

4 Type-2 Theory of Effectivity

Definition 4.1. a) A (possibly partial) multifunction $f : \subseteq X \rightrightarrows Y$ is a subset of $X \times Y$.

$\text{dom}(f) := \{x \in X \mid \exists y \in Y : (x, y) \in f\}$ and $f(x) := \{y \in Y \mid (x, y) \in f\}$.

- b) A **Type-2 Machine** has an infinite read-only input tape, an infinite one-way output tape, and an unbounded work tape. It computes a (possibly partial) function $F : \subseteq \{0, 1\}^\omega \rightarrow \{0, 1\}^\omega$.
- c) A **representation** of a set X is a partial surjective mapping $\alpha : \subseteq \{0, 1\}^\omega \rightarrow X$. We call $\bar{\sigma} \in \alpha$ an α -**name** of $\alpha(\bar{\sigma})$. A point $x \in X$ is α -**computable** if it has a decidable α -name.
- d) Fix representations α of X and β of Y and a (possibly partial and multivalued) function $f : \subseteq X \rightrightarrows Y$. A (α, β) -**realizer** of f is a (partial but single-valued) function $F : \subseteq \{0, 1\}^\omega \rightarrow \{0, 1\}^\omega$ with $f(\alpha(\bar{\sigma})) \ni \beta(F(\bar{\sigma}))$ for every $\bar{\sigma} \in \text{dom}(F) := \{\bar{\sigma} \mid \alpha(\bar{\sigma}) \in \text{dom}(f)\}$.
- e) A function as in d) is (α, β) -**computable** if it has a computable (α, β) -realizer. It is (α, β) -**continuous** if it has a continuous realizer.
- f) We say that $U \subseteq X$ is α -**r.e.** if there exists a Turing machine which terminates precisely on input of all α -names of $\bar{x} \in U$ and diverges on all α -names of $\bar{x} \in X \setminus U$.

Example 4.2 a) Define a ρ -**name**^{*} of $x \in \mathbb{R}$ to be a sequence $a_n \in \mathbb{Z}$ (encoded in binary) such that $|x - a_n/2^{n+1}| \leq 2^{-n}$.

- b) Define a ρ_C -**name** of $x \in \mathbb{R}$ to be two sequences $q_n, \varepsilon_n \in \mathbb{Q}$ such that $|x - q_n| < \varepsilon_n \rightarrow 0$.
- c) A $\rho_{<}$ -**name** of $x \in \mathbb{R}$ is a sequence $b_n \in \mathbb{Z}$ with $\sup_n b_n/2^{n+1} = x$;
a $\rho_{>}$ -**name** of $x \in \mathbb{R}$ is a sequence $c_n \in \mathbb{Z}$ with $\inf_n c_n/2^{n+1} = x$.
- d) Define a ρ_n -**name** of $x \in \mathbb{R}$ to be a sequence $a_n \in \mathbb{Z}$ such that $\lim_n a_n/2^{n+1} = x$.
- e) Define a v -**name** of $y \in \mathbb{N}$ to be the string $1^y 0^\omega$. Define a v_b -**name** of $y \in \mathbb{N}$ to be the string $(b_0, 0, b_1, 0, \dots, b_{n-1}, 0, 1^\omega)$ where $y = b_0 + 2b_1 + \dots + 2^{n-1}b_{n-1} + 2^n - 1$.

Theorem 4.3. a) Every (oracle-)computable $F : \subseteq \{0, 1\}^\omega \rightarrow \{0, 1\}^\omega$ is continuous.

- b) To every continuous $F : \subseteq \{0, 1\}^\omega \rightarrow \{0, 1\}^\omega$, there exists an oracle relative to which F becomes computable.
- c) Every oracle-computable $f : [0; 1] \rightarrow \mathbb{R}$ is continuous!
- d) To every continuous $f : \mathbb{R} \rightarrow \mathbb{R}$ there is an oracle relative to which f becomes computable.
- e) Every (relatively) ρ -**r.e.** set $U \subseteq \mathbb{R}$ is open.
- f) Every open $U \subseteq \mathbb{R}$ is relatively ρ -**r.e.**
- g) The identity $\text{id} : \mathbb{N} \rightarrow \mathbb{N}$ is both (v, v_b) -computable and (v_b, v) -computable.

