



## Solutions to the Exercises of Tutorial 08

1. *Proof.* Since  $u$  satisfies the mean value formula, we have

$$u(x) = \frac{1}{\pi r^2} \int_{B_r(x)} u(y) dy,$$

for any  $B_r(x) \subset \Omega$ .

We employ the argument of contradiction and assume that there exists a point  $x_0 \in \Omega$ , such that  $\Delta u(x_0) \neq 0$ . Without loss of generality we assume that  $\Delta u(x_0) > 0$ . From the continuity of  $u$  we conclude that there exists a ball  $B_\varepsilon(x_0)$  such that

$$\Delta u(x) > 0, \text{ for all } x \in B_\varepsilon(x_0), \quad (1)$$

here  $\varepsilon$  is a small positive number.

Since we assume that  $u \in C_2(\Omega)$ , we can apply the Green formula to get

$$\begin{aligned} \int_{B_\varepsilon(x_0)} \Delta u(x) dx &= \int_{\partial B_\varepsilon(x_0)} \nabla u(x) \cdot n dS_x \\ &= \int_0^{2\pi} \frac{\partial}{\partial r} u(r\omega) d\theta \\ &= \frac{\partial}{\partial r} \int_0^{2\pi} u(r\omega) d\theta \\ &= \frac{\partial}{\partial r} u(x_0) = 0. \end{aligned}$$

However, the integral  $\int_{B_\varepsilon(x_0)} \Delta u(x) dx$  is positive by (1).

Thus we arrive at a contradiction. Whence  $\Delta u(x) = 0$  for all  $x \in \Omega$ , i.e.  $u$  is harmonic.

2. *Proof.* Firstly we compute  $\Delta f(u)$  for  $C^2$ -functions  $f : \mathbb{R} \rightarrow \mathbb{R}$  and  $u : \mathbb{R}^n \rightarrow \mathbb{R}$ . There holds

$$\Delta(f(u)) = f'(u)\Delta u + f''(u)|\nabla u|^2.$$

i) Thus choosing  $f(u) = u^2$  we then have  $\Delta(u^2) = 2(u\Delta u + |\nabla u|^2)$ . Since  $u$  is a harmonic function, one has

$$\Delta(u^2) = 2|\nabla u|^2 \geq 0.$$

Now we choose a ball  $B \subset \mathbb{R}^n$ . It is easy to find a solution  $v$  to

$$\Delta v = 0, \text{ in } B,$$

and  $v|_{\partial B} = (u^2)|_{\partial B}$ . We need only to prove that  $v \leq u$  in  $B$ . To prove this we let  $w = u^2$  and  $F = w - v$ . Then  $F$  satisfies

$$\Delta F = g, \text{ in } B,$$

and  $F|_{\partial B} = 0$ , where  $g = 2|\nabla u|^2 \geq 0$ . Applying the maximum principle we obtain

$$F \leq 0.$$

Therefore  $u^2$  is sub-harmonic.

ii) For any convex function  $f \in C_2(\mathbb{R}, \mathbb{R})$ , by a slightly different argument we prove that the composite function  $f(u)$  is sub-harmonic.

**3. Proof.** The proof consists of three steps. We first construct a smooth approximation, say  $|x|_\varepsilon$ , of  $|x|$ , then prove this approximate function is sub-harmonic. Finally pass the approximate function to limit as  $\varepsilon \rightarrow 0$ .

i) We define

$$|x|_\varepsilon = \sqrt{|x|^2 + \varepsilon^2}.$$

It is easy to show that  $|x| + \sqrt{|x|^2 + \varepsilon^2} \geq \varepsilon$  for all  $x$ . Thus

$$||x|_\varepsilon - |x|| = \frac{\varepsilon^2}{|x|_\varepsilon + |x|} \leq \varepsilon \rightarrow 0$$

as  $\varepsilon \rightarrow 0$ .

ii) Straightforward computations yield

$$\partial_{x_i}(|x|_\varepsilon) = \frac{x_i}{|x|_\varepsilon},$$

and

$$\partial_{x_i}^2(|x|_\varepsilon) = \frac{|x|^2 + \varepsilon^2 - x_i^2}{|x|_\varepsilon^3},$$

from which we obtain

$$\Delta(|x|_\varepsilon) = \frac{(n-1)|x|^2 + n\varepsilon^2}{|x|_\varepsilon^3} =: f_\varepsilon(x).$$

