exponential function is arbitrarily often differentiable on \mathbb{R} , and we have $f^{(n)}(x) = e^x$ for all $x \in \mathbb{R}$ and for all $n \in \mathbb{N}$. Therefore we have

$$\frac{f^{(0)}(0)}{0!} = 1, \quad \frac{f^{(n)}(0)}{n!} = \frac{1}{n!}, \quad (T_n f)(x, 0) = \sum_{j=0}^n \frac{x^j}{j!}$$

and furthermore

$$\max_{\xi \in [0,x]} |f^{(n)}(\xi)| = e^x, \quad \max_{\xi \in [x,0]} |f^{(n)}(\xi)| = 1, \quad x \in \mathbb{R}$$

for all $n \in \mathbb{N}$. Corollary 3.6 therefore implies the proposition.

b) For $x \in (-1, 1]$, we have:

$$\log(1+x) = \sum_{n=1}^{\infty} (-1)^{n+1} \frac{x^n}{n}.$$

For the proof consider $f(x) := \log(1+x)$ for all x > -1. Then, f is arbitrarily often differentiable and we have

$$f^{(n)}(x) = \frac{(n-1)!(-1)^{n+1}}{(1+x)^n}, \quad \frac{f^{(0)}(0)}{0!} = 0, \quad \frac{f^{(n)}(0)}{n!} = \frac{(-1)^{n+1}}{n}, \quad n \in \mathbb{N},$$

and therefore

$$T_n f(x,0) = \sum_{j=1}^n \frac{(-1)^{j+1}}{j} x^j.$$

The Lagrange form of the remainder term for $x \in [0, 1]$ is

$$R_n f(x,0) = \frac{f^{(n+1)}(\xi)x^{n+1}}{(n+1)!} = \frac{(-1)^n x^{n+1}}{(1+\xi)^{n+1}(n+1)} \quad \text{for some } \xi \in (0,1).$$

Therefore, we have $|R_n f(x,0)| \leq \frac{1}{n+1} \left| \frac{x}{1+\xi} \right|^{n+1} \leq \frac{1}{n+1}$, and thus

$$R_n f(x,0) \stackrel{n \to \infty}{\longrightarrow} 0, \quad x \in [0,1].$$

If -1 < x < 0, we use the Cauchy form of the remainder term to deduce that

$$R_n f(x,0) = \frac{f^{(n+1)}(\xi)}{n!} \left(\frac{x-\xi}{x}\right)^n x^{n+1} = \frac{n!(-1)^n}{(1+\xi)^{n+1} n!} x^{n+1} \left(\frac{x-\xi}{x}\right)^n,$$

and therefore

$$|R_n f(x,0)| = \frac{|x-\xi|^n}{|1+\xi| |1+\xi|^n} |x|.$$

If $\xi \in (x,0)$ we have $\xi - x = \xi + 1 - (x+1)$, thus $\left| \frac{x-\xi}{1+\xi} \right| = \frac{\xi-x}{1+\xi} = 1 - \frac{1+x}{1+\xi} < 1$, hence

$$|R_n f(x,0)| \stackrel{n \to \infty}{\longrightarrow} 0.$$

In particular, for x = 1 we have

$$\ln(x+1) = \ln 2 = \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{n} = 1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \dots,$$

which gives us an explicit value for the alternating harmonic series.

Furthermore, Taylor's theorem gives a sufficient criterion to determine local extrema.

3.8 Theorem (Sufficient criteron for local extrema). Let $n \in \mathbb{N}$ be odd, $J \subset \mathbb{R}$ be an interval. Assume that $f: J \to \mathbb{R}$ is an (n+1)-times continuously differentiable function with

$$f'(a) = \dots = f^{(n)}(a) = 0$$
, and $f^{(n+1)}(a) \neq 0$, $a \in J$.

Then the following statements hold:

- a) If $f^{(n+1)}(a) > 0$, then f has a local minimum at a.
- b) If $f^{(n+1)}(a) < 0$, then f has a local maximum at a.

Proof. Let $f^{(n+1)}(a) > 0$. Since $f^{(n+1)}$ is continuous on J by assumption, there exists a neighbourhood $U_{\delta}(a) \subset J$ of a with $f^{(n+1)}(x) > 0$ for all $x \in U_{\delta}(a)$. Taylor's theorem with the Lagrange form of the remainder term implies that there exists a $\xi \in U_{\delta}(a)$ with

$$f(x) = f(a) + \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-a)^{n+1} > f(a) \quad \text{for all } x \in U_a,$$

which is just the proposition. For the case $f^{(n+1)}(a) < 0$, the proof is analogous.

We conclude this section by showing how to find approximations for the roots of differentiable functions. To this end we at first consider an affine approximation of f given by $F(x) = f(x_0) + f'(x_0)(x - x_0)$. Geometrically, this is the tangent to f at the point x_0 . If $f'(x_0) \neq 0$, we let

$$x_1 := x_0 - \frac{f(x_0)}{f'(x_0)},$$

thus x_1 is the root of the tangent. If $x_1 \in D_f$, we proceed by the same pattern and set $x_2 := x_1 - \frac{f(x_1)}{f'(x_1)}$. More general, we define the (n+1)-th iteration as

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \quad n = 0, 1, 2, \dots$$

This technique to approximate a root of a given function is called *Newton's method*.

- **3.9 Theorem (Convergence of Newton's method).** Let $f : [a,b] \to \mathbb{R}$ be a twice continuously differentiable function and assume that
 - a) f has a root ξ in [a,b],
 - b) $f'(x) \neq 0$ for all $x \in [a, b]$,
 - c) f is convex or concave on [a, b],
 - d) We have $x_0 \frac{f(x_0)}{f'(x_0)} \in [a, b]$ for $x_0 = a$ and $x_0 = b$.

Then Newton's method converges for each $x_0 \in [a,b]$ monotonously to ξ and we have the estimate

$$|x_k - \xi| \le \frac{M}{2m} |x_k - x_{k-1}|^2, \quad k \in \mathbb{N},$$

where $m := \min\{|f'(\tau)| : \tau \in [a, b]\}$ and $M := \max\{|f''(\tau)| : \tau \in [a, b]\}$.

The above estimate means that Newton's method has a quadratic rate of convergence.

Proof. We note that by b) f is strictly monotone, hence ξ is the only root of f in the interval [a,b]. We distinguish the four cases

$$f' > 0, \ f'' \ge 0$$
 $f' < 0, \ f'' \ge 0$
 $f' > 0, \ f'' \le 0$ $f' < 0, \ f'' \le 0$

and prove only the first one in detail. The proof of the other cases is analogous.

We define an auxiliary function $\varphi : [a, b] \to \mathbb{R}$ by

$$\varphi(x) := x - \frac{f(x)}{f'(x)}.$$

Then

$$\varphi'(x) = 1 - \frac{f'(x)^2 - f(x)f''(x)}{f'(x)^2} = \frac{f(x)f''(x)}{f'(x)^2} = \begin{cases} \le 0, & x \in [a, \xi] \\ \ge 0, & x \in [\xi, b] \end{cases}$$

where the inequalities follow from the facts that f is increasing, $f(\xi) = 0$, and $f'' \ge 0$. Furthermore, $\varphi(\xi) = \xi$ is a minimum of φ in [a, b]. By hypothesis d), it therefore follows that $\varphi(x) \in [\xi, b]$ for all $x \in [a, b]$ and we have $\varphi(x) \le x$ for all $x \in [\xi, b]$ (by definition of φ since we are considering the first case). We now set

$$x_{k+1} := \varphi(x_k) = x_k - \frac{f(x_k)}{f'(x_k)}.$$

Then we have $x_1 \in [\xi, b]$ and $x_k \in [\xi, b]$ implies $\xi \leq x_{k+1} \leq x_k$. Hence, $(x_k)_{k \in \mathbb{N}}$ is a bounded decreasing sequence with a limit ω . Since in particular φ is continuous, we have by the preceding formula (when $k \to \infty$)

$$\omega = \omega - \frac{f(\omega)}{f'(\omega)} \quad \Rightarrow \quad f(\omega) = 0 \quad \Rightarrow \quad \omega = \xi.$$

To prove the error estimate, we use the mean value theorem and obtain

$$\left| \frac{f(x_k) - f(\xi)}{x_k - \xi} \right| \ge m,$$

what in turn implies $|x_k - \xi| \leq \frac{|f(x_k)|}{m}$. Using Taylor's theorem at the point $a = x_{k-1}$ with the Lagrange form of the remainder term, we can estimate $|f(x_k)|$ by observing

$$f(x_k) = \underbrace{f(x_{k-1}) + f'(x_{k-1})(x_k - x_{k-1})}_{=0 \text{ by Construction}} + \frac{1}{2} f''(\tilde{x})(x_k - x_{k-1})^2$$

for some $\tilde{x} \in (x_{k-1}, x_k)$. Therefore we have $|f(x_k)| \leq \frac{M}{2}(x_k - x_{k-1})^2$ and thus

$$|x_k - \xi| \le \frac{M}{2m} |x_k - x_{k-1}|^2.$$

4 Convergence of Sequences of Functions

In analysis, methods to approximate functions f by sequences $(f_n)_{n\in\mathbb{N}}$ of functions with certain, often "better" properties than f, are of central importance. Our construction of the integral in the following chapter, for example, uses such an approximation method.

We start this section by considering a sequence $(f_n)_{n\in\mathbb{N}}$ of functions $f_n:D\to\mathbb{K}$ with a common domain $D\subset\mathbb{R}$. We call the sequence $(f_n)_{n\in\mathbb{N}}$ pointwise convergent on D, if for each (fixed) $x\in D$ the sequence $(f_n(x))_{n\in\mathbb{N}}$ converges in \mathbb{K} . By

$$f(x) := \lim_{n \to \infty} f_n(x)$$

we can define a limit function $f: D \to \mathbb{K}$. It is natural to ask the following questions:

- a) Are central properties of the functions f_n , such as continuity and differentiability, transferred to f?
- b) If so, is it possible to compute the derivative f' of the limit function from the derivatives of the functions f_n ?