4.1 Constructing with, and Comparing, Representations

Definition 4.4. a) Write $\alpha \preceq \beta$ if $\text{id} : X \rightarrow X$ is (α, β) -computable.

- b) Let α_i be representations for X_i , $i \in I \subseteq \mathbb{N}$, and $\langle \cdot \mid \cdot \rangle : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$ a computable surjective pairing function. Define $(\sigma_m)_m$ to be a $(\prod_{i \in I} \alpha_i)$ -name of $(x_i)_i \in \prod_i X_i$ iff $(\sigma_{\langle i, n \rangle})_n$ is an α_i -name of $x_i \in X_i$ for every $i \in I$.
- c) For representations α, β of X let $\alpha \sqcap \beta := (\alpha \times \beta) \upharpoonright^{\Delta_X}$, where $\Delta_X := \{(x, x) \mid x \in X\}$.

* This is subtly different from the representation denoted by ρ in [7]

- d) A **name** of a continuous partial $F : \subseteq \{0, 1\}^\omega \rightarrow \{0, 1\}^\omega$ is a monotone $\hat{f} : \{0, 1\}^* \rightarrow \{0, 1\}^*$ (enumerating its table of arguments and values as some $f \in \{0, 1\}^\omega$) with $f_\omega|_{\text{dom}(F)} = F$.
- e) Fix representations α of X and β of Y . The representation $[\alpha \rightarrow \beta]$ of the set $R_{\alpha, \beta}[X, Y]$ of all (α, β) -realizable total $g : X \rightarrow Y$ is defined as follows: A $[\alpha \rightarrow \beta]$ -name of g is a name of an (α, β) -realizer of g .
- f) For multifunctions $f : \subseteq X \rightrightarrows Y$ and $g : \subseteq Y \rightrightarrows Z$, their **composition** is defined as

$$g \circ f := \{ (x, z) \mid x \in X, z \in Z, f(x) \subseteq \text{dom}(g), \exists y \in Y : (x, y) \in f \wedge (y, z) \in g \} . \quad (1)$$

Proposition 4.5. a) Let α, β, γ denote representations of X, Y, Z , respectively. If $f : \subseteq X \rightrightarrows Y$ is (α, β) -computable and $g : \subseteq Y \rightrightarrows Z$ is (β, γ) -computable, then their composition $g \circ f$ is (α, γ) -computable.

- b) For $\alpha \preceq \alpha'$ and $\beta \preceq \beta'$, $[\alpha' \rightarrow \beta] \preceq [\alpha \rightarrow \beta']$.
- c) Let α be a representation of X . Then $\alpha^\omega \preceq [\nu \rightarrow \alpha] \preceq \alpha^\omega$.
- d) Fix representations α of X and β of Y and γ of $R_{\alpha, \beta}[X, Y]$.
 $R_{\alpha, \beta}[X, Y] \times X \ni (g, x) \mapsto g(x) \in Y$ is $(\gamma \times \alpha, \beta)$ -computable iff $\gamma \preceq [\alpha \rightarrow \beta]$.
- e) Fix representations α of X and β of Y and γ of Z . Then type conversion

$$R_{\alpha \times \beta, \gamma}[X \times Y, Z] \times X \ni (g, x) \mapsto (Y \ni y \mapsto g(x, y) \in Z) \in R_{\beta, \gamma}[Y, Z] \quad (2)$$

is well-defined and $([\alpha \times \beta \rightarrow \gamma] \times \alpha, [\beta \rightarrow \gamma])$ -computable.

f) Also the converse conversion

$$\begin{aligned} R_{\alpha, [\beta \rightarrow \gamma]}[X, R_{\beta, \gamma}[Y, Z]] \ni (X \ni x \mapsto g(x, \cdot) \in R_{\beta, \gamma}[Y, Z]) \\ \mapsto (X \times Y \ni (x, y) \mapsto g(x, y) \in Z) \in R_{\alpha \times \beta, \gamma}[X \times Y, Z] \end{aligned}$$

is well-defined and $([\alpha \rightarrow [\beta \rightarrow \gamma]], [\alpha \times \beta \rightarrow \gamma])$ -computable.

