

9. Differential Calculus

Definition 9.1

Let V and W be two Banach spaces, $D \subseteq V$ be open in V and let $a \in D$. A function $f: D \rightarrow W$ is called differentiable at a if there exists a continuous linear transformation $T \in \mathcal{L}(V, W)$ such that

$$(*) \quad \lim_{x \rightarrow a} \frac{f(x) - f(a) - T(x-a)}{\|x-a\|} = 0$$

Remark 9.2

In the hypothesis of the above definition, for a function $f: D \rightarrow W$ the following are equivalent:

(i) f is differentiable at a ;

(ii) there exists $T \in \mathcal{L}(V, W)$ s.t. $\lim_{x \rightarrow a} \frac{\|f(x) - f(a) - T(x-a)\|}{\|x-a\|} = 0$;

(iii) there exist $T \in \mathcal{L}(V, W)$ and $r: D \rightarrow W$ s.t.

(a) $f(x) = f(a) + T(x-a) + r(x)$ for all $x \in D$, and

(b) $\lim_{x \rightarrow a} \frac{\|r(x)\|}{\|x-a\|} = 0$;

(iv) there exist $T \in \mathcal{L}(V, W)$ and $r': D \rightarrow W$ s.t.

(a) $f(x) = f(a) + T(x-a) + \|x-a\| \cdot r'(x)$ for all $x \in D$, and

(b) $\lim_{x \rightarrow a} \|r'(x)\| = 0$.

(v) there exist $T \in \mathcal{L}(V, W)$ and a map $\varphi: U_0 \rightarrow W$, where $U_0 \subseteq V$ is a neighborhood of 0 s.t.

(a) $f(a+h) = f(a) + T(h) + \psi(h)$ for all $h \in U_0$, and

(b) $\lim_{h \rightarrow 0} \frac{\psi(h)}{\|h\|} = 0;$

(vii) there exist $T \in \mathcal{L}(V, W)$ and a map $\psi: U_0 \rightarrow W$, where U_0 is a neighborhood of 0 in V s.t.

(a) $f(a+h) = f(a) + T(h) + \|h\| \cdot \psi(h)$ for all $h \in U_0$, and

(b) $\lim_{h \rightarrow 0} \psi(h) = 0.$

Proof

Exercise. □

Proposition 9.3

If f is differentiable at a , then the continuous linear transformation satisfying (*) is uniquely determined.

Proof

Assume that $S \in \mathcal{L}(V, W)$ is another function having property (*). It follows that

$$\begin{aligned} \lim_{x \rightarrow a} \frac{T(x-a) - S(x-a)}{\|x-a\|} &= \lim_{x \rightarrow a} \frac{(f(x) - f(a) - T(x-a)) - (f(x) - f(a) - S(x-a))}{\|x-a\|} \\ &= \lim_{x \rightarrow a} \frac{f(x) - f(a) - T(x-a)}{\|x-a\|} - \lim_{x \rightarrow a} \frac{f(x) - f(a) - S(x-a)}{\|x-a\|} \\ &= 0. \end{aligned}$$

We shall prove that $T(y) = S(y)$ for all $y \in V$. If $y = 0$, then $T(0) = S(0) = 0$.

Assume now that $y \neq 0$. Since $a \in D$ and D is open in V , there exists $r > 0$ s.t. $U_r(a) \subseteq D$. Then by setting $\delta := \frac{r}{\|y\|}$ we get that for all $t \in]0, \delta[$,

$\|(a+ty) - a\| = \|ty\| = t \cdot \|y\| < \delta \cdot \|y\| = r$, so $(a+ty) \in U_r(a) \subseteq D$.

Since $\lim_{t \rightarrow 0} (a+ty) = a$, we set that

$$\begin{aligned}
0 &= \lim_{t \rightarrow 0} \frac{T((a+ty)-a) - S((a+ty)-a)}{\|(a+ty)-a\|} = \lim_{t \rightarrow 0} \frac{T(ty) - S(ty)}{t \cdot \|y\|} = \\
&= \lim_{t \rightarrow 0} \frac{t(T(y) - S(y))}{t \cdot \|y\|} = \lim_{t \rightarrow 0} \frac{T(y) - S(y)}{\|y\|} = \frac{T(y) - S(y)}{\|y\|}.
\end{aligned}$$

Hence, $T(y) = S(y)$.

□

Definition 3.4

The uniquely determined continuous linear transformation T of the Definition 3.1 is called the derivative of f at a and is denoted by $f'(a)$ or $Df(a)$.

Definition 3.5

We say that $f: D \rightarrow W$ is differentiable if f is differentiable at every point $a \in D$. In that case, the derivative f' is a map

$$f': D \rightarrow \mathcal{L}(V, W), \quad a \mapsto f'(a).$$

from D into the Banach space $(\mathcal{L}(V, W), \|\cdot\|)$, where $\|\cdot\|$ is the operator norm.

We say that f is continuously differentiable or that f is of class C^1 if f' is continuous.

Remark 3.6

If V and W are finite dimensional normed spaces (and, hence, Banach spaces by Theorem 6.43), then any linear transformation $T: V \rightarrow W$ is continuous (see Proposition 6.46).

Moreover, since any two norms on a finite dimensional normed space are equivalent, it follows that the property of a function to be differentiable does not depend on V and W .

Remark 3.7

In the case $V = W = \mathbb{K}$ we get the usual definition of differentiability in \mathbb{K} from Analysis I.

Proof

Use the fact that a function $T: \mathbb{K} \rightarrow \mathbb{K}$ is linear iff there exists $L \in \mathbb{K}$ s.t. $T(x) = Lx$ for all $x \in \mathbb{K}$.

□

Proposition 3.8

Let V and W be Banach spaces, $D \subseteq V$ be open in V , $a \in D$ and $f: D \rightarrow W$ be differentiable at a . Then there exists a constant $c > 0$ s.t. for all x from a neighborhood of a

$$\|f(x) - f(a)\| \leq c \|x - a\|.$$

In particular, f is continuous at a .

Proof

Let us use Remark 3.2 (iv). Then there exists $r: D \rightarrow W$ s.t.

(5)

$f(x) = f(a) + f'(a)(x-a) + \|x-a\| r(x)$ for all $x \in D$ and $\lim_{x \rightarrow a} r(x) = 0$.

We get that for all $x \in D$,

$$\begin{aligned} \|f(x) - f(a)\| &= \left\| f'(a) \cdot (x-a) + \|x-a\| \cdot r(x) \right\| \leq \|f'(a) \cdot (x-a)\| + \\ &+ \|x-a\| \cdot \|r(x)\| \leq (\|f'(a)\| + \|r(x)\|) \|x-a\|. \end{aligned}$$

Since $\lim_{x \rightarrow a} r(x) = 0$, there exists $\delta > 0$ s.t.

$$(\forall x \in D) (0 < \|x-a\| < \delta \Rightarrow \|r(x)\| < 1).$$

Let $U := U_\delta(a)$. Then for all $x \in U$,

$$\|f(x) - f(a)\| \leq (\|f'(a)\| + 1) \cdot \|x-a\| = c \|x-a\|,$$

where $c = \|f'(a)\| + 1$.