If the functions f_n are continuous at $x_0 \in D$ then the limit function f is continuous at $x_0 \in D$, if and only if we have $\lim_{x\to x_0} f(x) = f(x_0)$, i.e. if and only if

$$\lim_{x \to x_0} \lim_{n \to \infty} f_n(x) = \lim_{n \to \infty} \lim_{x \to x_0} f_n(x).$$

The question about the continuity of limit functions therefore leads us naturally to the problem of *interchanging limits*. In the following, we show that such limits *cannot* be interchanged in general.

4.1 Examples.

a) Let D = [0, 1], and $f_n(x) = x^n$ for all $x \in [0, 1]$ and all $n \in \mathbb{N}$. Then the functions f_n are continuous on D for all $n \in \mathbb{N}$. However the limit function f, given by

$$f(x) = \begin{cases} 0, & x \in [0, 1) \\ 1, & x = 1, \end{cases}$$

is not continuous at x = 1.

b) Let again D = [0, 1] and $g_n(x) = \frac{\sin nx}{\sqrt{n}}$ for all $n \in \mathbb{N}$. The limit function is $g \equiv 0$ with derivative $g' \equiv 0$. On the other hand, we have $g'_n(x) = \sqrt{n} \cos nx$ for all $n \in \mathbb{N}$ and the sequence $g'_n(x)$ diverges at each point $x \in D$.

4.2 Definition. Let $D \subset \mathbb{R}$ be an arbitrary set and $f_n : D \to \mathbb{K}$ for all $n \in \mathbb{N}$. The sequence $(f_n)_{n \in \mathbb{N}}$ is called *uniformly convergent on* D *to* $f : D \to \mathbb{K}$, if for each $\varepsilon > 0$, there exists a $N_0 \in \mathbb{N}$ with

$$|f(x) - f_n(x)| < \varepsilon$$
 for all $x \in D$, $n \ge N_0$,

or reformulated,

$$(\forall \varepsilon > 0) (\exists N_0 \in \mathbb{N}) (\forall n > N_0) (\forall x \in D) ||f(x) - f_n(x)| < \varepsilon$$

- **4.3 Remarks.** a) Of course, a sequence (f_n) of functions that converges uniformly to f, also converges pointwise to f. The converse, however, is wrong in general.
- b) If we let

$$||f||_{\infty} := \sup_{x \in D} |f(x)|,$$

then $(f_n)_{n\in\mathbb{N}}$ converges uniformly to f if and only if we have

$$||f_n - f||_{\infty} \stackrel{n \to \infty}{\longrightarrow} 0$$

- c) For the function sequences of the above examples a) and b) we have $||f_n f||_{\infty} = 1$ and $||g_n g||_{\infty} = 1/\sqrt{n}$ for all $n \in \mathbb{N}$, respectively. Clearly (g_n) converges uniformly on [0, 1] to $g \equiv 0$.
- However, the sequence $(f_n)_{n\in\mathbb{N}}$ from example a) does not converge uniformly on [0,1], because otherwise, for given $\varepsilon = \frac{1}{4}$, there would exist a global N_0 such that $x^n < \frac{1}{4}$ for all $x \in [0,1)$ and all $n \geq N_0$, but $((1+\frac{1}{n})^{-1})^n \geq 1/3$ for all $n \in \mathbb{N}$. Contradiction!
- d) The difference between pointwise and uniform convergence can be described as follows: In the case of pointwise convergence, if we consider an $x \in D$, then for each $\varepsilon > 0$, there exists a number $N = N(\varepsilon, x)$ such that $|f_n(x) f(x)| < \varepsilon$ for all $n \ge N$. Here, the number $N(\varepsilon, x)$ may depend on x. For uniform convergence, there is for each $\varepsilon > 0$ a universal number $N = N(\varepsilon)$ such that for all $n > N(\varepsilon)$ and all $x \in D$ we have $|f_n(x) f(x)| < \varepsilon$.
- e) For x > 0 and $n \in \mathbb{N}$ consider $f_n(x) = \frac{1}{nx}$. This sequence of functions converges pointwise to 0. It does not converge uniformly on its domain $(0, \infty)$ (consider $x_n = 1/n > 0$), however it does converge uniformly on $[a, \infty)$ for each a > 0.

The following theorem gives – in analogy to the treatment for series – an inner criterion for the uniform convergence of a function sequence which does not presuppose the knowledge of the limit function.

4.4 Theorem (Cauchy criterion for uniform convergence). A sequence $(f_n)_{n\in\mathbb{N}}$ of functions $f_n: D \to \mathbb{K}$ converges uniformly if and only if for all $\varepsilon > 0$, there exists an $N_0 \in \mathbb{N}$ with

$$||f_n - f_m||_{\infty} < \varepsilon$$
 for all $n, m \ge N_0$.

Proof. \Longrightarrow : Assume that the sequence $(f_n)_{n\in\mathbb{N}}$ converges uniformly to the limit function f. Then there exists, to each $\varepsilon > 0$ an N_0 with $||f_n - f||_{\infty} < \frac{\varepsilon}{2}$ for all $n > N_0$. This implies

$$||f_n - f_m||_{\infty} \le ||f_n - f|| + ||f - f_m||_{\infty} < \varepsilon$$
 for all $n, m \ge N_0$.

 \Leftarrow : The assumption implies that $(f_n(x))_{n\in\mathbb{N}}$ is a Cauchy sequence in \mathbb{K} for each $x\in D$. Since K is complete, there is a unique pointwise limit $f(x) = \lim_{n \to \infty} f_n(x)$. To show that the sequence $(f_n)_{n\in\mathbb{N}}$ converges uniformly to f, let $\varepsilon>0$. We have to

prove the existence of an N_0 such that $|f_n(x)-f(x)|<\varepsilon$ for all $n\geq N_0$. By assumption there is an N_0 such that $|f_n(x) - f_m(x)| < \varepsilon/2$ for all $x \in D$ and all $n, m \ge N_0$. Hence, if we let $m \to \infty$, we get – as required – for all $n > N_0$

$$|f_n(x) - f(x)| = \lim_{m \to \infty} |f_n(x) - f_m(x)| \le \varepsilon/2 < \varepsilon, \quad x \in D.$$

In the following, we consider in detail the initially posed question, under which conditions certain properties of the functions f_n , such as continuity, boundedness and differentiability, are passed on to the limit function f. We begin with the property of boundedness.

4.5 Lemma. Let $f_n: D \to \mathbb{K}$ be bounded functions for all $n \in \mathbb{N}$. If the sequence $(f_n)_{n\in\mathbb{N}}$ converges uniformly on D to a function f, then f is bounded on D as well.

Proof. For $\varepsilon = 1$, there exists an $N_1 \in \mathbb{N}$ such that $|f(x) - f_{N_1}(x)| < 1$ for all $x \in D$. By assumption, there exists furthermore a constant M_{N_1} with $|f_{N_1}(x)| \leq M_{N_1}$ for all $x \in D$. Hence,

$$|f(x)| \le \underbrace{|f(x) - f_{N_1}(x)|}_{<1} + \underbrace{|f_{N_1}(x)|}_{\le M_{N_1}} \le 1 + M_{N_1} \text{ for all } x \in D.$$

The following result says that the property of continuity of an approximating sequence of functions $(f_n)_{n\in\mathbb{N}}$ is inherited to the limit function f, provided the convergence is uniform.

4.6 Theorem. [Uniform limit of continuous functions is continuous] Assume that $D \subset \mathbb{R}$ and $f_n : D \to \mathbb{K}$ are continuous functions for all $n \in \mathbb{N}$. If $(f_n)_{n \in \mathbb{N}}$ converges uniformly to $f:D\to\mathbb{K}$, then f is continuous. In other words, uniform limits of continuous functions are continuous.

Proof. Let $x_0 \in D$ and $\varepsilon > 0$. Since $(f_n)_{n \in \mathbb{N}}$ converges uniformly to f, there exists an $N_0 \in \mathbb{N}$ with $|f_{N_0}(x) - f(x)| < \frac{\varepsilon}{3}$ for all $x \in D$. Furthermore, because f_{N_0} is continuous by assumption, there exists a $\delta > 0$ with

$$|f_{N_0}(x) - f_{N_0}(x_0)| < \frac{\varepsilon}{3}$$
 for all $x \in U_\delta(x_0) \cap D$.

Therefore,

$$|f(x) - f(x_0)| \le \underbrace{|f(x) - f_{N_0}(x)|}_{<\frac{\varepsilon}{3}} + \underbrace{|f_{N_0}(x) - f_{N_0}(x_0)|}_{<\frac{\varepsilon}{3}} + \underbrace{|f_{N_0}(x_0) - f(x_0)|}_{<\frac{\varepsilon}{3}} \le \varepsilon$$

for all $x \in U_{\delta}(x_0) \cap D$.

The above Example 4.1 b) shows that there can't be a result analogous to Theorem 4.6 for differentiable functions, i.e. uniform limits of differentiable functions are not necessarily differentiable.

Rather, in this situation, we have to require uniform convergence of the sequence $(f'_n)_{n\in\mathbb{N}}$. This is made precise in the following theorem.

- **4.7 Theorem.** Let $a, b \in \mathbb{R}$ with a < b and let $f_n : [a, b] \to \mathbb{K}$ be continuously differentiable functions for all $n \in \mathbb{N}$, having the following properties:
- a) The sequence $(f_n(c))_{n\in\mathbb{N}}\subset\mathbb{K}$ converges for some $c\in[a,b]$.
- b) There is a function $f^*: [a,b] \to \mathbb{K}$, such that the sequence $(f'_n)_{n \in \mathbb{N}}$ converges uniformly on [a,b] to f^* .

Then the sequence $(f_n)_{n\in\mathbb{N}}$ converges uniformly. The limit function f is differentiable, and $f'=f^*$.

Proof. We divide the proof in three steps:

Step 1: First of all, we show that the sequence $(f_n)_{n\in\mathbb{N}}$ converges uniformly. Indeed,

$$|f_n(x) - f_m(x)| \le |f_n(x) - f_m(x) - [f_n(c) - f_m(c)]| + |f_n(c) - f_m(c)|$$

for all $n, m \in \mathbb{N}$ and all $x \in [a, b]$. The mean value theorem applied to the first term on the right hand side yields

$$|f_n(x) - f_m(x)| \le |f'_n(\xi) - f'_m(\xi)||x - c| + |f_n(c) - f_m(c)|$$
 for some $\xi \in (a, b)$.