Choose any ball  $B \subset \mathbb{R}^n$ . Suppose that  $v^\varepsilon$  is a solution to

$$\Delta v^\varepsilon = 0, \text{ in } B,$$

and  $v^\varepsilon|_{\partial B} = (|x|_\varepsilon)|_{\partial B}$ . From the lecture notes we know such solution exists. Let  $w_\varepsilon = |x|_\varepsilon - v^\varepsilon$ , then  $w$  satisfies

$$\Delta w = f, \text{ in } B,$$

and  $w_\varepsilon|_{\partial B} = 0$ . Note that  $f_\varepsilon \geq 0$ . Applying the maximum principle yields

$$w \leq 0$$

whence  $|x|_\varepsilon$  is sub-harmonic.

iii)  $|x|_\varepsilon$  converges to  $|x|$  uniformly. Note that

$$|x| \leq |x|_\varepsilon \leq v^\varepsilon, \text{ in } B$$

and  $(v^\varepsilon)|_{\partial B} = |x|_\varepsilon|_{\partial B} \rightarrow (|x|)|_{\partial B}$  as  $\varepsilon \rightarrow 0$ . We also have  $v^\varepsilon \rightarrow v$  in  $C(\bar{B})$  which is harmonic. Thus  $|x|$  is sub-harmonic. This argument indicates that Theorem 5.12 in the lecture notes is still true for the case that we have infinitely many sub-solutions.

4. i) Define  $w \equiv 0$ . It is easy to see that  $w$  is a super-solution to the equation

$$\lambda v + \Delta v = 0, \text{ in } \Omega,$$

with  $\lambda \leq 0$  satisfying the boundary condition  $w|_{\partial\Omega} = 0$ .

ii) There are two cases according to  $\lambda = 0$  or  $\lambda < 0$ .

a) We assume firstly that  $\lambda < 0$ . Define a function in the form:

$$u_1(x) = -M(1 - e^{-\mu d(x)})$$

Here  $M, \mu > 0$  are positive constants to be determined later on, and  $d = d(x)$  defined  $d(x) = \text{dist}(x, \partial\Omega)$  for any  $x \in \Omega$ , is the distance function which is Lipschitz continuous (this can be proven by using the triangle inequality easily). Furthermore, since the boundary  $\partial\Omega$  is  $C^2$ , we have that  $d(x)$  is  $C^2$  too for  $x$  near  $\partial\Omega$ ,  $u_1$  is also  $C^2$ . Now we calculate

$$\partial_i u_1 = -\mu M e^{-\mu d} \partial_i d,$$

and

$$\partial_i^2 u_1 = (\mu(\partial_i d)^2 - \partial_i^2 d) M \mu e^{-\mu d},$$

Therefore, we obtain for  $x$  near  $\partial\Omega$ , say  $x \in \Omega_\gamma = \left\{x \in \Omega \mid d(x) < \frac{1}{\gamma}\right\}$ , that

$$\begin{aligned} \lambda u_1 + \Delta u_1 &= -\lambda M + \left( \lambda + \mu^2 \sum_{i=1}^3 (\partial_i d)^2 - \mu \Delta d \right) M e^{-\mu d} \\ &\geq -\lambda M + \frac{1}{2} \lambda M \\ &= -\frac{1}{2} \lambda M > 0, \end{aligned}$$

provided that  $x \in \Omega_\gamma$  and  $\gamma = \frac{1}{\mu}$ , where  $\mu$  is sufficiently small from which it follows that  $e^{-\mu d}$  approaches to 1 (In fact, we have  $e^{-1} \leq e^{-\mu d} \leq 1$  for all  $x \in \Omega_\gamma$ ), also the

continuity of  $\Delta d$  and  $\partial_i d$  over  $\bar{\Omega}_\gamma$  which implies that they are uniformly bounded on  $\bar{\Omega}_\gamma$ , namely there exists a constant  $K$  such that  $|\partial_i d| + |\Delta d| \leq K$ .