In particular, this implies that

$$\lim_{x \rightarrow a} \|f(x) - f(a)\| \leq \lim_{x \rightarrow a} c \cdot \|x-a\| = 0,$$

so $\lim_{x \rightarrow a} f(x) = f(a)$. Thus, f is continuous at a . □

Operations with differentiable functions

In this section V, W, U are Banach spaces.

Proposition 3.3

Let D be open in V , $a \in D$ and $f, g: D \rightarrow W$. Assume that f and g are differentiable at a . Then

(i) $f+g$ is differentiable at a , and

$$(f+g)'(a) = f'(a) + g'(a).$$

(6)

(ii) for all $c \in \mathbb{R}$, $c \cdot f$ is differentiable at a , and

$$(c \cdot f)'(a) = c \cdot f'(a).$$

Proof

Since f, g are differentiable at a , there are $\tau_1, \tau_2: D \rightarrow W$

s.t.

$$f(x) = f(a) + f'(a)(x-a) + \tau_1(x), \quad \lim_{x \rightarrow a} \frac{\tau_1(x)}{\|x-a\|} = 0$$

$$g(x) = g(a) + g'(a)(x-a) + \tau_2(x), \quad \lim_{x \rightarrow a} \frac{\tau_2(x)}{\|x-a\|} = 0.$$

(i) Let $\tau := \tau_1 + \tau_2$. then

$$(f+g)(x) = (f+g)(a) + (f'(a) + g'(a))(x-a) + \tau(x), \text{ and}$$

$$\lim_{x \rightarrow a} \frac{\tau(x)}{\|x-a\|} = \lim_{x \rightarrow a} \frac{\tau_1(x)}{\|x-a\|} + \lim_{x \rightarrow a} \frac{\tau_2(x)}{\|x-a\|} = 0.$$

Thus, $f+g$ is differentiable at a and $(f+g)'(a) = f'(a) + g'(a)$.

(ii) Let $\tau := c\tau_1$. then

$$(c \cdot f)(x) = c f(a) + (c f'(a))(x-a) + \tau(x), \text{ and}$$

$$\lim_{x \rightarrow a} \frac{\tau(x)}{\|x-a\|} = c \cdot \lim_{x \rightarrow a} \frac{\tau_1(x)}{\|x-a\|} = 0.$$

Proposition 3.10

Let D be open in V and E be open in W . Let $f: D \rightarrow E$ and $g: E \rightarrow U$ be two functions. Assume that f is differentiable at $a \in D$ and g is differentiable at $f(a)$. Then $g \circ f$ is differentiable at a , and

$$(g \circ f)'(a) = g'(f(a)) \circ f'(a).$$

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Before giving the proof, we make explicit the meaning of the above formula. Note that $f'(a): V \rightarrow W$ is a continuous linear transformation, and $g'(f(a)): W \rightarrow U$ is also a continuous linear transformation. These transformations can be composed to get a continuous linear transformation from V to U .

Proof

For brevity, we set $b = f(a)$, $T_1 = f'(a)$ and $T_2 = g'(f(a)) = g'(b)$.

Hence, we have to prove that $g \circ f$ is differentiable at a , and $(g \circ f)'(a) = T_2 \circ T_1$.

We use Lemma 9.2 (iii). Since f is differentiable at a and g is differentiable at b , there exist $r_1: D \rightarrow W$ and $r_2: E \rightarrow U$ s.t.

$$f(x) = f(a) + T_1(x-a) + r_1(x) \text{ for all } x \in D, \text{ and } \lim_{x \rightarrow a} \frac{r_1(x)}{\|x-a\|} = 0$$

$$g(y) = g(b) + T_2(y-b) + r_2(y) \text{ for all } y \in E, \text{ and } \lim_{y \rightarrow b} \frac{r_2(y)}{\|y-b\|} = 0.$$

$$\text{Let } r: D \rightarrow U, \quad r(x) = (g \circ f)(x) - (g \circ f)(a) - (T_2 \circ T_1)(a).$$

Thus, $(g \circ f)(x) = (g \circ f)(a) + (T_2 \circ T_1)(a) + r(x)$ for all $x \in D$. It remains

to prove that $\lim_{x \rightarrow a} \frac{r(x)}{\|x-a\|} = 0$.

We have that for all $x \in D$,

$$\begin{aligned} r(x) &= g(f(x)) - g(b) - T_2(T_1(a)) = (g(b) + T_2(f(x)-b) + r_2(f(x))) - \\ &\quad - g(b) - T_2(T_1(a)) = T_2(f(x)-b) - T_2(T_1(a)) + r_2(f(x)) = \\ &= T_2(f(x)-b-T_1(a)) + r_2(f(x)) = T_2(r_1(x)) + r_2(f(x)). \end{aligned}$$

It follows that

$$\begin{aligned} \frac{\|r(x)\|}{\|x-a\|} &= \frac{\|T_2(r_1(x)) + r_2(f(x))\|}{\|x-a\|} \leq \frac{\|T_2(r_1(x))\|}{\|x-a\|} + \frac{\|r_2(f(x))\|}{\|x-a\|} \\ &\leq \|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + \frac{\|r_2(f(x))\|}{\|x-a\|} = \|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + \\ &\quad + \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \cdot \frac{\|f(x)-f(a)\|}{\|x-a\|} \\ &\leq \|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + c \cdot \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \quad \text{for all } x \text{ from} \end{aligned}$$

a neighborhood of a , by Prop. 9.8.

Since $\lim_{x \rightarrow a} \left(\|T_2\| \cdot \frac{\|r_1(x)\|}{\|x-a\|} + c \cdot \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \right) = \|T_2\| \cdot 0 +$
 $+ c \cdot \lim_{x \rightarrow a} \frac{\|r_2(f(x))\|}{\|f(x)-f(a)\|} \stackrel{y:=f(x)}{=} c \cdot \lim_{y \rightarrow b} \frac{\|r_2(y)\|}{\|y-a\|} = c \cdot 0 = 0,$

it follows that $\lim_{x \rightarrow a} \frac{\|r(x)\|}{\|x-a\|} = 0$, so $\lim_{x \rightarrow a} \frac{r(x)}{\|x-a\|} = 0$.