For $\varepsilon > 0$, there exists by assumptions a) and b) an N_0 with

$$||f'_n - f'_m||_{\infty} \le \frac{\varepsilon}{2(b-a)}, \text{ for all } n, m \ge N_0$$

and $|f_n(c) - f_m(c)| \leq \frac{\varepsilon}{2}$ for all $n, m \geq N_0$. Therefore,

$$|f_n(x) - f_m(x)| \le \frac{\varepsilon}{2(b-a)}(b-a) + \frac{\varepsilon}{2} = \varepsilon$$
 for all $x \in [a,b]$.

Now the claim follows from the Cauchy criterion 4.4.

Step 2: We define

$$f:=\lim_{n\to\infty}f_n.$$

Then f_n converges uniformly to f by step 1. Moreover, by Theorem 4.6, the limit function f is continuous on [a,b] and the same is true for $f^* := \lim_{n \to \infty} f'_n$.

Step 3: We show that the limit function f is differentiable and that we have $f' = f^*$. For this, we consider the functions $g_n : [0,1] \to \mathbb{K}$, given by

$$g_n(t) = f_n(x_0 + t(x - x_0)) - tf'_n(x_0)(x - x_0).$$

for $x, x_0 \in [a, b]$. By the mean value theorem, we have $g_n(1) - g_n(0) = g'_n(\xi)$ for some $\xi \in (0, 1)$. Therefore, we have

$$g_n(1)-g_n(0) = f_n(x)-f_n(x_0)-f_n'(x_0)(x-x_0) = g_n'(\xi) = [f_n'(x_0+\xi(x-x_0))-f_n'(x_0)](x-x_0),$$

and thus, for $n \to \infty$,

$$f(x) - f(x_0) - f^*(x_0)(x - x_0) = [f^*(x_0 + \xi(x - x_0)) - f^*(x_0)](x - x_0) =: \varphi(x)(x - x_0).$$

Now f^* is continuous by step 2, and we have

$$\lim_{x \to x_0} \varphi(x) = \lim_{x \to x_0} f^*(x_0 + \xi(x - x_0)) - f^*(x_0) = 0.$$

Therefore, f is differentiable in x_0 by Theorem 1.3, and we have $f'(x_0) = f^*(x_0)$.

4.8 Examples.

a) Let $D = \mathbb{R}$ and define f_n as

$$f_n(x) = \begin{cases} -1, & x < -\frac{\pi}{n} \\ \sin\frac{nx}{2}, & -\frac{\pi}{n} \le x \le \frac{\pi}{n} \\ 1, & \frac{\pi}{n} < x. \end{cases}$$

Then the functions f_n are continuous for all $n \in \mathbb{N}$, but the limit function f, given by

$$f(x) = \begin{cases} +1, & x > 0 \\ 0, & x = 0 \\ -1, & x < 0 \end{cases}$$

is discontinuous at x = 0. Therefore, the sequence $(f_n)_{n \in \mathbb{N}}$ does not converge uniformly to f.

b) For $n \in \mathbb{N}$, consider the functions $f_n : \mathbb{R} \to \mathbb{R}$ given by $f_n(x) = \frac{1}{n}\sin(n^2x)$. Then the sequence $(f_n)_{n \in \mathbb{N}}$ converges uniformly to $f \equiv 0$, because we have $\sin(n^2x) \leq 1$ for all $n \in \mathbb{N}$ and all $x \in \mathbb{R}$. Therefore, $f' \equiv 0$ as well. On the other hand, the sequence $(f'_n)(x) = (n\cos(n^2x))_{n \in \mathbb{N}}$ is divergent for all $x \in \mathbb{R}$. This means that the assumption b) of Theorem 4.7 is indispensable.

To conclude this section, we consider criteria for the uniform convergence of series of functions.

4.9 Theorem (Weierstraß M-test (Weierstraßsches Konvergenzkriterium)). Let $f_n: D \to \mathbb{K}$ for $n \in \mathbb{N}$ be a sequence of functions with $\sum_{n=0}^{\infty} ||f_n||_{\infty} < \infty$. Then the series of functions $\sum_{n=0}^{\infty} f_n$ converges uniformly, i.e., the sequence of partial sums converges uniformly.

The proof is left as an exercise.

The above criterion has important applications for power series. In particular, we have the following corollary.

4.10 Corollary. A power series $\sum_{n=0}^{\infty} a_n x^n$ with radius $\rho > 0$ of convergence converges absolutely and uniformly on $\overline{U_r(0)} := \{z \in \mathbb{C} : |z| \leq r\}$ for each $r \in (0, \rho)$.

Indeed, we know from earlier results about power series that $\sum_{n=0}^{\infty} |a_n| r^n$ converges. Considering the function $f_n : \overline{U_r(0)} \to \mathbb{C}$ given by $f_n(x) := a_n x^n$, we know that $||f_n||_{\infty} \leq |a_n| r^n$ and the claim follows from the Weierstraß M-test 4.9.

An immediate consequence is that power series define continuous functions in the interior of their disc of convergence.

- **4.11 Corollary.** A power series with radius $\rho > 0$ of convergence defines a continuous function on $U_{\rho}(0)$.
- **4.12 Examples.** a) The series

$$\sum_{n=1}^{\infty} \frac{\cos(nx)}{n^2}$$

converges absolutely and uniformly on \mathbb{R} , because we have $\left|\frac{\cos(n\cdot x)}{n^2}\right| \leq \frac{1}{n^2}$ for all $x \in \mathbb{R}$.

b) The Riemann Zeta function ζ , given by

$$\zeta(z) := \sum_{n=1}^{\infty} \frac{1}{n^z}$$

converges absolutely and uniformly on the set $\{z \in \mathbb{C} : \Re z \geq \alpha\}$ when $\alpha > 1$, since $\left|\frac{1}{n^z}\right| = \left|\frac{1}{n^{\Re z}}\right| \leq \frac{1}{n^{\alpha}}$.

Finally we consider the question whether a function that is given by a power series is differentiable. We begin with a lemma.

4.13 Lemma. Let $\sum_{n=0}^{\infty} a_n x^n$ be a power series with radius $\varrho > 0$ of convergence. Then the formal derivative

$$\sum_{n=1}^{\infty} n a_n x^{n-1}$$

has radius ϱ of convergence.

The proof is left as an exercise.

4.14 Theorem. Let $f(x) = \sum_{n=0}^{\infty} a_n x^n$ be a power series with radius $\rho > 0$ of convergence. Then $f: (-\varrho, \varrho) \to \mathbb{K}$ is differentiable and we have

$$\left(\sum_{n=0}^{\infty} a_n x^n\right)' = f'(x) = \sum_{n=1}^{\infty} n a_n x^{n-1} = \sum_{n=0}^{\infty} (a_n x^n)', \quad x \in (-\varrho, \varrho),$$

i.e. power series can be differentiated termwise.

The proof is a consequence of Corollary 4.10 and Theorem 4.7.

For |x| < 1 consider the following example:

$$\sum_{n=1}^{\infty} nx^n = x \sum_{n=1}^{\infty} nx^{n-1} = x \frac{d}{dx} \sum_{n=0}^{\infty} x^n = x \frac{d}{dx} \frac{1}{(1-x)} = \frac{x}{(1-x)^2}.$$

If we iterate the statement of the above theorem, we obtain the following strengthening of Theorem 4.14.

4.15 Corollary. Let $f(x) = \sum_{n=0}^{\infty} a_n x^n$ be a power series with radius $\rho > 0$ of convergence. Then $f: (-\varrho, \varrho) \to \mathbb{K}$ is arbitrarily often differentiable and we have

$$a_n = \frac{f^{(n)}(0)}{n!}$$
 for all $n \in \mathbb{N}_0$.

We conclude the section with Abel's theorem, which we cite without proof.

4.16 Theorem (Abel's theorem (Abelscher Grenzwertsatz)). Let $\sum_{n=0}^{\infty} a_n$ be a convergent series. Then the power series

$$f(x) := \sum_{n=0}^{\infty} a_n x^n$$

converges uniformly for $x \in [0,1]$ and therefore defines a continuous function $f:[0,1] \to \mathbb{K}$.

4.17 Example. We calculate the power series expansion of the arctan-function, given by

$$\arctan(x) = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{2n+1}, \quad x \in (-1,1).$$

The series $\sum_{n=0}^{\infty} (-1)^n \frac{1}{2n+1}$ converges by the Leibniz criterion. Therefore, by Abel's theorem we have

$$\frac{\pi}{4} \stackrel{\text{III.4}}{=} \arctan(1) \stackrel{\text{Abel}}{=} \sum_{n=0}^{\infty} (-1)^n \frac{1}{2n+1} = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \cdots$$

Chapter V

Integration in one Variable

The calculation of areas, volumes, and lengths of curves belongs to the oldest mathematical problems. Today these questions — having remained as relevant as ever — form the central motivations for modern integration theory.

To ARCHIMEDES (287-212 B.C.), it was evident, that a figure that is bounded by curved lines has a well defined area. To determine this area, it was approximated 'from inside' and 'from outside' by easier objects with known area.

The systematic investigation of the integral concept began only much later with the discovery of the connection between differentiation and integration by G.W. LEIBNIZ (1646-1716) and I. NEWTON (1642-1727) in the 17th century. A. L. CAUCHY, in his famous textbook *Calcul infinitésimal*, was the first to point out the necessity of a definition of the integral and, building on this, of a development of the theory of integration. B. RIEMANN (1826-1866) extended this concept to a bigger class of functions. A different, but very general concept of integral was finally introduced by H. L. LEBESGUE in the year 1902. We will examine Lebesgue's integral intensively in the lecture Analysis IV.

In this chapter, we restrict our attention at first on the integral for so-called jump continuous functions, a less general class of functions than that of Riemann integrable functions. The advantage of this approach is that we can first define the integral directly for so-called *step functions* and later extend this definition — via an approximation process — to more general functions.

We begin this chapter in Section 1 by defining step functions and jump continuous functions. The approximation theorem of jump continuous functions by step functions is the main result of this section and is the basis of our approach to the integral. Section 2 is devoted to the fundamental theorem of calculus and to the comparison of of our concept of integral with the so-called Riemann integral. Afterwards, in Section 3, we consider classical integration techniques such as partial integration and substitution, before we consider improper integrals in the last section.

1 Step functions and jump continuous functions

In this section, a and b are always real numbers with a < b, and I denotes the compact interval I := [a, b]. We begin with the notion of a partition of the interval I.

