



## Partial Differential Equations I: Linear Theory

### Solutions to the Exercises of Tutorial 11

**1. Proof.** Since  $x_0, y \in \Gamma$  and  $\Gamma$  is flat, we see that the normal vector  $n_y$ , at  $y$ , to  $\Gamma$  is orthogonal to  $\Gamma$ . That is

$$(x_0 - y) \cdot n_y = 0. \quad (1)$$

Hereafter the integer upper-scripts as in e.g.  $y^j, x_0^j$ , denote the  $j$ th component of the vectors  $y, x_0$  respectively. Recalling that for  $j = 1, 2, 3$

$$\frac{\partial}{\partial y^j} |x_0 - y| = \frac{y^j - x_0^j}{|x_0 - y|},$$

$$\frac{d}{dr} \frac{e^{i\sqrt{\lambda}r}}{r} = \frac{i\sqrt{\lambda}r - 1}{r^2} e^{i\sqrt{\lambda}r},$$

and that  $\frac{\partial}{\partial n_y} = n_y \cdot \nabla_y$ , we obtain

$$\begin{aligned} \frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x_0-y|}}{|x_0-y|} &= \frac{i\sqrt{\lambda}r - 1}{r^2} e^{i\sqrt{\lambda}r} \Big|_{r=|x_0-y|} \sum_{i=1}^3 \left( \frac{\partial}{\partial y^i} |x_0 - y| \right) \cdot n_y^i \\ &= \frac{i\sqrt{\lambda}r - 1}{r^2} e^{i\sqrt{\lambda}r} \Big|_{r=|x_0-y|} \frac{(y - x_0) \cdot n_y}{|x_0 - y|} \\ &= 0, \end{aligned} \quad (2)$$

here, we used (1). And the proof of the assertion is complete.

**2. Solution.** We use the jump relation for the double layer potential

$$\lim_{y \rightarrow x} u(y) = -v(x) + \frac{1}{2\pi} \int_{\partial\Omega} \frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x_0-y|}}{|x_0-y|} v(y) dS_y$$

for  $x \in \partial\Omega$ .

We define

$$v(y) = \begin{cases} 0, & \text{if } y \in \partial\Omega \setminus \Gamma, \\ -f(y), & \text{if } y \in \Gamma. \end{cases}$$

By the jump relation and (2) we then have that if  $x \in \Gamma$ ,

$$\begin{aligned} \lim_{y \rightarrow x} u(y) &= -v(x) + \frac{1}{2\pi} \int_{\partial\Omega} \frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x_0-y|}}{|x_0-y|} v(y) dS_y \\ &= f(x) + \frac{1}{2\pi} \left( \int_{\partial\Omega \setminus \Gamma} + \int_{\Gamma} \right) \frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x_0-y|}}{|x_0-y|} v(y) dS_y \\ &= f(x). \end{aligned} \quad (3)$$

The integrals in (3) is zero since the integrand is equal to zero, due to in first part of the integral  $v = 0$  in  $\partial\Omega \setminus \Gamma$  while the first factor of the integrand in  $\Gamma$  is equal to zero because of (2). Thus we have constructed a solution to

$$\begin{aligned} \Delta u(x) + \lambda u(x) &= 0, \quad x \in \Omega, \\ u(x) &= f(x), \quad x \in \Gamma. \end{aligned}$$

**3. Solution.** The function  $u$  constructed above is, in general, not a solution of the Dirichlet problem

$$\begin{aligned} \Delta u(x) + \lambda u(x) &= 0, \quad x \in \Omega, \\ u(x) &= f(x), \quad x \in \partial\Omega. \end{aligned} \quad (4)$$

The reason is as follows: for  $x \in \partial\Omega \setminus \Gamma$ , we can not obtain that  $u(x) = 0$  which is required by the jump relation. In fact, we have

$$-v(x) + \frac{1}{2\pi} \int_{\partial\Omega} \frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x-y|}}{|x-y|} v(y) dS_y = -\frac{1}{2\pi} \int_{\Gamma} \frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x-y|}}{|x-y|} f(y) dS_y.$$

Since  $x \in \partial\Omega \setminus \Gamma$  and  $y \in \Gamma$ , one can assume reasonably that  $\text{dist}\{x, y\} \neq 0$ , from which we conclude that  $\frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x-y|}}{|x-y|}$  is continuous and is not identically equal to zero from the computations in Problem 1. Thus there exists at least one point, say  $x_0$ , such that

$$\frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x-y|}}{|x-y|} \neq 0.$$

Thus if we define a continuous function  $f$  such that  $f(x) = 1$  for all  $x \in B_\varepsilon(x_0)$  with  $\varepsilon$  being suitably small,  $f(x) = 0$  for  $x \in \mathbb{R}^3 \setminus B_{2\varepsilon}(x_0)$ , and  $f(x) \in [0, 1]$  for  $x \in B_{2\varepsilon} \setminus B_\varepsilon(x_0)$ , then there holds for this  $f$  that

$$-\frac{1}{2\pi} \int_{\Gamma} \frac{\partial}{\partial n_y} \frac{e^{i\sqrt{\lambda}|x-y|}}{|x-y|} f(y) dS_y \neq 0.$$

which by jump relation should be equal to zero since  $f(x) = 0$  for  $x \in \partial\Omega \setminus \Gamma$ . Therefore,  $u$  constructed in Problem 3 is not necessary a solution to problem (4) – (5).