□

Proposition 9.11

Let D be open in V and E be open in W . Let $f: D \rightarrow E$ be a bijective function and $a \in D$. If f is differentiable at a with invertible derivative $f'(a)$ and if the inverse mapping $f^{-1}: E \rightarrow D$ is continuous at $b = f(a)$, then f^{-1} is differentiable at b with derivative

$$(f^{-1})'(b) = (f'(a))^{-1} = (f'(f^{-1}(b)))^{-1}.$$

Proof

Since f is differentiable at a , by Remark 8.2 (iv), there exists

$r: D \rightarrow W$ s.t.

$$(1) \quad f(x) = f(a) + f'(a)(x-a) + \|x-a\| \cdot r(x) \quad \text{for all } x \in D, \text{ and}$$

$$\lim_{x \rightarrow a} r(x) = 0.$$

By taking $x = f^{-1}(y)$ in (1), we get that

$$(2) \quad y = b + f'(a)(f^{-1}(y) - f^{-1}(b)) + \|f^{-1}(y) - f^{-1}(b)\| \cdot r(f^{-1}(y))$$

for all $y \in E$.

For brevity, let us set $T := (f'(a))^{-1}$. By applying T to both members of (2), it follows that

$$T(y-b) = f^{-1}(y) - f^{-1}(b) + T(\|f^{-1}(y) - f^{-1}(b)\| \cdot r(f^{-1}(y))),$$

so

$$f^{-1}(y) = f^{-1}(b) + T(y-b) + \|f^{-1}(y) - f^{-1}(b)\| \cdot (-T \circ r \circ f^{-1})(y)$$

for all $y \in E$.

$$\text{Let } r': E \rightarrow W, \quad r'(y) = \frac{\|f^{-1}(y) - f^{-1}(b)\|}{\|y-b\|} \cdot (-T \circ r \circ f^{-1})(y)$$

if $y \neq b$

$$r'(b) = 0$$

Then for all $y \in E$,

$$f^{-1}(y) = f^{-1}(b) + T(y-b) + \|y-b\| \cdot r'(y).$$

Hence, it remains to prove that $\lim_{y \rightarrow b} r'(y) = 0$.

First, let us remark that, since f^{-1} is continuous at $b = f(a)$, we have that $\lim_{y \rightarrow b} f^{-1}(y) = f^{-1}(b) = a$. It follows that

$$\begin{aligned} \lim_{y \rightarrow b} \tau(f^{-1}(y)) &= \lim_{x \rightarrow a} \tau(x) = 0, \text{ so } \lim_{y \rightarrow b} (\tau \circ f^{-1})(y) = \\ &= \tau(0) = 0. \end{aligned}$$

Now, we shall prove that there exists $M > 0$ s.t.

$$\|f^{-1}(y) - f^{-1}(b)\| \leq M \cdot \|y - b\| \quad \text{for all } y \text{ from a neighborhood of } b.$$

It follows then that $\lim_{y \rightarrow b} \tau^{-1}(y) = 0$.

We have that for all $y \in E_1$

$$\begin{aligned} \|f^{-1}(y) - f^{-1}(b)\| &\leq \|\tau(y - b)\| + \|f^{-1}(y) - f^{-1}(b)\| \cdot \|-(\tau \circ f^{-1})(y)\| \\ &\leq \|\tau\| \cdot \|y - b\| + \|f^{-1}(y) - f^{-1}(b)\| \cdot \|-(\tau \circ f^{-1})(y)\|. \end{aligned}$$

Since $\lim_{y \rightarrow b} (-(\tau \circ f^{-1})(y)) = 0$, we get that there exists a neighborhood G of b s.t.

$$\|-(\tau \circ f^{-1})(y)\| \leq \frac{1}{2} \quad \text{for all } y \in G \setminus \{b\}.$$

Hence, for all $y \in G \setminus \{b\}$,

$$\|f^{-1}(y) - f^{-1}(b)\| \leq \|\tau\| \cdot \|y - b\| + \frac{1}{2} \cdot \|f^{-1}(y) - f^{-1}(b)\|,$$

so

$$(3) \quad \|f^{-1}(y) - f^{-1}(b)\| \leq 2 \cdot \|\tau\| \cdot \|y - b\|.$$

Inequality (3) is also true for $y = b$.

□

Proposition 9.12

Let D be open in V , $a \in D$ and $f, g: D \rightarrow \mathbb{R}$. Assume that f, g are differentiable at a . Then

(i) $f \cdot g: D \rightarrow \mathbb{R}$, $(f \cdot g)(x) = f(x) \cdot g(x)$ is differentiable at a , and

$$(f \cdot g)'(a) = f(a) \cdot g'(a) + g(a) \cdot f'(a).$$

(ii) if $f(a) \neq 0$, then $\frac{1}{f}$ is differentiable at a , and

$$\left(\frac{1}{f}\right)'(a) = -\frac{1}{f(a)^2} f'(a)$$

Proof

(i) Let $T := f(a) \cdot g'(a) + g(a) \cdot f'(a)$. Then for all $v \in V$, we have that

$$T(v) = f(a) \cdot g'(a)(v) + g(a) \cdot f'(a)(v).$$

We have that

$$\begin{aligned} & \lim_{x \rightarrow a} \frac{(f \cdot g)(x) - (f \cdot g)(a) - T(x-a)}{\|x-a\|} = \\ & = \lim_{x \rightarrow a} \frac{f(x)g(x) - f(a)g(a) - f(a)g'(a)(x-a) - g(a)f'(a)(x-a)}{\|x-a\|} = \\ & = \lim_{x \rightarrow a} \frac{(f(x) - f(a) - f'(a)(x-a))g(a) + f(x)(g(x) - g(a) - g'(a)(x-a))}{\|x-a\|} + \\ & \quad + \frac{(f(x) - f(a))g'(a)(x-a)}{\|x-a\|} \\ & = \lim_{x \rightarrow a} \frac{f(x) - f(a) - f'(a)(x-a)}{\|x-a\|} \cdot g(a) + \lim_{x \rightarrow a} f(x) \cdot \frac{g(x) - g(a) - g'(a)(x-a)}{\|x-a\|} + \\ & \quad + \lim_{x \rightarrow a} \frac{f(x) - f(a)}{\|x-a\|} \cdot g'(a)(x-a) = 0 \cdot g(a) + f(a) \cdot 0 + 0 = 0, \end{aligned}$$

Since f is continuous at a , so $\lim_{x \rightarrow a} f(x) = f(a)$, and

$$\frac{\|f(x) - f(a)\|}{\|x - a\|} \leq c \text{ for } x \text{ in some neighborhood of } a \text{ (see Prop. 9.8)}$$

$$\lim_{x \rightarrow a} f'(a)(x-a) = f'(a)(0) = 0.$$

(ii) Assume that $f(a) \neq 0$. Since f is continuous at a , there exists a neighborhood G of a s.t. $f(x) \neq 0$ for all $x \in G \subseteq D$.

Then $\frac{1}{f}: G \rightarrow \mathbb{W}$, $x \mapsto \frac{1}{f(x)}$ is well defined.