1.1 Definition. a) We call $Z := (x_0, \ldots, x_n)$ a partition of I, if

$$a = x_0 < x_1 < x_2 < \ldots < x_n = b$$

holds.

- b) A partition $\overline{Z} := (y_0, \dots, y_n)$ is called refinement of Z, if $\{x_0, \dots, x_n\} \subset \{y_0, \dots, y_k\}$. If this is the case, we also write $Z \subset \overline{Z}$.
- c) A function $f: I \to \mathbb{K}$ is called *step function (Treppenfunktion)*, if there exists a partition $Z = (x_0, \ldots, x_n)$ of I, such that f is constant on all intervals (x_{j-1}, x_j) , where $j = 1, \ldots, n$.
- d) A function $f: I \to \mathbb{K}$ is called jump continuous (sprungstetig) on I, if
 - i) f has one sided limits from the left and from the right at each $c \in (a, b)$, i.e., the limits

$$\lim_{x \to c-} f(x)$$
 and $\lim_{x \to c+} f(x)$

exist, and,

- ii) f has a limit from the right at a and a limit from the left at b.
- **1.2 Remarks.** a) The set of step functions

$$\mathcal{T}([a,b],\mathbb{K}) := \{ \varphi : [a,b] \to \mathbb{K} : \varphi \text{ is a step function on } [a,b] \}$$

as well as the set of jump continuous functions

$$\mathcal{S}([a,b],\mathbb{K}) := \{ \varphi : [a,b] \to \mathbb{K} : \varphi \text{ is jump continuous on } [a,b] \}$$

are vector spaces over \mathbb{K} . Further, $\mathcal{T}([a,b],\mathbb{K})$ is a linear subspace of $\mathcal{S}([a,b],\mathbb{K})$.

- b) Every continuous function on [a, b] is jump continuous.
- c) Every monotone function on [a, b] is jump continuous.
- d) If we define

$$C([a,b],\mathbb{K}) := \{f : [a,b] \to \mathbb{K} : f \text{ is continuous on } [a,b]\},$$

$$C^1([a,b],\mathbb{K}) := \{f: [a,b] \to \mathbb{K}: f \text{ is continuously differentiable on } [a,b]\},$$

$$B([a,b],\mathbb{K}) := \{f: [a,b] \to \mathbb{K}: f \text{ is bounded on } [a,b]\},\$$

then $C([a,b],\mathbb{K})$, $C^1([a,b],\mathbb{K})$ and $B([a,b],\mathbb{K})$ are also vector spaces over \mathbb{K} and we have

$$C^1([a,b],\mathbb{K}) \subset C([a,b],\mathbb{K}) \subset \mathcal{S}([a,b],\mathbb{K}) \subset B([a,b],\mathbb{K}),$$

where the inclusions are linear subspace inclusions.

We now define the integral for step functions.

1.3 Definition. Let $f:[a,b] \to \mathbb{K}$ be a step function and $Z=(x_0,\ldots,x_n)$ a partition of I. Furthermore assume that $f(x)=c_j$ for all $x\in(x_{j-1},x_j)$ and all $j=1,\ldots,n$. Then

$$\int_{Z} f := \sum_{j=1}^{n} c_{j}(x_{j} - x_{j-1})$$

is called the integral of f (with respect to Z).

First of all, we have to show that the integral $\int_Z f$ of a function f depends only on f and not on the chosen partition Z.

1.4 Lemma. Let Z and Z' be partitions of I and assume that f is a step function with respect to Z as well as Z'. Then we have

$$\int_{Z} f = \int_{Z'} f.$$

Proof. We prove the claim first for pairs of partitions partitions where one is a refinement of the other. In particular, consider the partitions $Z = (x_0, \ldots, x_n)$ and $Z' = (x_0, \ldots, x_k, y, x_{k+1}, \ldots, x_n)$ of I. Then we have

$$\int_{Z} f = \sum_{j=1}^{n} c_{j}(x_{j} - x_{j-1})$$

$$= \sum_{j=1}^{k} c_{j}(x_{j} - x_{j-1}) + \underbrace{c_{k+1}(x_{k+1} - x_{k})}_{=c_{k+1}(x_{k-1} - y) + c_{k+1}(y - x_{k})} + \sum_{j=k+2}^{n} c_{j}(x_{j} - x_{j-1}) = \int_{Z'} f.$$

If Z' is an arbitrary refinement of Z, then the claim follows by iteration of the above argument. If Z and Z' are arbitrary partitions of I, then $Z \cup Z'$ is a refinement of Z as well as Z'. Therefore,

$$\int_{Z} f = \int_{Z \cup Z'} f = \int_{Z'} f.$$

The above Lemma implies that we can now define the integral of a step function as

$$\int_I f := \int_a^b f(x) dx := \int_I f dx := \int_Z f.$$

The following properties of the inegral are immediately evident.

- **1.5 Lemma.** Assume that $\varphi, \psi \in \mathcal{T}([a,b], \mathbb{K})$ and $\alpha, \beta \in \mathbb{K}$. Then the following propositions hold:
 - a) $\int_{I} (\alpha \varphi + \beta \psi) = \alpha \int_{I} \varphi + \beta \int_{I} \psi$ (Linearity of the integral).
 - b) $\left| \int_{I} \varphi \right| = \left| \int_{a}^{b} \varphi(x) dx \right| \le (b a) \|\varphi\|_{\infty}$.
 - c) If φ and ψ are real valued with $\varphi \leq \psi$, we have $\int_I \varphi \leq \int_I \psi$ (Monotonicity of the integral).

In the following our aim is to extend the integral — which we have only defined for step functions up to now — to jump continuous functions in such a way that the above properties of the integral are preserved. To this end, the following approximation theorem for jump continuous functions is crucial.

1.6 Theorem. (Approximation theorem for jump continuous functions). A function $f:[a,b] \to \mathbb{K}$ is jump continuous on [a,b] if and only if there exists a sequence $(\varphi_n)_{n\in\mathbb{N}} \subset \mathcal{T}([a,b],\mathbb{K})$ of step functions on [a,b] such that $(\varphi_n)_{n\in\mathbb{N}}$ converges uniformly on [a,b] to f, i.e. if $||f - \varphi_n||_{\infty} \xrightarrow{n \to \infty} 0$ holds.

Proof. \Longrightarrow : Let $f \in \mathcal{S}([a,b],\mathbb{K})$ be a jump continuous function and $n \in \mathbb{N}$. Then for all $x \in I = [a,b]$ there exist real numbers α_x and β_x with $\alpha_x < x < \beta_x$ and

$$|f(s) - f(t)| < \frac{1}{n}, \quad s, t \in (\alpha_x, x) \cap I \text{ or } s, t \in (x, \beta_x) \cap I.$$

Now the set $\{(\alpha_x, \beta_x) : x \in I\}$ is an open cover of the compact interval [a, b]. Therefore there exists a finite subcover of I, i.e. there exist $x_0 < x_1 < \ldots < x_m$ with $I \subset \bigcup_{j=0}^m (\alpha_{x_j}, \beta_{x_j})$. If we set $y_0 := a, y_{j+1} := x_j$ for $j = 0, \ldots, m$, as well as $y_{m+2} := b$, we obtain a partition $Z_0 = (y_0, \ldots, y_{m+2})$ of I. Now we choose a refinement $Z_1 = (z_0, \ldots, z_k)$ of Z_0 with

$$|f(s) - f(t)| < \frac{1}{n}, \quad s, t \in (z_{j-1}, z_j), \quad j = 1, \dots, k$$

(from the construction of Z_0 it follows that this property can be obtained by inserting at most one additional point between each pair (y_{j-1}, y_j) of points of Z_0) and define the function φ_n approximating the function f by

$$\varphi_n(x) := \begin{cases} f(x), & x \in \{z_0, \dots, z_k\} \\ f(\frac{z_{j-1} + z_j}{2}), & x \in (z_{j-1}, z_j), \ j = 1, \dots, k. \end{cases}$$

Then φ_n is a step function on [a,b] for each $n \in \mathbb{N}$ and by construction we have $|f(x) - \varphi_n(x)| < \frac{1}{n}$ for all $x \in I$, i.e. we have $||f - \varphi_n||_{\infty} < \frac{1}{n}$ for all $n \in \mathbb{N}$.

 \Leftarrow : By assumption, $\varphi_n \in \mathcal{T}([a,b],\mathbb{K})$ and we have $\|\varphi_n - f\|_{\infty} < \frac{1}{n}$ for all $n \in \mathbb{N}$. We have to show that f is jump continuous. For $\varepsilon > 0$ we choose $n \in \mathbb{N}$ in such a way that we have $|f(x) - \varphi_n(x)| < \frac{\varepsilon}{2}$ for all $x \in I$. Further, since φ_n is a step function, there exists for all $x \in (a,b]$ an $a' \in [a,x)$ with $\varphi_n(s) = \varphi_n(t)$ for all $s,t \in (a',x)$. Therefore we have

$$|f(s) - f(t)| < |f(s) - \varphi_n(s)| + |\varphi_n(t) - f(t)| < \varepsilon$$
, for all $s, t \in (a', x)$.

Now assume that $(s_j)_{j\in\mathbb{N}}\subset I$ is such that $s_j\to x-$. Then there exists an $N\in\mathbb{N}$ such that $s_j\in(a',x)$ for all $j\geq N$ and thus

$$|f(s_j) - f(s_k)| < \varepsilon$$
, for all $j, k \ge N$.

Thus, $(f(s_j))_{j\in\mathbb{N}}$ is a Cauchy sequence with $\lim_{j\to\infty} f(s_j) = r$. If $(t_k)_{k\in\mathbb{N}}$ is another sequence as above, we have $\lim_{n\to\infty} f(t_n) = r'$. But since $|f(s_j) - f(t_k)| < \varepsilon$ for all j, k > N, we have r = r', and thus the limit from the left, $\lim_{y\to x^-} f(y)$, exists. The proof for the limit from the right is analogous.