4. *Solution.* Since  $\Omega = B_R(0) \subset \mathbb{R}^3$ , we know that the normal derivative is radial, i.e.  $\frac{\partial}{\partial n_y} = \frac{y}{|y|} \cdot \nabla_y$ . We consider the real valued solution, whence the jump relation becomes

$$\begin{aligned} \lim_{y \rightarrow x} u(y) &= -v(x) + \frac{1}{2\pi} \int_{\partial B_R(0)} \frac{\partial}{\partial n_y} \frac{1}{|x-y|} v(y) dS_y \\ &= -v(x) - \frac{1}{2\pi} \int_{|y|=R} \sum_{j=1}^3 \frac{y^j}{|y|} \cdot \frac{y^j - x^j}{|x-y|^3} v(y) dS_y \\ &= -v(x) - \frac{1}{2\pi} \int_{|y|=R} \frac{y \cdot (y-x)}{R|x-y|^3} v(y) dS_y. \end{aligned} \quad (6)$$

Suppose that there is a solution  $u$  to the boundary value problem

$$\begin{aligned} \Delta u(x) &= 0, \quad x \in B_R(0), \\ u(x) &= f(x), \quad x \in \partial B_R(0) \end{aligned}$$

where  $f = \text{const}$ , then  $f$  satisfies

$$\text{const} = f(x) = -v(x) - \frac{1}{2\pi} \int_{|y|=R} \frac{y \cdot (y-x)}{R|x-y|^3} v(y) dS_y.$$

We choose that  $v(x) = V = \text{const}$ , then the above equality becomes

$$\begin{aligned} \text{const} &= -V - \frac{1}{2\pi} \int_{|y|=R} \frac{y \cdot (y-x)}{R|x-y|^3} V dS_y \\ &= -V \left( 1 + \frac{1}{2\pi} \int_{|y|=R} \frac{y \cdot (y-x)}{R|x-y|^3} dS_y \right). \end{aligned}$$

from which  $V$  can be solved if

$$\frac{1}{2\pi} \int_{|y|=R} \frac{y \cdot (y-x)}{R|x-y|^3} dS_y \neq -1.$$

Thus we prove the existence of solution  $u$ .

5. *Solution.* i) Let  $z_0 = (0, 0, 1)$ . To compute the integral

$$\frac{1}{2\pi} \int_{|z|=1} \frac{z \cdot (z - z_0)}{|z_0 - z|^3} dS_z,$$

we use the spherical coordinates:

$$\begin{aligned} z_1 &= R \sin \phi \cos \theta, \\ z_2 &= R \sin \phi \sin \theta, \\ z_3 &= R \cos \phi, \end{aligned}$$

where  $R = 1$ ,  $\phi \in [0, \pi]$  and  $\theta \in [0, 2\pi]$ . Thus  $dS_z = \sin \phi d\theta d\phi$ . Moreover, we have

$$z \cdot (z - z_0) = 1 - \cos \phi, \quad |z_0 - z| = \sqrt{2(1 - \cos \phi)},$$

and the integral turns out to be

$$\begin{aligned} \frac{1}{2\pi} \int_0^{2\pi} d\theta \int_0^\pi \frac{1 - \cos \phi}{\left(\sqrt{2(1 - \cos \phi)}\right)^3} \sin \phi d\phi &= 2^{-\frac{3}{2}} \int_0^\pi \frac{\sin \phi d\phi}{\sqrt{1 - \cos \phi}} \\ &= 2^{-\frac{3}{2}} \int_0^2 \frac{dt}{\sqrt{t}} \\ &= 1 \neq -1. \end{aligned} \quad (7)$$

ii) Making a suitable rotation we find that the assumption that  $z_0 = (0, 0, 1)$  is not a restriction due to the rotation invariance of this integral. Namely, for any  $z_0 \in \partial B_1(0)$ , we write it  $z_0 = (\sin \phi_0 \cos \theta_0, \sin \phi_0 \sin \theta_0, \cos \phi_0)$ , then we make suitable rotation transform  $M$  such that

$$Mz_0 = (0, 0, 1),$$

However, the form of the integral is not changed.

To do this, we first define

$$M_1 = \begin{pmatrix} \cos \phi_1 & -\sin \phi_1 & 0 \\ \sin \phi_1 & \cos \phi_1 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

and

$$M_2 = \begin{pmatrix} \cos \phi_2 & 0 & -\sin \phi_2 \\ 0 & 1 & 0 \\ \sin \phi_2 & 0 & \cos \phi_2 \end{pmatrix},$$

where  $\phi_1, \phi_2$  are two constant to be determined. Then define

$$M = M_1 M_2.$$

Letting

$$\phi_1 = -\theta_0, \quad \phi_2 = \phi_0.$$

It is easy to check that  $M^T M = I$  and  $Mz_0 = (0, 0, 1)$ . Let  $y = Mz$  and  $y_0 = Mz_0$ . There hold  $|y| = |Mz| = 1$ ,

$$z \cdot (z - z_0) = My \cdot (My - z_0) = y \cdot (y - y_0),$$

and  $|z - z_0| = |M(y - y_0)| = |y - y_0|$ . The integral turns out to be

$$\frac{1}{2\pi} \int_{|y|=1} \frac{y \cdot (y - y_0)}{|y_0 - y|^3} dS_y,$$

which has the exact form as that for  $z$ . This allows us to repeat i) for  $y$  to evaluate the integral.