Consider the differentiable real function $g: \mathbb{R} \setminus \{0\} \rightarrow \mathbb{R}$ defined

by $g(y) = \frac{1}{y}$. Then $\frac{1}{f} = g \circ f$.

We can apply the Chain Rule to get that $\frac{1}{f}$ is differentiable at a with derivative

$$\left(\frac{1}{f}\right)'(a) = g'(f(a)) \cdot f'(a) = -\frac{1}{f(a)^2} f'(a).$$

□

Differentiability in \mathbb{R}^n

In the sequel, we consider $V = \mathbb{R}^n$, $W = \mathbb{R}^m$, where $m, n \in \mathbb{N}$ and the norms are the Euclidean norms, if not otherwise stated.

A function $f: D \rightarrow \mathbb{R}^m$, where $D \subseteq \mathbb{R}^n$, can be written in the form

$$f(x) = \begin{pmatrix} f_1(x) \\ \vdots \\ f_m(x) \end{pmatrix} \text{ for all } x \in \mathbb{R}^n, \text{ where } f_j: D \rightarrow \mathbb{R}, j=1, \dots, m \text{ are}$$

the components of f . We shall write $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$.

Example 9.14

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$, $f(x, y, z) = \begin{pmatrix} x^2 - y^2 \\ 2xz + 1 \end{pmatrix}$. Then $f = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix}$, where

$$f_1, f_2: \mathbb{R}^3 \rightarrow \mathbb{R}, \quad f_1(x, y, z) = x^2 - y^2, \quad f_2(x, y, z) = 2xz + 1.$$

Proposition 9.15

Let D be open in \mathbb{R}^n , $a \in D$ and $f: D \rightarrow \mathbb{R}^m$. Then

f is differentiable at $a \iff f_1, \dots, f_m$ are differentiable at a .

In this case, the derivative $f'(a) \in \mathcal{L}(\mathbb{R}^n, \mathbb{R}^m)$ is given by

$$f'(a) = \begin{pmatrix} f_1'(a) \\ \vdots \\ f_m'(a) \end{pmatrix}.$$

That is, $(f'(a))_j = f_j'(a)$ for all $j=1, \dots, m$.

Proof

We have that

f is differentiable at a with derivative $f'(a) \iff$

$$\iff \lim_{x \rightarrow a} \frac{f(x) - f(a) - f'(a)(x-a)}{\|x-a\|} = 0$$

$$\iff \lim_{x \rightarrow a} \left(\frac{f_1(x) - f_1(a) - (f'(a))_1(x-a)}{\|x-a\|} \dots \frac{f_m(x) - f_m(a) - (f'(a))_m(x-a)}{\|x-a\|} \right)^T = 0$$

$$\iff \text{for all } j=1, \dots, m, \quad \lim_{x \rightarrow a} \frac{f_j(x) - f_j(a) - (f'(a))_j(x-a)}{\|x-a\|} = 0$$

\iff for all $j=1, \dots, m$, f_j is differentiable at a and $f'_j(a) = (f'(a))_j$.

The last equivalence is true iff $(f'(a))_j \in \mathcal{L}(\mathbb{R}^n, \mathbb{R})$. It is easy to prove that if $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation, $T = \begin{pmatrix} T_1 \\ \vdots \\ T_m \end{pmatrix}$, then T_j is a linear transformation for all $j=1, \dots, m$. □

Remark 8.16

As a consequence of the above proposition, we get that for a path $\gamma: I \rightarrow \mathbb{R}^n$, where I is an open interval in \mathbb{R} , γ is differentiable $\iff \gamma$ is differentiable in the sense of Definition 8.13.

If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$, where D is open, is differentiable at $a \in D$, then the derivative $f'(a)$ is a linear transformation $\mathbb{R}^n \rightarrow \mathbb{R}^m$. Then $f'(a)$ can be represented by a $m \times n$ -matrix and sometimes $f'(a)$ is identified with this matrix. If $A = (a_{ij})_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$ is the associated matrix and

$$h = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \in \mathbb{R}^n, \text{ then } f'(a)(h) = Ah = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix}.$$

If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ is real-valued, then $f'(a)$ is a linear transformation $\mathbb{R}^n \rightarrow \mathbb{R}$, so it is represented by a $1 \times n$ -matrix, that is a row vector. The transpose $[f'(a)]^T$ of this $1 \times n$ -matrix is a $n \times 1$ -matrix, a column vector.

Definition 3.17

Let $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$, where D is open in \mathbb{R}^n , and assume that f is differentiable at a . The gradient of f at a , denoted by $\text{grad } f(a)$ or $\nabla f(a)$, is defined as

$$\text{grad } f(a) := [f'(a)]^T.$$

Directional and partial derivatives

In the sequel, $D \subseteq \mathbb{R}^n$ is open, $a \in D$ and $f: D \rightarrow \mathbb{R}^m$.

Remark 3.18

For any vector $v \in \mathbb{R}^n$, there exists a neighborhood $U_0 \subseteq \mathbb{R}$ of 0 s.t. $a + tv \in D$ for all $t \in U_0$.

Proof

Since $a \in D$ and D is open, there exists $r > 0$ s.t. $U_r(a) \subseteq D$. Let $v \in \mathbb{R}^n$. If $v = 0$, we can take any neighborhood of 0, since $a + t \cdot 0 = a \in D$. Assume that $v \neq 0$, so $\|v\| \neq 0$. Then by setting $\delta := \frac{r}{\|v\|}$ we get that for all

$$t \in U_0 :=]-\delta, \delta[,$$

$$\|(a + tv) - a\| = \|tv\| = |t| \cdot \|v\| < \delta \cdot \|v\| = r,$$

$$\text{so } a + tv \in U_r(a) \subseteq D.$$

Definition 9.18

Let $v \in \mathbb{R}^n, v \neq 0$. The directional derivative of f at a in the direction v

is defined as

$$D_v f(a) = \lim_{t \rightarrow 0} \frac{f(a+tv) - f(a)}{t},$$

provided the limit exists.

Proposition 9.20

Let $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$ and $v \in \mathbb{R}^n \setminus \{0\}$. Then

$D_v f(a)$ exists $\iff D_v f_j(a)$ exists for all $j=1, \dots, m$.