1.7 Corollary. A function $f:[a,b] \to \mathbb{K}$ is jump continuous if and only if it can be written as

$$f = \sum_{n=1}^{\infty} \varphi_n \text{ with } \varphi_n \in \mathcal{T}([a,b],\mathbb{K}) \text{ such that } \sum_{n=1}^{\infty} \|\varphi_n\|_{\infty} < \infty \text{ holds.}$$

Proof. \Longrightarrow : By the above Theorem 1.6 we can choose a function $\psi_n \in \mathcal{T}([a,b],\mathbb{K})$ for each $n \in \mathbb{N}$ in such a way that $||f - \psi_n||_{\infty} \leq \frac{1}{2^n}$. If we further set $\varphi_1 := \psi_1$ and $\varphi_k := \psi_k - \psi_{k-1}$ for $k \geq 2$, we have

$$|f(x) - \sum_{j=1}^{n} \varphi_j(x)| = |f(x) - \psi_n(x)| \le ||f - \psi_n||_{\infty} \le \frac{1}{2^n},$$

and therefore $\sum_{j=1}^{\infty} \varphi_j(x) = f(x)$ for all $x \in [a, b]$. Further we have

$$\|\varphi_j\|_{\infty} \le \underbrace{\|\psi_j - f\|_{\infty}}_{\le \frac{1}{2^j}} + \underbrace{\|f - \psi_{j-1}\|_{\infty}}_{\le \frac{1}{2^{j-1}}} = \frac{3}{2^j},$$

and thus $\sum_{n=1}^{\infty} \|\varphi_n\|_{\infty} < \infty$.

 \Leftarrow : For $n \in \mathbb{N}$ we define $\psi_n := \sum_{j=1}^n \varphi_j$. Then $\psi_n \in \mathcal{T}([a,b],\mathbb{K})$ for all $n \in \mathbb{N}$ and we have

$$||f - \psi_n||_{\infty} = ||f - \sum_{j=1}^n \varphi_j||_{\infty} = ||\sum_{j=n+1}^\infty \varphi_j|| \le \sum_{j=n+1}^\infty ||\varphi_j||_{\infty} \stackrel{n \to \infty}{\longrightarrow} 0.$$

Thus, the claim follows from Theorem 1.6

1.8 Corollary. A jump continuous function $f \in \mathcal{S}([a,b],\mathbb{K})$ has at most countably many points of discontinuity. This holds in particular for monotone functions.

Proof. By the above Theorem 1.6, we can express f as a limit of a sequence $(\varphi_n)_{n\in\mathbb{N}}$ of step functions. By unfolding the ε - δ -definition of continuity, and applying a $\frac{\varepsilon}{3}$ -argument, it is easy to see that f is continuous at a given x whenever all φ_n are continuous at x. Thus, the points of discontinuity of f are contained in the union of the sets of points of discontinuity of all φ_n . This is a countable union of finite sets, hence at most countable.

2 The integral and its properties

In this section, let again $a, b \in \mathbb{R}$ with a < b and I = [a, b]. We consider the following situation: Let $f \in \mathcal{S}([a, b], \mathbb{K})$ be a jump continuous function which is approximated uniformly by a sequence $(\varphi_n)_{n \in \mathbb{N}} \subset \mathcal{T}([a, b], \mathbb{K})$ of step functions, as described in Theorem 1.6; i.e. we have $||f - \varphi_n||_{\infty} \xrightarrow{n \to \infty} 0$. If we set $I_n := \int_a^b \varphi_n$, we have

$$|I_n - I_m| \stackrel{1.5b}{\leq} (b - a) \|\varphi_n - \varphi_m\|_{\infty} \leq (b - a) (\|\varphi_n - f\|_{\infty} + \|f - \varphi_m\|_{\infty}) \stackrel{n \to \infty}{\longrightarrow} 0,$$

i.e., $(I_n)_{n\in\mathbb{N}}$ is a Cauchy sequence and thus convergent. Let further $(\psi_n)_{n\in\mathbb{N}}\subset\mathcal{T}([a,b],\mathbb{K})$ be another sequence of step functions with $\|\psi_n-f\|_{\infty}\stackrel{n\to\infty}{\longrightarrow} 0$. If we consider the sequence $\varphi_1,\psi_1,\varphi_2,\psi_2,\ldots=:(g_n)_{n\in\mathbb{N}}$ of step functions, we have $\|f-g_n\|_{\infty}\stackrel{n\to\infty}{\longrightarrow} 0$. Thus, the sequence $(\int_a^b g_n)_{n\in\mathbb{N}}$ converges and the subsequences $(\int_a^b \varphi_n)_{n\in\mathbb{N}}$ and $(\int_a^b \psi_n)_{n\in\mathbb{N}}$ have the same limit. These considerations show that we have the following result.

2.1 Theorem and Definition. Let $f \in \mathcal{S}([a,b],\mathbb{K})$ and $\varphi_n \in \mathcal{T}([a,b],\mathbb{K})$ for all $n \in \mathbb{N}$ with $||f - \varphi_n||_{\infty} \xrightarrow{n \to \infty} 0$. Then the limit

$$\lim_{n \to \infty} \int_a^b \varphi_n(x) dx =: \int_a^b f(x) dx.$$

exists and is independent of the choice of φ_n . This limit is called the integral of f on [a,b].

In the following, we also use the notations $\int f$, $\int_I f$ or $\int_I f(x) dx$ for the integral of a jump continuous function f. Since continuous functions and monotone functions are jump continuous, the following corollary is immediately evident:

2.2 Corollary. The integral $\int_a^b f(x)dx$ exists for every continuous and every monotone (real-valued) function f on [a,b].

On the other hand, we remark that not every function on [a, b] is integrable. A counterexample is the Dirichlet function already known from Chapter III. More precisely, the integral of the function f, given by

$$f(x) = \begin{cases} 1, & x \in \mathbb{Q} \cap [0, 1] \\ 0, & x \in \mathbb{R} \setminus \mathbb{Q} \cap [0, 1] \end{cases}$$

does not exist.

2.3 Theorem. Let $\alpha, \beta \in \mathbb{K}$ and $f, g \in \mathcal{S}([a, b], \mathbb{K})$. Then we have

- a) $\int_a^b (\alpha f + \beta g) = \alpha \int_a^b f + \beta \int_a^b g$ (Linearity of the integral).
- b) $|f| \in \mathcal{S}([a,b],\mathbb{R})$ and

$$\left| \int_a^b f \right| \le \int_a^b |f| \le (b-a) ||f||_{\infty}.$$

c) If we have $f \leq g$, i.e. $f(x) \leq g(x)$ for all $x \in [a, b]$, we also have

$$\int_{a}^{b} f \leq \int_{a}^{b} g, \quad (Monotonicity of the integral).$$

Proof. Assume that $\varphi_n, \psi_n \in \mathcal{T}([a, b], \mathbb{K})$ are step functions for all $n \in \mathbb{N}$, and $(\varphi_n)_{n \in \mathbb{N}}$ and $(\psi_n)_{n \in \mathbb{N}}$ converge uniformly to f and g, respectively.

Then $(\alpha \varphi_n + \beta \psi_n)$ converges uniformly to $\alpha f + \beta g$ and we have

$$\int_{a}^{b} (\alpha f + \beta g) = \lim_{n \to \infty} \left(\int_{a}^{b} (\alpha \varphi_{n} + \beta \psi_{n}) \right) =$$

$$\alpha \left(\lim_{n \to \infty} \int_{a}^{b} \varphi_{n} \right) + \beta \left(\lim_{n \to \infty} \int_{a}^{b} \psi_{n} \right) = \alpha \int_{a}^{b} f + \beta \int_{a}^{b} g,$$

which is claim a).

b) Since the sequence $(|\varphi_n|)_{n\in\mathbb{N}}$ converges uniformly to |f|, and since $|f| \in \mathcal{S}([a,b],\mathbb{R})$ (compare Theorem 1.6), it follows that $\int |f| \stackrel{\text{Thm.2.1}}{=} \lim_{n\to\infty} \int |\varphi_n|$. Thus,

$$\left| \int f \right| = \left| \lim_{n \to \infty} \int \varphi_n \right| = \lim_{n \to \infty} \left| \int \varphi_n \right| \le \lim_{n \to \infty} \int |\varphi_n| \le \lim_{n \to \infty} \|\varphi_n\|_{\infty} |b - a| = \|f\|_{\infty} (b - a).$$

c) Assume that φ_n and ψ_n are real valued step functions on [a,b]. Then $\Phi_n := \varphi_n - ||f - \varphi_n||_{\infty}$ and $\Psi_n := \psi_n + ||g - \psi_n||_{\infty}$ are also step functions on [a,b] with $\Phi_n \leq f \leq g \leq \Psi_n$ and $(\Phi_n)_{n \in \mathbb{N}}$ and $(\Psi_n)_{n \in \mathbb{N}}$ converge uniformly to f and g, respectively. Thus, we have

$$\int_{a}^{b} f = \lim_{n \to \infty} \int_{a}^{b} \Phi_{n} \le \lim_{n \to \infty} \int_{a}^{b} \Psi_{n} = \int_{a}^{b} g.$$

We now consider a jump continuous function $f \in \mathcal{S}([a,b],\mathbb{K})$, real numbers $c,d \in [a,b]$ and define

$$\int_{c}^{d} f := \int_{c}^{d} f(x) dx := \begin{cases} \int_{[c,d]} f, & c < d \\ 0, & c = d \\ -\int_{[d,c]} f, & d < c. \end{cases}$$

In particular, we have

$$\int_{c}^{d} f = -\int_{d}^{c} f.$$

2.4 Lemma. (Additivity of the integral). Let $f \in \mathcal{S}([a,b],\mathbb{K})$ and $c \in [a,b]$. Then we have

$$\int_{a}^{b} f = \int_{a}^{c} f + \int_{c}^{b} f.$$

Proof. Let $a \leq c \leq b$. Then the claim is obviously true for all step functions $f \in \mathcal{T}([a,b],\mathbb{K})$. Therefore, we consider a sequence $(\varphi_n)_{n\in\mathbb{N}} \subset \mathcal{T}([a,b],\mathbb{K})$ which converges uniformly on [a,b] to f. Then $\varphi_n|_J \in \mathcal{T}(J,\mathbb{K})$ and $(\varphi_n|_J)_{n\in\mathbb{N}}$ converges uniformly to $f|_J$ for each compact subinterval J of [a,b]. Since $\int_a^b \varphi_n = \int_a^c \varphi_n + \int_c^b \varphi_n$, it follows that $\int_a^b f = \int_a^c f + \int_c^b f$.