The above computations motivate us to construct a sub-solution as follows: Choose the two positive constants  $M, C$  such that  $C \ll M$ . Then we have

$$\underline{u}(x) = u_1(x)$$

for  $x$  which closes sufficiently to the boundary of  $\Omega$ , otherwise

$$\underline{u}(x) = -C.$$

Using the property that  $\max\{f, g\}$  is a sub-solution if  $f, g$  are sub-solutions (see also Theorem 5.12 in the lecture notes), one can easily prove that  $\underline{u}$  is a sub-solution. to the Helmholtz equation, satisfying  $\underline{u}|_{\partial\Omega} = 0$ . It remains to show that  $u_1$  is a sub-solution.

Since  $d$  may be not differentiable at  $x$  which is not near the boundary, we employ an approximate procedure. One way is to apply the Weierstrass theorem which says that a continuous function can be approximated by a polynomial sequence. Another is to use the convolution introduced in the lecture. Here we use the latter one. Taking a function  $\varphi_\varepsilon \in C_\infty$  such that  $\int_{\mathbb{R}^n} \varphi_\varepsilon dx = 1$ , the support of  $\varphi_\varepsilon(x)$  is  $B_\varepsilon(0)$ . It is not difficult to prove that

$$f * \varphi_\varepsilon \in C_\infty(\mathbb{R}^n),$$

if  $f \in L_{1,\text{loc}}(\mathbb{R}^n)$ . Applying this to function  $d$  which is Lipschitz continuous, hence  $d \in L_1(\Omega)$ , so  $d * \varphi_\varepsilon \in C_\infty(\Omega)$ . Moreover, we have

$$d * \varphi_\varepsilon \rightarrow d, \text{ in } C(\Omega).$$

We now define a new function  $u_1^\varepsilon$  by

$$u_1^\varepsilon(x) = -M (1 - e^{-\mu d^\varepsilon(x)})$$

Similar the computations carried out for  $u_1$ , and choosing  $\mu$  suitably small (however maybe depends on  $\varepsilon$  in this case) yield

$$\begin{aligned} \lambda u_1^\varepsilon + \Delta u_1^\varepsilon &= -\lambda M + \left( \lambda + \mu^2 \sum_{i=1}^3 (\partial_i d^\varepsilon)^2 - \mu \Delta d^\varepsilon \right) M e^{-\mu d^\varepsilon} \\ &\geq -\lambda M + \frac{1}{2} \lambda M \\ &= -\frac{1}{2} \lambda M > 0, \end{aligned}$$

for any fixed  $\varepsilon$ . From this one can conclude that  $u_1^\varepsilon$  is a sub-solution to Helmholtz equation satisfying suitable boundary condition. Using again Theorem 5.12 in a slightly general version (i.e. for infinitely many sub-solutions), we then conclude

the limit,  $u_1$ , of  $u_1^\varepsilon$ , is also a sub-solution to the Helmholtz equation satisfying the zero boundary condition.

b) We now consider the case that  $\lambda = 0$ . For this problem, the above technique does not work. However it is valid for a new function  $v^\varepsilon$  which is defined by  $v^\varepsilon = e^{\varepsilon x_1} u$  with a small parameter  $\varepsilon$ . For simplicity we omit the upper-script  $\varepsilon$  till we investigate its limit. Then one has

$$\partial_1 v = \varepsilon e^{\varepsilon x_1} u + e^{\varepsilon x_1} \partial_1 u, \quad \partial_i v = e^{\varepsilon x_1} \partial_i u, \text{ for } i \neq 1,$$

and

$$\partial_1^2 v = \varepsilon^2 e^{\varepsilon x_1} u + 2\varepsilon e^{\varepsilon x_1} \partial_1 u + e^{\varepsilon x_1} \partial_1^2 u, \quad \partial_i^2 v = e^{\varepsilon x_1} \partial_i^2 u, \text{ for } i \neq 1,$$

Thus

$$\Delta v + 2\varepsilon \partial_1 v - 3\varepsilon^2 v = 0.$$

There is a term in the equation, which involves the first order derivative  $\partial_1 v$ . However, from the argument in a) we see that this is not an essential difficulty. Letting  $\lambda = -3\varepsilon^2$ , we see that this equation satisfies the requirement of a), i.e.  $\lambda < 0$ .

Therefore we can construct a sub-solution satisfying  $v^\varepsilon|_{\partial\Omega} = 0$ , in a similar manner as in a), for every fixed  $\varepsilon$ . Then letting  $\varepsilon \rightarrow 0$  we get the limit function  $u$  satisfying  $u|_{\partial\Omega} = 0$  and  $u$  is a sub-solution to the Helmholtz equation.