In this case,
$$D_v f(a) = \begin{pmatrix} D_v f_1(a) \\ \vdots \\ D_v f_m(a) \end{pmatrix}.$$

Proof

Similar to the proof of Proposition 9.15. □

Proposition 9.21

Assume that f is differentiable at a . Then for any $v \in \mathbb{R}^n, v \neq 0$, the directional derivative $D_v f(a)$ exists and

$$D_v f(a) = f'(a)(v).$$

Proof

Let $v \in \mathbb{R}^n, v \neq 0$. Since f is differentiable at a , by Remark 9.2 (vi),

there exists a map $\psi: U_0 \rightarrow \mathbb{R}^m$, where U_0 is a neighborhood of 0 in \mathbb{R}^n ,

s.t.

$$(1) \quad f(a+h) = f(a) + f'(a)(h) + \|h\| \cdot \psi(h) \quad \text{for all } h \in U_0$$

$$\text{and } \lim_{h \rightarrow 0} \psi(h) = 0.$$

As in Remark 3.18, we can find a neighborhood V_0 of 0 in \mathbb{R}^n s.t. $tv \in U_0$ for all $t \in V_0$. Then for $t \in V_0$ we can take $h := tv$ in (1) to get that

$$f(a+tv) = f(a) + f'(a)(tv) + \|tv\| \cdot \psi(tv), \text{ so}$$

$$f(a+tv) - f(a) = t \cdot f'(a)(v) + |t| \cdot \|v\| \cdot \psi(tv).$$

We get that

$$(2) \quad \frac{f(a+tv) - f(a)}{t} = f'(a)(v) + \frac{|t|}{t} \cdot \|v\| \cdot \psi(tv) \quad \text{for all } t \in V_0 \setminus \{0\}.$$

Since $\lim_{t \rightarrow 0} tv = 0$, we have that $\lim_{t \rightarrow 0} \psi(tv) = 0$ by (1). Moreover,

$$\left| \frac{|t|}{t} \cdot \|v\| \right| = \|v\|, \text{ so we can conclude that } \lim_{t \rightarrow 0} \left(\frac{|t|}{t} \cdot \|v\| \cdot \psi(tv) \right) = 0.$$

Thus, by (2), $\lim_{t \rightarrow 0} \frac{f(a+tv) - f(a)}{t} = f'(a)(v)$. That is, the

directional derivative $D_v f(a)$ exists and $D_v f(a) = f'(a)(v)$. □

Thus, differentiability at a implies the existence of all directional derivatives at a . We shall see later that the converse is not true. There exist functions having all directional derivatives at a point without being differentiable at that point.

Proposition 3.21 can be used to compute $f'(a)$ when we know that f is differentiable at a . If v_1, \dots, v_n is a basis of \mathbb{R}^n , then every vector $h \in \mathbb{R}^n$ can be uniquely represented as a linear combination

$h = \sum_{i=1}^n \alpha_i v_i$, with $\alpha_i \in \mathbb{R}$. Since $f'(a)$ is linear, we get that $f'(a)(h) = f'(a)\left(\sum_{i=1}^n \alpha_i v_i\right) = \sum_{i=1}^n \alpha_i f'(a)(v_i) = \sum_{i=1}^n \alpha_i D_{v_i} f(a)$.

Therefore $f'(a)$ is known if the directional derivatives $D_{v_i} f(a)$ for the basis vectors are known.

Let us consider the standard basis $e_1, \dots, e_n \in \mathbb{R}^n$, where

$e_i = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ ← i th position for all $i=1, \dots, n$.

Definition 3.22

Let $i=1, \dots, n$. The i -th partial derivative of f at a or the partial derivative of f at a with respect to the i -th variable is by definition the

directional derivative $D_{e_i} f(a)$ at a in the direction e_i , provided it exists.

We use the following notations for the i -th partial derivative of f at a :

$\frac{\partial f}{\partial x_i}(a), \partial_i f(a), D_i f(a)$.

If $\frac{\partial f}{\partial x_i}(a)$ exists, we say also that f is partial differentiable at a

with respect to the i -th variable. We say that f is partial differentiable

at a if $\frac{\partial f}{\partial x_1}(a), \dots, \frac{\partial f}{\partial x_n}(a)$ exists

If $\frac{\partial f}{\partial x_i}(a)$ exists for all $a \in D$ we get a function

$\frac{\partial f}{\partial x_i} : D \rightarrow \mathbb{R}^m$ whose value at any $a \in D$ is $\frac{\partial f}{\partial x_i}(a)$; $\frac{\partial f}{\partial x_i}$ is the

i -th partial derivative.

Remark 1.23

Let $i=1, \dots, n$ and $a = (a_1, \dots, a_n) \in D$.

$$(i) \quad \frac{\partial f}{\partial x_i}(a) = \lim_{x_i \rightarrow a_i} \frac{f(a_1, \dots, a_{i-1}, x_i, a_{i+1}, \dots, a_n) - f(a)}{x_i - a_i}.$$

(ii) If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ is real-valued, then

$$\frac{\partial f}{\partial x_i}(a) = \lim_{x_i \rightarrow a_i} \frac{\varphi_i(x_i) - \varphi_i(a_i)}{x_i - a_i} = \varphi_i'(a_i),$$

where $\varphi_i: \mathbb{R} \rightarrow \mathbb{R}$, $\varphi_i(t) = f(a_1, \dots, a_{i-1}, t, a_{i+1}, \dots, a_n)$.

Proof

$$\begin{aligned} (i) \quad \frac{\partial f}{\partial x_i}(a) &= \text{Def } f(a) = \lim_{t \rightarrow 0} \frac{f(a + te_i) - f(a)}{t} = \\ &= \lim_{t \rightarrow 0} \frac{f(a_1, \dots, a_{i-1}, a_i + t, a_{i+1}, \dots, a_n) - f(a)}{t} \\ &= \lim_{\substack{x_i = a_i + t \\ x_i \rightarrow a_i}} \lim_{x_i \rightarrow a_i} \frac{f(a_1, \dots, a_{i-1}, x_i, a_{i+1}, \dots, a_n) - f(a)}{x_i - a_i} \end{aligned}$$

(ii) Apply (i). □

Remark 1.24

Let $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$. Then for all $i=1, \dots, m$,

$$\frac{\partial f}{\partial x_i}(a) \text{ exists} \iff \frac{\partial f_1}{\partial x_i}(a), \dots, \frac{\partial f_m}{\partial x_i}(a) \text{ exists.}$$

In this case, $\frac{\partial f}{\partial x_i}(a) = \begin{pmatrix} \frac{\partial f_1}{\partial x_i}(a) \\ \vdots \\ \frac{\partial f_m}{\partial x_i}(a) \end{pmatrix}$.

Proof

It is a consequence of Proposition 9.20. □

Let $D \subseteq \mathbb{R}^n$ be open, $f: D \rightarrow \mathbb{R}^m$, $f = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$ and $a \in D$. In order to compute a partial derivative of f at a , we compute the partial derivatives at a of the components f_1, \dots, f_m . Thus, we reduce the problem to real-valued functions.

If $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ is real-valued, then we compute the partial derivative $\frac{\partial f}{\partial x_i}(a)$ as follows: we fix all the variables except for the i -th, putting them equal to $a_1, \dots, a_{i-1}, a_{i+1}, \dots, a_n$ and we consider the real function $z \mapsto f(a_1, \dots, a_{i-1}, z, a_{i+1}, \dots, a_n)$, $z \in \mathbb{R}$; now we differentiate this function at a as in Analysis I and the result is $\frac{\partial f}{\partial x_i}(a)$.