2.5 Lemma. Let $f \in \mathcal{S}([a,b],\mathbb{R})$ be a jump continuous function with $f(x) \geq 0$ for all $x \in [a,b]$. If f is continuous at $c \in [a,b]$ and f(c) > 0, it follows that $\int_a^b f > 0$.

Proof. First, let a < c < b. Since f in continuous at c by assumption, there exists a $\delta > 0$ with $[c - \delta, c + \delta] \subset [a, b]$ and

$$f(x) \ge \frac{1}{2}f(c)$$
, for all $x \in [c - \delta, c + \delta]$.

Since $f \geq 0$, the monotonicity of the integral (Theorem 2.3) implies that $\int_a^{c-\delta} f \geq 0$ and $\int_{c+\delta}^b f \geq 0$. Therefore we have

$$\int_a^b f \stackrel{2.4}{=} \int_a^{c-\delta} f + \int_{c-\delta}^{c+\delta} f + \int_{c+\delta}^b f \ge \int_{c-\delta}^{c+\delta} f \ge \frac{1}{2} f(c) \int_{c-\delta}^{c+\delta} 1 = \delta f(c) > 0.$$

The proof for the cases c = a and c = b is similar.

2.6 Theorem (Mean value theorem for integrals (Mittelwertsatz für das Integral)). Let $f \in C([a,b],\mathbb{R}), \varphi \in \mathcal{S}([a,b],\mathbb{R})$ with f being real valued and $\varphi \geq 0$. Then there exists a point $\xi \in [a,b]$ with

$$\int_{a}^{b} f(x)\varphi(x)dx = f(\xi)\int_{a}^{b} \varphi(x)dx.$$

Proof. Because f is continuous on a compact interval, there exist $m, M \in [a, b]$ such that $f(m) = \min_{x \in [a,b]} f(x)$ and $f(M) = \max_{x \in [a,b]} f(x)$. Since $\varphi \ge 0$, we have

$$f(m)\varphi(x) \le f(x)\varphi(x) \le f(M)\varphi(x),$$

and by the monotonicity of the integral

$$f(m) \int_{a}^{b} \varphi(x) dx \le \int_{a}^{b} f(x) \varphi(x) dx \le f(M) \int_{a}^{b} \varphi(x) dx.$$

Now the function $g(t) := f(t) \int_a^b \varphi(x) dx$ is continuous, whence by the intermediate value theorem there exists a ξ between m and M such that $f(\xi) \int_a^b \varphi(x) dx = \int_a^b f(x) \varphi(x) dx$. This is precisely the claim.

If we consider the above theorem for the particular case $\varphi \equiv 1$, we obtain the following corollary.

2.7 Corollary. To each $f \in C([a,b],\mathbb{R})$ there exists a point $\xi \in [a,b]$ such that

$$\int_{a}^{b} f(x)dx = f(\xi)(b-a).$$

Now, for $f \in \mathcal{S}([a,b],\mathbb{K})$ we consider the mapping

$$F:[a,b]\to\mathbb{K},\quad F(x):=\int_a^x f(s)ds.$$

Then the additivity of the integral implies

$$F(x) - F(y) = \int_a^x f(s)ds - \int_a^y f(s)ds = \int_y^x f(s)ds, \quad \text{for all } x, y \in [a, b].$$

Now Theorem 2.3 b) immediately implies the estimate

$$|F(x) - F(y)| \le ||f||_{\infty} |x - y|, \quad x, y \in [a, b].$$

2.8 Theorem. (Differentiability of the integral by the upper bound). Assume that $f \in \mathcal{S}([a,b],\mathbb{K})$ is continuous at $c \in [a,b]$ and let $F : [a,b] \to \mathbb{K}$ be defined by

$$F(x) := \int_{-\infty}^{x} f(s)ds.$$

Then F is differentiable in c and we have F'(c) = f(c).

Proof. Let $h \neq 0$ such that $c + h \in [a, b]$. Then we have

$$\frac{F(c+h) - F(c)}{h} = \frac{1}{h} \left(\int_a^{c+h} f(s) ds - \int_a^c f(s) ds \right) \stackrel{\text{Add.}}{=} \frac{1}{h} \int_c^{c+h} f(s) ds.$$

Since $\int_{c}^{c+h} f(c)ds = f(c)h$, we have

$$\frac{F(c+h) - F(c) - f(c)h}{h} = \frac{1}{h} \int_{c}^{c+h} (f(s) - f(c))ds,$$

and thus

$$\left|\frac{F(c+h) - F(c) - f(c)h}{h}\right| \leq \frac{1}{|h|} \int_{c}^{c+h} |f(s) - f(c)| ds \leq \sup_{s \in [c,c+h]} |f(s) - f(c)| \xrightarrow{h \to 0} 0,$$

since f is continuous in c. Therefore, F is differentiable in c and we have F'(c) = f(c).

We summarize our previous considerations in the following fundamental theorem of calculus.

2.9 Theorem. (Fundamental Theorem of calculus (Hauptsatz der Differential- und Integralrechnung)). Let $f:[a,b] \to \mathbb{K}$ be a continuous function and for $c \in [a,b]$ let

$$F(x) := \int_{c}^{x} f(s)ds, \quad x \in [a, b].$$

Then we have

- a) F is differentiable for all $x \in [a, b]$ and we have F'(x) = f(x) for all $x \in [a, b]$.
- b) If $\phi:[a,b]\to\mathbb{K}$ is a differentiable function with $\phi'(x)=f(x)$ for all $x\in[a,b]$, we have

$$\phi(x) = \phi(y) + \int_{y}^{x} f(s)ds, \quad x, y \in [a, b].$$

Proof. Claim a) follows directly from Theorem 2.8. To show claim b), let F and ϕ as in the assumption. Then we have $(F - \phi)' = 0$, thus $F = \phi + \alpha$ for a constant $\alpha \in \mathbb{C}$. Therefore,

$$\int_{y}^{x} f(s) \, ds = F(x) - F(y) = \phi(x) + \alpha - \phi(y) - \alpha = \phi(x) - \phi(y).$$

2.10 Definition.

Let $f \in \mathcal{S}([a,b],\mathbb{K})$. A differentiable function $F:[a,b] \to \mathbb{K}$ with F'(x)=f(x) for all $x \in [a,b]$ is called *antiderivative (Stammfunktion)* of f.

The above fundamental theorem of calculus implies the following corollary.

2.11 Corollary. Every continuous function $f : [a, b] \to \mathbb{K}$ has an antiderivative F and we have:

 $\int_{u}^{x} f(s) \, ds = F(x) - F(y) =: F \Big|_{y}^{x}, \quad x, y \in [a, b].$

Thus, the above corollary guarantees the existence of antiderivatives for continuous functions. However, we remark that in the most cases, it is not possible to give an explicit definition of antiderivatives.

2.12 Examples. a) In the following table, we collect examples of functions f for which antiderivatives F can be given explicitly.

f(x)	F(x)
x^a	$\frac{x^{a+1}}{a+1}, \ a \neq -1$
$\frac{1}{x}$	$\log x $
e^{x}	e^x
$\cos x$	$\sin x$
$\frac{1}{\cos^2 x}$	$\tan x$
$\frac{1}{1+x^2}$	$\arctan x$
$\frac{1}{\sqrt{1-x^2}}$	$\arcsin x$

b) If $f:(a,b)\to\mathbb{R}$ is differentiable and $f(x)\neq 0$ for all $x\in(a,b)$, we have

$$\int \frac{f'}{f} = \log|f|.$$

In analogy to the previous section we now consider a sequence of jump continuous functions $(f_n)_{n\in\mathbb{N}}$, which converge uniformly to a function f on [a,b], and ask whether f is in turn integrable (i.e. jump continuous). The answer is given by the following theorem.

2.13 Theorem. Let $(f_n)_{n\in\mathbb{N}}\subset \mathcal{S}([a,b],\mathbb{K})$ be a sequence of jump continuous functions which converge uniformly to f on [a,b]. Then $f\in \mathcal{S}([a,b],\mathbb{K})$ and we have

$$\lim_{n \to \infty} \int_a^b f_n(x) \, dx = \int_a^b f(x) \, dx.$$

Proof. For given $\varepsilon > 0$ we choose $n \in \mathbb{N}$ so big, that $||f - f_n||_{\infty} \le \varepsilon/2$, and for given f_n , we choose a step function φ with $||f_n - \varphi||_{\infty} \le \varepsilon/2$. Then we have $||f - \varphi|| \le \varepsilon$ and thus $f \in \mathcal{S}([a, b], \mathbb{K})$. Furthermore, we have

$$\left| \int_a^b f(x) \, dx - \int_a^b f_n(x) \, dx \right| \le \|f - f_n\|(b - a) \le \varepsilon(b - a),$$

and this is the proposition.

2.14 Remark. The above Theorem 2.13 allows to give an easy and elegant proof of Theorem IV.4.7. First of all, the limit function $f^* = \lim_{n\to\infty} f'_n$ of the derivatives is continuous on [a,b] by Theorem IV.4.6. For fixed $a\in I$ and arbitrary $x\in I$ we have

$$f_n(x) = f_n(a) + \int_a^x f'_n(t)dt,$$

and thus, by Theorem 2.13, we have

$$f(x) = f(a) + \int_{a}^{x} f^{*}(t)dt$$

for $n \to \infty$. By the fundamental theorem of calculus, f is differentiable and we have $f'(x) = f^*(x) = \lim_{n \to \infty} f'_n(x)$.

In the following, we consider the approximation of the integral by so-called Riemann sums

2.15 Definition. Assume that $f:[a,b] \to \mathbb{K}$ is a function, $Z:=(x_0,\ldots,x_n)$ is a partition of the interval [a,b] and $\xi_j \in [x_{j-1},x_j]$ for $j \in \{1,\ldots,n\}$. Then

$$\sum_{j=1}^{n} f(\xi_j) (x_j - x_{j-1})$$

is called the *Riemann sum* (*Riemann Summe*) of f with respect to Z. The norm (Feinheit) of the partition Z is defined as $||Z|| := \max_{1 \le j \le n} (x_j - x_{j-1})$.

We have the following theorem.

2.16 Theorem. Let $f \in \mathcal{S}([a,b],\mathbb{K})$ be a jump continuous function. Then to each $\varepsilon > 0$ there exists some $\delta > 0$, such that for every partition Z of [a,b] with norm $\|Z\| < \delta$ and every choice of points $\xi_j \in [x_{j-1},x_j]$ we have

$$\left| \sum_{j=1}^{n} f(\xi_j)(x_j - x_{j-1}) - \int_a^b f(x) dx \right| < \varepsilon.$$

Proof. First, we show the claim for step functions φ via induction on the number m of discontinuities of φ . Then we deduce the claim for general jump continuous functions using the approximation theorem (1.6).

a) Let $\varphi \in \mathcal{T}([a,b],\mathbb{K})$ be a step function and $\varepsilon > 0$. If we have $\varphi = c$ for all $x \in [a,b]$ and a $c \in \mathbb{K}$, the claim follows immediately. If φ has exactly one discontinuous point, the claim follows easily by setting $\delta := \frac{\varepsilon}{4||\varphi||}$.

For the induction step assume that the proposition holds for step functions with m discontinuities and consider a step function φ with m+1 discontinuous points. We then decompose φ into $\varphi = \varphi' + \varphi''$, where φ' is a step function with m discontinuities and φ'' is a step function with exactly one discontinuities. For a given $\varepsilon > 0$ we choose a $\delta'(\varepsilon/2)$ for φ' and a $\delta''(\varepsilon/2)$ for φ'' in such a way that the proposition holds for φ' and φ'' ; if we then set $\delta = \min(\delta', \delta'')$ the proposition also holds for φ .

b) For $f \in \mathcal{S}([a,b],\mathbb{K})$ choose $\varphi \in \mathcal{T}([a,b],\mathbb{K})$ with $||f - \varphi||_{\infty} < \frac{\varepsilon}{3(b-a)}$ and $\delta := \delta(\frac{\varepsilon}{3})$. By a), we have $|\sum_{j=1}^{n} \varphi(\xi_j)(x_j - x_{j-1}) - \int_a^b \varphi dx| < \frac{\varepsilon}{3}$; therefore,

$$\left| \sum_{j=1}^{n} f(\xi_{j})(x_{j} - x_{j-1}) - \int_{a}^{b} f \, dx \right| \leq \left| \sum_{j=1}^{n} f(\xi_{j})(x_{j} - x_{j-1}) - \sum_{j=1}^{n} \varphi(\xi_{j})(x_{j} - x_{j-1}) \right|$$

$$+ \left| \sum_{j=1}^{n} \varphi(\xi_{j})(x_{j} - x_{j-1}) - \int_{a}^{b} \varphi \, dx \right|$$

$$< \sum_{j=1}^{n} \|f - \varphi\|_{\infty} (x_{j} - x_{j-1}) + \frac{\varepsilon}{3} + \frac{\varepsilon}{3} < \varepsilon$$

2.17 Corollary. Let Z_1, Z_2, \ldots , be a sequence of partitions of the interval [a, b] with $||Z_n|| \to 0$, $n \to \infty$. Let $f \in \mathcal{S}([a, b], \mathbb{K})$ and S_n be the corresponding sequence of Riemann sums. Then we have

 $\lim_{n \to \infty} S_n = \int_a^b f.$

2.18 Remarks. a) A function $f:[a,b]\to\mathbb{C}$ is called *Riemann integrable* if there exists a $c\in\mathbb{C}$ with the following property: To each $\varepsilon>0$ there exists a $\delta>0$ such that

$$\left|c - \sum_{j=1}^{n} f(\xi_j)(x_j - x_{j-1})\right| < \varepsilon$$

for every partition $Z := (x_0, \ldots, x_n)$ with norm $||Z|| < \delta$ and every choice of $\xi_j \in [x_{j-1}, x_j]$.

- b) The above Theorem 2.16 says that every jump continuous function $f \in \mathcal{S}([a,b],\mathbb{K})$ is Riemann integrable and the Riemann integral coincides with our integral for these functions.
- c) There exist Riemann-integrable functions which are not jump continuous.

The above Corollary 2.17 allows in many cases to transfer statements about sums to integrals. As an example consider the Hölder inequality for integrals. To this end define

$$||f||_p := \left(\int_a^b |f(x)|^p dx\right)^{1/p}$$

for $f \in \mathcal{S}([a, b], \mathbb{K})$ and 1 . Then the following inequality holds.

2.19 Corollary. For $f, g \in \mathcal{S}([a, b], \mathbb{K})$ and $1 < p, q < \infty$ we have

$$\int_a^b |f(x)g(x)| \, dx \le ||f||_p ||g||_q \,, \quad \frac{1}{p} + \frac{1}{q} = 1.$$

For p = q = 2, this is the Cauchy-Schwarz inequality for integrals.

3 Integration techniques

The fundamental theorem of calculus from the previous section allows to transfrom the product rule and the substitution rule from differential calculus into very useful integration techniques. We start this relatively short section with the substitution rule. In the entire section, let $I \subset \mathbb{R}$ be a compact interval and $a, b \in \mathbb{R}$ with a < b.

3.1 Theorem (Substitution rule). (Substitutions regel) Let $f \in C(I, \mathbb{K})$ and $\varphi \in C^1([a, b], \mathbb{R})$ with $\varphi([a, b]) \subset I$. Then we have

$$\int_a^b f(\varphi(x))\varphi'(x) dx = \int_{\varphi(a)}^{\varphi(b)} f(y) dy.$$

Proof. By the fundamental theorem, f has an antiderivative $F \in C^1(I, \mathbb{K})$. The chain rule implies that $F \circ \varphi \in C^1([a, b], \mathbb{K})$ and that

$$(F \circ \varphi)'(x) = F'(\varphi(x))\varphi'(x) = f(\varphi(x))\varphi'(x), \quad x \in [a, b].$$

Therefore,

$$\int_{a}^{b} f(\varphi(x))\varphi'(x) dx = (F \circ \varphi)\big|_{a}^{b} = F(\varphi(b)) - F(\varphi(a)) = F\big|_{\varphi(a)}^{\varphi(b)} = \int_{\varphi(a)}^{\varphi(b)} f(y) dy.$$

3.2 Examples. a) For $\alpha > 0$ and $\beta \in \mathbb{R}$ we have

$$\int_{a}^{b} \cos(\alpha x + \beta) dx = \frac{1}{\alpha} \int_{\alpha a + \beta}^{\alpha b + \beta} \cos u \, du = \frac{1}{\alpha} \sin \Big|_{\alpha a + \beta}^{\alpha b + \beta} = \frac{1}{\alpha} (\sin(\alpha b + \beta) - \sin(\alpha a + \beta)).$$

b) We have

$$\int_0^1 x^{n-1} \sin(x^n) \, dx = \frac{1}{n} \int_0^1 \sin u \, du = -\frac{\cos u}{n} \Big|_0^1 = \frac{1}{n} (1 - \cos 1).$$

3.3 Theorem (Integration by parts). (Partielle Integration) For functions $f, g \in C^1([a, b], \mathbb{K})$ we have

$$\int_a^b fg' dx = (fg)\Big|_a^b - \int_a^b f'g dx.$$

3. INTEGRATION TECHNIQUES

The proof is easy. By the product rule, we have (fg)' = f'g + fg'; and thus

$$\int_{a}^{b} (fg)'dx = \int_{a}^{b} f'gdx + \int fg'dx.$$

3.4 Examples. a) We have

$$\int_{a}^{b} x e^{x} dx = x e^{x} \Big|_{a}^{b} - \int_{a}^{b} e^{x} dx = b e^{b} - a e^{a} - [e^{b} - e^{a}].$$

b) We identify a recursion formula $I_n = \int \sin^n x dx$ for $n \ge 2$ as follows: We have

$$I_n = \int \sin x \cdot \sin^{n-1} x dx = -\cos x \sin^{n-1}(x) + (n-1) \int \cos x \sin^{n-2} x \cos x dx$$

$$= -\cos x \sin^{n-1} x + (n-1) \int (1 - \sin^2 x) \sin^{n-2} x dx$$

$$= -\cos x \sin^{n-1} x + (n-1)I_{n-2} - (n-1)I_n$$

and thus

$$I_n = \frac{n-1}{n} I_{n-2} - \frac{1}{n} \cos x \sin^{n-1} x,$$

where $I_0 = \int \sin^0 x = \int 1 dx = x$ and $I_1 = \int \sin x = -\cos x$.

c) $Wallis' \ product \ (Wallissches \ Produkt - cf. \ exercises)$: We have

$$\frac{\pi}{2} = \prod_{i=1}^{\infty} \frac{4j^2}{4j^2 - 1}.$$

For the proof, consider $A_n = \int_0^{\frac{\pi}{2}} \sin^n x \, dx$.

3.5 Example. Area of the unit circle

Consider the function $f: [-1,1] \to \mathbb{R}$ given by $x \mapsto \sqrt{1-x^2}$. If we define $A = \int_{-1}^{1} \sqrt{1-x^2} \, dx$ and substitute $x = \cos t$, we obtain

$$A = -\int_{\pi}^{0} \sqrt{1 - \cos^{2} t} \sin t \, dt = \int_{0}^{\pi} \sin^{2} t \, dt = -\sin t \cos t \Big|_{0}^{\pi} + \int_{0}^{\pi} \cos^{2} t \, dt$$
$$= \int_{0}^{\pi} (1 - \sin^{2} t) \, dt = \pi - \int_{0}^{\pi} \sin^{2} t \, dt$$

by partial integration, and by the previous example we know

$$\int_0^\pi \sin^2 t dt = \frac{\pi}{2}.$$

Hence, the area of the unit circle is $2 \cdot \frac{\pi}{2} = \pi$.

4 Improper integrals

With our current concept of integral, we can integrate jump continuous functions which are defined on a compact interval I = [a, b].

In this section, we want to extend this concept of integral in order to integrate functions on arbitrary (not necessarily compact) intervals of the real line. This leads to the concept of *improper integrals*.

In the entire section we assume $-\infty \le a < b \le \infty$. We call a function $f:(a,b) \to \mathbb{C}$ admissible, , if the restriction of f to each compact subinterval of (a,b) is jump continuous. It is clear that a continuous function $f:(a,b) \to \mathbb{K}$ is admissible; likewise $f \in \mathcal{S}((a,b),\mathbb{K})$ is admissible if $a,b \in \mathbb{R}$, and |f| is admissible if $f:(a,b) \to \mathbb{K}$ is admissible.