Definition 9.25

Assume that $f: D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ is partial differentiable at $a \in D$.

Then the matrix of partial derivatives

$$\begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a) & \frac{\partial f_1}{\partial x_2}(a) & \dots & \frac{\partial f_1}{\partial x_n}(a) \\ \frac{\partial f_2}{\partial x_1}(a) & \frac{\partial f_2}{\partial x_2}(a) & \dots & \frac{\partial f_2}{\partial x_n}(a) \\ \dots & \dots & \dots & \dots \\ \frac{\partial f_m}{\partial x_1}(a) & \frac{\partial f_m}{\partial x_2}(a) & \dots & \frac{\partial f_m}{\partial x_n}(a) \end{pmatrix}$$

is called the Jacobi matrix of f at a and is denoted by $Jf(a)$. (21)

If $m=n$, then the matrix $Jf(a)$ is square and its determinant $\det Jf(a)$ is called the Jacobian determinant or the Jacobian of f at a .

It is frequently denoted $\frac{\partial(f_1, \dots, f_n)}{\partial(x_1, \dots, x_n)}$ or $\frac{D(f_1, \dots, f_n)}{D(x_1, \dots, x_n)}$.

Remark 9.26

If $f: \mathbb{R}^3 \rightarrow \mathbb{R}$, one also uses the notation $\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}$, $\frac{\partial f}{\partial z}$ instead

of $\frac{\partial f}{\partial x_1}$, $\frac{\partial f}{\partial x_2}$, $\frac{\partial f}{\partial x_3}$.

Example 9.27

(i) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f(x_1, x_2) = x_1^2 x_2 + x_2^3$.

To find $\frac{\partial f}{\partial x_1}(x_1, x_2)$ we hold x_2 constant and differentiate only with respect to x_1 ; this yields

$$\frac{\partial f}{\partial x_1}(x_1, x_2) = \frac{d(x_1^2 x_2 + x_2^3)}{dx_1} = 2x_1 x_2.$$

Similarly, to find $\frac{\partial f}{\partial x_2}(x_1, x_2)$ we hold x_1 constant and differentiate

only with respect to x_2 :

$$\frac{\partial f}{\partial x_2}(x_1, x_2) = \frac{d(x_1^2 x_2 + x_2^3)}{dx_2} = x_1^2 + 3x_2^2.$$

Thus, f is partial differentiable on \mathbb{R}^2 and for all $a = (a_1, a_2) \in \mathbb{R}^2$,

$$\begin{aligned} \frac{\partial f}{\partial x_1}(a) &= 2a_1 a_2, \quad \frac{\partial f}{\partial x_2}(a) = a_1^2 + 3a_2^2, \quad Jf(a) = \begin{pmatrix} \frac{\partial f}{\partial x_1}(a) & \frac{\partial f}{\partial x_2}(a) \end{pmatrix} \\ &= (2a_1 a_2 \quad a_1^2 + 3a_2^2). \end{aligned}$$

(ii) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $f(x_1, x_2) = \begin{pmatrix} x_1^2 - x_2^2 \\ 2x_1x_2 \end{pmatrix}$.

The components of f are $f_1, f_2: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f_1(x_1, x_2) = x_1^2 - x_2^2$,

$f_2(x_1, x_2) = 2x_1x_2$.

Then f is partial differentiable on \mathbb{R}^2 and for all $a = (a_1, a_2) \in \mathbb{R}^2$

we get that

$$\begin{aligned} \mathcal{D}f(a_1, a_2) &= \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a_1, a_2) & \frac{\partial f_1}{\partial x_2}(a_1, a_2) \\ \frac{\partial f_2}{\partial x_1}(a_1, a_2) & \frac{\partial f_2}{\partial x_2}(a_1, a_2) \end{pmatrix} = \\ &= \begin{pmatrix} 2a_1 & -2a_2 \\ 2a_2 & 2a_1 \end{pmatrix}. \end{aligned}$$

(iii) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$, $f(x, y) = \begin{pmatrix} x^2 - 2xy \\ x^2 + y^3 \\ \sin x \end{pmatrix}$

The components of f are $f_1, f_2, f_3: \mathbb{R}^2 \rightarrow \mathbb{R}$,

$f_1(x, y) = x^2 - 2xy$, $f_2(x, y) = x^2 + y^3$, $f_3(x, y) = \sin x$.

For all $(x, y) \in \mathbb{R}^2$, f is partial differentiable at (x, y) and

$$\mathcal{D}f(x, y) = \begin{pmatrix} \frac{\partial f_1}{\partial x}(x, y) & \frac{\partial f_1}{\partial y}(x, y) \\ \frac{\partial f_2}{\partial x}(x, y) & \frac{\partial f_2}{\partial y}(x, y) \\ \frac{\partial f_3}{\partial x}(x, y) & \frac{\partial f_3}{\partial y}(x, y) \end{pmatrix} = \begin{pmatrix} 2x - 2y & -2x \\ 2x & 3y^2 \\ \cos x & 0 \end{pmatrix}$$

In particular, $\mathcal{D}f(0, 1) = \begin{pmatrix} -2 & 0 \\ 0 & 3 \\ 1 & 0 \end{pmatrix}$.

(iv) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f(x, y) = x^{\frac{1}{3}} y^{\frac{1}{3}} = \sqrt[3]{x} \cdot \sqrt[3]{y}$.

Then for all $(x, y) \in \mathbb{R}^2 \setminus \{(0, 0)\}$,

$$\begin{aligned} \nabla f(x, y) &= \left(\frac{\partial f}{\partial x}(x, y) \quad \frac{\partial f}{\partial y}(x, y) \right) = \left(\frac{1}{3} \cdot y^{\frac{1}{3}} \cdot x^{-\frac{2}{3}}, \frac{1}{3} x^{\frac{1}{3}} y^{-\frac{2}{3}} \right) \\ &= \left(\frac{1}{3} \frac{\sqrt[3]{y}}{\sqrt[3]{x^2}} \quad \frac{1}{3} \frac{\sqrt[3]{x}}{\sqrt[3]{y^2}} \right). \end{aligned}$$

To obtain the partial derivative at $(0, 0)$ we can not simply substitute $(x, y) = (0, 0)$. In this case, we use the definition.

$$\frac{\partial f}{\partial x}(0, 0) = \lim_{x \rightarrow 0} \frac{f(x, 0) - f(0, 0)}{x - 0} = \lim_{x \rightarrow 0} \frac{0 - 0}{x} = 0.$$

$$\frac{\partial f}{\partial y}(0, 0) = \lim_{y \rightarrow 0} \frac{f(0, y) - f(0, 0)}{y - 0} = 0.$$

Thus, $\nabla f(0, 0) = (0 \ 0)$.

Proposition 9.28

Let $D \subseteq \mathbb{R}^n$ be open, $a \in D$ and $f: D \rightarrow \mathbb{R}^m$. If f is differentiable at a , then f is partial differentiable at a and for all $h \in \mathbb{R}^n$

$$f'(a)(h) = \nabla f(a) \cdot h.$$

Thus, the matrix associated to $f'(a)$ is the Jacobi matrix of f at a .

Proof

By Proposition 9.21, f is partial differentiable at a and for all $i = 1, \dots, n$

$$\frac{\partial f}{\partial x_i}(a) = \text{Dei } f(a) = f'(a)(e_i).$$

Let $h = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \in \mathbb{R}^n$. Then $h = \sum_{i=1}^n h_i e_i$, so

$$f'(a)(h) = f'(a) \left(\sum_{i=1}^n h_i e_i \right) = \sum_{i=1}^n h_i f'(a)(e_i) = \sum_{i=1}^n h_i \frac{\partial f}{\partial x_i}(a)$$

$$= \sum_{i=1}^n h_i \cdot \begin{pmatrix} \frac{\partial f_1}{\partial x_i}(a) \\ \vdots \\ \frac{\partial f_m}{\partial x_i}(a) \end{pmatrix}, \text{ by Remark 9.24}$$

$$= \begin{pmatrix} \sum_{i=1}^n h_i \cdot \frac{\partial f_1}{\partial x_i}(a) \\ \vdots \\ \sum_{i=1}^n h_i \cdot \frac{\partial f_m}{\partial x_i}(a) \end{pmatrix} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a) & \dots & \frac{\partial f_1}{\partial x_n}(a) \\ \vdots & & \vdots \\ \frac{\partial f_m}{\partial x_1}(a) & \dots & \frac{\partial f_m}{\partial x_n}(a) \end{pmatrix} \cdot \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix}$$

$$= J_f(a) \cdot h.$$

Remark 9.28

It is possible that all partial derivatives exist at a without f being differentiable at a . Then the Jacobi matrix can be formed, but it does not represent the derivative $f'(a)$, which does not exist.

Remark 9.30

To check whether f is differentiable at a , one first verifies that f is partial differentiable at a . This is a necessary condition for the existence of $f'(a)$, by Proposition 9.28. Then one forms the Jacobi matrix $J_f(a)$ and considers the associated linear transformation $T \in \mathcal{L}(\mathbb{R}^n, \mathbb{R}^m)$, $T(h) = J_f(a)h$. Finally, one tests if $\lim_{x \rightarrow a} \frac{f(x) - f(a) - T(x-a)}{\|x-a\|} = 0$ holds. If this holds, then f is differentiable at a with derivative $f'(a) = T$.

The following example shows that a function can have all directional derivatives at a without being differentiable at a.

Example 8.31

Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ be defined by

$$f(x_1, x_2) = \begin{cases} 0 & \text{for } (x_1, x_2) = (0, 0) \\ \frac{|x_1| \cdot x_2}{\sqrt{x_1^2 + x_2^2}} & \text{for } (x_1, x_2) \neq (0, 0). \end{cases}$$

Then f has all directional derivatives at $(0, 0)$, but f is not differentiable at $(0, 0)$.

Proof

Let $v = (v_1, v_2) \in \mathbb{R}^2 \setminus \{(0, 0)\}$. Then

$$\begin{aligned} D_v f(0, 0) &= \lim_{t \rightarrow 0} \frac{f((0, 0) + tv) - f(0, 0)}{t} = \lim_{t \rightarrow 0} \frac{f(tv) - f(0, 0)}{t} = \lim_{t \rightarrow 0} \frac{f(tv)}{t} \\ &= \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{|tv_1| \cdot tv_2}{\sqrt{t^2 v_1^2 + t^2 v_2^2}} = \lim_{t \rightarrow 0} \frac{|v_1| \cdot v_2}{|t| \cdot \sqrt{v_1^2 + v_2^2}} \\ &= \lim_{t \rightarrow 0} \frac{|v_1| \cdot v_2}{\sqrt{v_1^2 + v_2^2}} = \frac{|v_1| \cdot v_2}{\sqrt{v_1^2 + v_2^2}}. \end{aligned}$$

It follows that $\frac{\partial f}{\partial x_1}(0, 0) = D_{e_1} f(0, 0) = \frac{|1| \cdot 0}{\sqrt{1+0}} = 0$ and

$\frac{\partial f}{\partial x_2}(0, 0) = D_{e_2} f(0, 0) = 0$. Thus, $\nabla f(0, 0) = (0 \ 0)$.

Assume now that f is differentiable at $(0, 0)$. By Proposition 8.28, we must have for all $v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in \mathbb{R}^2$:

$$f'(0, 0)(v) = \nabla f(0, 0) \cdot v = (0 \ 0) \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0.$$

Thus, $D_v f(0,0) = f'(0,0)(v) = 0$. Yet, the preceding computations yield for $v = (1,1)$ that $D_v f(0,0) = \frac{1}{\sqrt{2}}$.

We have got a contradiction. Thus, f is not differentiable at $(0,0)$. □

Proposition 9.32

Let D be open in \mathbb{R}^n , $a \in D$ and $f: D \rightarrow \mathbb{R}^m$. Assume that f is partial differentiable on D and that the partial derivatives $\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}$ are continuous at a .

Then f is differentiable at a and $f'(a)$ has as associate matrix the Jacobi matrix $J_f(a)$ of f at a .

Proof

By Propositions 9.15 and Remark 9.24, it follows that it is enough to consider the case $m=1$. We have to prove that $f: D \rightarrow \mathbb{R}$ is differentiable at a and that for all $h = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} \in \mathbb{R}^n$,

$$f'(a)(h) = J_f(a) \cdot h = \begin{pmatrix} \frac{\partial f}{\partial x_1}(a) & \dots & \frac{\partial f}{\partial x_n}(a) \end{pmatrix} \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix} = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(a) \cdot h_i.$$

Let $T \in \mathcal{L}(\mathbb{R}^n, \mathbb{R})$ be defined by $T(h) = \sum_{i=1}^n \frac{\partial f}{\partial x_i}(a) h_i$.