4.1 Definition. An admissible function $f:(a,b)\to\mathbb{C}$ is called *improperly integrable*, if there exists a constant $c\in(a,b)$ such that the limits

$$\lim_{\alpha \to a+} \int_{\alpha}^{c} f \quad \text{and} \quad \lim_{\beta \to b-} \int_{c}^{\beta} f$$

exist.

We remark at this point that for an improperly integrable function f the above limits exist for all $c \in (a, b)$.

4.2 Definition. Assume that $f:(a,b)\to\mathbb{K}$ is improperly integrable and $c\in(a,b)$. Then

$$\int_{a}^{b} f \, dx := \int_{a}^{b} f(x) \, dx := \lim_{\alpha \to a+} \int_{\alpha}^{c} f \, dx + \lim_{\beta \to b-} \int_{c}^{\beta} f \, dx$$

is called the *improper integral* of f over (a, b).

4.3 Examples. a) For $\alpha \in \mathbb{R}$ we have

$$\int_{1}^{\infty} \frac{1}{x^{\alpha}} dx \text{ exists } \Leftrightarrow \alpha > 1.$$

To see this, we choose $\alpha \neq 1$. Then we have

$$\int_{1}^{b} \frac{1}{x^{\alpha}} dx = \frac{1}{1 - \alpha} x^{1 - \alpha} \Big|_{1}^{b} = \frac{1}{1 - \alpha} (b^{1 - \alpha} - 1),$$

and the above integral converges for $b \to \infty$ if and only if $\alpha > 1$. If $\alpha = 1$, we have $\int_1^b \frac{1}{x} dx = \log b$ which means that the limit $\lim_{b \to \infty} \int_1^b \frac{1}{x} dx$ does not

4. IMPROPER INTEGRALS

133

exist.

b) Analogously, one proves the following proposition:

$$\int_0^1 \frac{1}{x^{\alpha}} dx \text{ exists } \Leftrightarrow \alpha < 1.$$

c) We have

$$\int_0^\infty \frac{1}{1+x^2} \, dx = \frac{\pi}{2},$$

because the antiderivative of $x\mapsto \frac{1}{1+x^2}$ is given by $x\mapsto \arctan x$ and we have

$$\lim_{b \to \infty} \arctan x \big|_0^b = \frac{\pi}{2}.$$

d) For $\alpha > 0$ we have

$$\int_0^\infty e^{-\alpha x} dx = \frac{1}{\alpha},$$

because we have $\int_0^R e^{-\alpha x} dx = \frac{1}{\alpha} (1 - e^{-\alpha R}) \stackrel{R \to \infty}{\longrightarrow} \frac{1}{\alpha}$.

4.4 Theorem. (Comparison of integrals and series). Let $f:[1,\infty)\to\mathbb{R}_+$ be an admissible and monotone decreasing function. Then we have

$$\sum_{n=1}^{\infty} f(n) < \infty \quad \iff \quad \int_{1}^{\infty} f(x) \, dx \quad exists.$$

Proof. For $x \in [n-1,n]$ and $n \ge 2$, we have $f(n) \le f(x) \le f(n-1)$ by assumption. Therefore, $f(n) \le \int_{n-1}^n f(x) \, dx \le f(n-1)$ and thus

$$\sum_{n=2}^{N} f(n) \le \int_{1}^{N} f(x) \, dx \le \sum_{n=1}^{N-1} f(n), \quad N \ge 2.$$

Hence,

$$\int_{1}^{N} f(x) dx \le \sum_{n=1}^{N-1} f(n) \le \sum_{n=1}^{\infty} f(n)$$

and thus $\lim_{N\to\infty} \int_1^N f(x)\,dx$ exists whenever $\sum_{n=1}^\infty f(n)$ converges. To show the converse direction, we note that

$$\sum_{n=2}^{N} f(n) \le \int_{1}^{N} f(x) dx \le \int_{1}^{\infty} f(x) dx < \infty.$$

Thus, $(\sum_{n=1}^{N} f(n))_{N \in \mathbb{N}}$ is a monotone and bounded sequence, and this implies that $\sum_{n=1}^{\infty} f(n)$ converges.

As an example, consider the function $f:[1,\infty)\to\mathbb{R}_+$, given by $f(x)=\frac{1}{x^{\alpha}}$. In this case, the theorem yields

$$\sum_{n=1}^{\infty} \frac{1}{n^{\alpha}} \text{ is convergent} \quad \Leftrightarrow \quad \int_{1}^{\infty} \frac{1}{x^{\alpha}} \, dx \text{ exists} \quad \stackrel{4.3}{\Leftrightarrow} \quad \alpha > 1.$$

- **4.5 Definition.** An admissible function $f:(a,b)\to\mathbb{K}$ is called absolutely integrable (absolut integrierbar), if $\int_a^b |f(x)| dx$ exists.
- **4.6 Lemma.** An absolutely integrable function $f:(a,b)\to \mathbb{K}$ is integrable.

For the proof we refer to the exercises.

4.7 Theorem. (Comparison test for integrals). Assume that $f, g:(a,b) \to \mathbb{R}$ are admissible functions, such that we have

$$|f(x)| \le g(x), \quad x \in (a, b).$$

If g is integrable, then f is absolutely integrable.

For the proof we again refer to the exercises.

4.8 Example. The integral

$$\int_0^\infty \frac{\sin x}{x} dx$$

is convergent, but *not* absolutely convergent

To see this, we first of all observe that $\lim_{x\to 0} \frac{\sin x}{x} = 1$ (thus the integrand is continuous on the whole real line). Therefore, it suffices to examine the convergence of the integral $\int_1^\infty \frac{\sin x}{x} dx$. An integration by parts gives

$$\int_{1}^{R} \frac{\sin x}{x} dx = \cos 1 - \frac{\cos R}{R} - \int_{1}^{R} \frac{\cos x}{x^2} dx.$$

The integral $\int_1^\infty \frac{\cos x}{x^2} dx$ exists, since it is dominated by the convergent integral $\int_1^\infty \frac{1}{x^2} dx$. This means that the limit

$$\lim_{R \to \infty} \int_{1}^{R} \frac{\sin x}{x} dx$$

exists.

On the other hand, the integral $\int_1^\infty \frac{\sin x}{x} dx$ does not converge absolutely, since for each $k \in \mathbb{N}$ we have

$$\int_{k\pi}^{(k+1)\pi} |\frac{\sin x}{x}| \, dx \ge \frac{1}{(k+1)\pi} \int_{k\pi}^{(k+1)\pi} |\sin x| \, dx = \frac{2}{(k+1)\pi},$$

and therefore we have

$$\int_0^{(k+1)\pi} |\frac{\sin x}{x}| dx \ge \frac{2}{\pi} \sum_{n=0}^k \frac{1}{n+1}.$$

The latter expression is the harmonic series, whence the above limit does not exist for $k \to \infty$.

To conclude this section, we consider the gamma function and the beta function. Both functions are defined by improper integrals and represent important functions of analysis.

4.9 Example. (The gamma function).

We begin with the definition of the gamma function. For $z \in \mathbb{C}$ with Re(z) > 0 we define

$$\Gamma(z) := \int_0^\infty t^{z-1} e^{-t} dt.$$

This function was introduced by Euler, whose motivation was to interpolate the factorial function $n \mapsto n!$, defined for $n \in \mathbb{N}$. First of all, we show that the gamma function is well defined.

For $t \in (0,1]$ we have the estimate

$$|t^{z-1}e^{-t}|=t^{Re(z)-1}e^{-t}\leq t^{Re(z)-1},$$

and by Example 4.3b) and Theorem 4.7 it follows that $\int_0^1 t^{z-1} e^{-t} dt$ converges absolutely. For $t \in [1, \infty)$ we have

$$t^{Re(z)-1}e^{-t} < C_z e^{-t/2}$$

for a constant C_z which depends on z. Since the integral $\int_1^\infty e^{-t/2} dt$ exists by Example 4.3 d), the integral $\int_1^\infty t^{z-1} e^{-t} dt$ is absolutely convergent. The gamma function $\Gamma: \{z \in \mathbb{C} : Re(z) > 0\} \to \mathbb{C}$ defined in this way has the following properties:

- a) $\Gamma(z+1) = z \Gamma(z), Re(z) > 0,$
- b) $\Gamma(1) = 1$,
- c) $\Gamma(n+1) = n!$, $n \in \mathbb{N}$.

To see property a), we integrate by parts to obtain

$$\underbrace{\int_{a}^{b} t^{z} e^{-t} dt}_{\rightarrow \Gamma(z+1) \text{ for } b \rightarrow \infty, \ a \rightarrow 0+} = \underbrace{-t^{z} e^{-t} \mid_{a}^{b}}_{\rightarrow 0 \text{ for } b \rightarrow \infty, \ a \rightarrow 0+} + \underbrace{z \int_{a}^{b} t^{z-1} e^{-t} dt}_{a}, \ 0 < a < b < \infty.$$

Therefore we have $\Gamma(z+1)=z$ for Re(z)>0.

Property b) follows immediately from Example 4.3 d). Similarly, property c) follows by applying a) repeatedly in connection with b).

In many applications, it is important to calculate approximate values of $\Gamma(x)$ or n! of large x and n, respectively. In this context, the *Stirling formula* is of particular interest. It says that for x>0 we have

$$\Gamma(x) = \sqrt{2\pi} x^{x-1/2} e^{-x+\mu(x)}, \text{ with } 0 < \mu(x) < \frac{1}{12x}.$$

Therefore, $\sqrt{2\pi}x^{x-1/2}e^{-x}$ is often used as an approximation of $\Gamma(x)$. The relative error of the approximation is $e^{-12x} - 1$ and is smaller than one percent already for x > 10.

4.10 Example. (The beta function)

Another important function, also defined by an improper integral, is the so-called *beta* function. For $p, q \in \mathbb{C}$ with Re(p), Re(q) > 0, it is defined by

$$B(p,q) = \int_0^1 t^{p-1} (1-t)^{q-1} dt.$$

The above integral is absolutely convergent (cf. exercises) and thus B(p,q) is well defined. Furthermore, we have the relation

$$\frac{\Gamma(p)\Gamma(q)}{\Gamma(p+q)} = B(p,q), \quad Re(p), Re(q) > 0.$$