Let $\epsilon > 0$. Since for any $i=1, \dots, n$, the function $\frac{\partial f}{\partial x_i}: D \rightarrow \mathbb{R}$ is continuous at a , there exists $r_i > 0$ s.t. $U_{r_i}(a) \subseteq D$ and

$$(\forall x \in D) \left(x \in U_{r_i}(a) \implies \left| \frac{\partial f}{\partial x_i}(x) - \frac{\partial f}{\partial x_i}(a) \right| < \frac{\epsilon}{n} \right).$$

Let $r := \min_{i=1, \dots, n} r_i$. Then $U_r(a) \subseteq U_{r_i}(a) \subseteq D$ and

$$(1) (\forall i=1, \dots, n) (\forall \epsilon > 0) (x \in U_r(a) \implies \left| \frac{\partial f}{\partial x_i}(x) - \frac{\partial f}{\partial x_i}(a) \right| < \frac{\epsilon}{n}).$$

Let $x \in U_r(a)$. Then

$$\begin{aligned}
f(x) - f(a) - T(x-a) &= f(x_1, x_2, \dots, x_n) - f(a_1, a_2, \dots, a_n) - \sum_{i=1}^n \frac{\partial f}{\partial x_i}(a)(x_i - a_i) \\
&= \left[f(x_1, x_2, \dots, x_n) - f(a_1, x_2, \dots, x_n) - \frac{\partial f}{\partial x_1}(a)(x_1 - a_1) \right] + \\
&\quad + \left[f(a_1, x_2, \dots, x_n) - f(a_1, a_2, x_3, \dots, x_n) - \frac{\partial f}{\partial x_2}(a)(x_2 - a_2) \right] + \\
&\quad + \dots + \\
&\quad + \left[f(a_1, a_2, \dots, a_{n-1}, x_n) - f(a_1, a_2, \dots, a_n) - \frac{\partial f}{\partial x_n}(a)(x_n - a_n) \right].
\end{aligned}$$

For any $i=1, \dots, n$ let us define the real function

$$\varphi_i: [a_i, x_i] \rightarrow \mathbb{R}, \quad \varphi_i(t) = f(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a) \cdot t,$$

where we have assumed without loss of generality that $a_i \leq x_i$; the same reasoning applies when $x_i \leq a_i$.

Then for any $t \in [a_i, x_i]$ we have that $(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) \in D$

since $\|(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) - (a_1, \dots, a_n)\| = \|(0, \dots, 0, t - a_i, \dots, x_n - a_n)\|$

$$\begin{aligned}
&= \sqrt{(t - a_i)^2 + \sum_{k=i+1}^n (x_k - a_k)^2} \leq \sqrt{(x_i - a_i)^2 + \sum_{k=i+1}^n (x_k - a_k)^2} \leq \\
&\leq \|x - a\| < r, \text{ so } (a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n) \in U_r(a) \subseteq D.
\end{aligned}$$

It follows that $\varphi_i'(t) = \lim_{y \rightarrow t} \frac{\varphi_i(y) - \varphi_i(t)}{y - t}$

$$= \lim_{y \rightarrow t} \frac{f(a_1, \dots, a_{i-1}, y, x_{i+1}, \dots, x_n) - f(a_1, \dots, a_{i-1}, t, x_{i+1}, \dots, x_n)}{y - t}$$

$$-\frac{\partial f}{\partial x_i}(a) = \frac{\partial f}{\partial x_i}(a_1, \dots, a_{i-1}, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a)$$

Hence, φ_i is differentiable on $[a_i, x_i]$ so we can apply the Mean Value Theorem from Analysis I to get the existence of $\zeta_i \in]a_i, x_i[$ s.t.

$$\varphi_i(x_i) - \varphi_i(a) = \varphi_i'(\zeta_i)(x_i - a_i).$$

That is,

$$\begin{aligned} & f(a_1, \dots, a_{i-1}, x_i, x_{i+1}, \dots, x_n) - f(a_1, \dots, a_{i-1}, a_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a)(x_i - a_i) = \\ & = \left(\frac{\partial f}{\partial x_i}(a_1, \dots, a_{i-1}, \zeta_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a) \right) \cdot (x_i - a_i). \end{aligned}$$

Hence,

$$\begin{aligned} |f(x) - f(a) - T(x-a)| &\leq \sum_{i=1}^n \left| f(a_1, \dots, a_{i-1}, x_i, x_{i+1}, \dots, x_n) - f(a_1, \dots, a_{i-1}, a_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a)(x_i - a_i) \right| \\ &= \sum_{i=1}^n |\varphi_i(x_i) - \varphi_i(a_i)| = \sum_{i=1}^n \left| \frac{\partial f}{\partial x_i}(a_1, \dots, a_{i-1}, \zeta_i, x_{i+1}, \dots, x_n) - \frac{\partial f}{\partial x_i}(a) \right| \cdot |x_i - a_i| \\ &\stackrel{(1)}{<} \frac{\varepsilon}{n} \cdot \sum_{i=1}^n |x_i - a_i| \leq \frac{\varepsilon}{n} \cdot \sum_{i=1}^n \|x - a\| = \\ &= \frac{\varepsilon}{n} \cdot n \cdot \|x - a\| = \varepsilon \cdot \|x - a\|. \end{aligned}$$

Thus, we have got that

$$(\forall \varepsilon > 0) \left(x \in U_\varepsilon(a) \implies \frac{|f(x) - f(a) - T(x-a)|}{\|x-a\|} < \varepsilon \right)$$

This shows that $\lim_{x \rightarrow a} \frac{|f(x) - f(a) - T(x-a)|}{\|x-a\|} = 0$, that is f is differentiable and $f'(a) = T$.

Example 8.33

(i) The functions from Example 8.27 (i), (ii) and (iii) are differentiable on their domain, since they have continuous partial derivatives.

(ii) Let us consider the function defined in Example 8.27 (iv).

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}, f(x, y) = \sqrt[3]{x} \cdot \sqrt[3]{y}.$$

Then for $(x, y) \neq (0, 0)$ we have that $\frac{\partial f}{\partial x}(x, y) = \frac{1}{3} \frac{\sqrt[3]{y}}{\sqrt[3]{x^2}}$,

$$\frac{\partial f}{\partial y}(x, y) = \frac{1}{3} \frac{\sqrt[3]{x}}{\sqrt[3]{y^2}} \text{ and } \frac{\partial f}{\partial x}(0, 0) = \frac{\partial f}{\partial y}(0, 0) = 0.$$

It follows easily that $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}$ are continuous on $\mathbb{R}^2 \setminus \{(0, 0)\}$ but they are not continuous at $(0, 0)$.

Hence, f is differentiable on $\mathbb{R}^2 \setminus \{(0, 0)\}$ by Proposition 8.28.

In order to check differentiability at $(0, 0)$ we use Remark 8.30.

If f is differentiable at $(0, 0)$ then we must have $f'(0, 0)(h) = \nabla f(0, 0)h =$

$$= (0, 0) \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} = 0 \text{ for all } h = (h_1, h_2) \in \mathbb{R}^2. \text{ Hence, we must have}$$

$$\lim_{(x, y) \rightarrow (0, 0)} \frac{f(x, y) - f(0, 0) - 0}{\|(x, y)\|} = \lim_{(x, y) \rightarrow (0, 0)} \frac{\sqrt[3]{xy}}{\sqrt{x^2 + y^2}} = 0. \text{ It is easy to see}$$

that this is not true. Hence, f is not differentiable at $(0, 0)$. □