4.2 Representing real functions and closed subsets

Definition 4.6. a) The representation $[\widehat{\rho^d \rightarrow \rho}]$ of $f \in C(\mathbb{R}^d)$ is defined as follows: A name is a double sequence $P_{n, m} \in \mathbb{D}[X_1, \dots, X_d]$ with $|f(\vec{x}) - P_{n, m}(\vec{x})| \leq 2^{-n}$ for all $\|\vec{x}\| \leq m$.

b) A nonempty closed set $A \subseteq \mathbb{R}^d$ is computable if the function

$$\text{dist}_A : \mathbb{R}^d \ni \vec{x} \mapsto \min \{ \|\vec{x} - \vec{a}\| : \vec{a} \in A \} \in \mathbb{R} \quad (3)$$

is computable. A Ψ^d -name of $A \in \mathcal{A}^{(d)}$ is a $[\rho^d \rightarrow \rho]$ -name of dist_A , where $\mathcal{A}^{(d)}$ denotes the space of nonempty closed subsets of \mathbb{R}^d .

- c) A $\Psi^d_{<}$ -name of A is a $(\prod_{m \in \mathbb{N}} \rho^d)$ -name of some sequence $\vec{x}_m \in A$ dense in A .
- d) A $\Psi^d_{>}$ -name of A are two sequences $\vec{q}_n \in \mathbb{Q}^d$ and $\varepsilon_n \in \mathbb{Q}$ such that

$$\mathbb{R}^d \setminus A = \bigcup_n B(\vec{q}_n, \varepsilon_n) \quad \text{where} \quad B(\vec{x}, r) := \{ \vec{y} : \|\vec{x} - \vec{y}\| < r \} . \quad (4)$$

- Theorem 4.7.** a) It holds $\rho \preceq \rho_{<} \sqcap \rho_{>} \preceq \rho_{\mathbb{C}} \preceq \rho$ and $[\rho^d \rightarrow \rho] \preceq [\rho^d \rightarrow \rho_{<}] \sqcap [\rho^d \rightarrow \rho_{>}] \preceq [\rho^d \rightarrow \rho]$.
- b) It holds $R_{\rho^d, \rho}[\mathbb{R}^d, \mathbb{R}] = C(\mathbb{R}^d, \mathbb{R})$ and $[\widehat{\rho^d \rightarrow \rho}] \preceq [\rho^d \rightarrow \rho] \preceq [\widehat{\rho^d \rightarrow \rho}]$
- c) Every $(\rho, \rho_{<})$ -computable $f : [0; 1] \rightarrow \mathbb{R}$ is lower semi-continuous.
- d) A set $A \in \mathcal{A}^{(d)}$ is $\psi_{>}^d$ -computable iff $\mathbb{R}^d \setminus A$ is ρ^d -r.e.
- e) Let $\|\cdot\|$ in Equation (4) denote any fixed computable norm.
Let $\|\cdot\|'$ denote some other norm on \mathbb{R}^d with induced representation $\psi_{>}^d$.
Then i) $\psi_{>}^d \preceq \psi_{>}^d$ and ii) $\psi_{<}^d \preceq \psi_{<}^d$.
- f) It holds $\psi^d \preceq \psi_{<}^d \sqcap \psi_{>}^d \preceq \psi^d$.
Moreover A is $\psi_{<}^d$ -computable iff dist_A is $(\rho^d, \rho_{>})$ -computable;
and A is $\psi_{>}^d$ -computable iff dist_A is $(\rho^d, \rho_{<})$ -computable.
- g) Union $\mathcal{A}^{(d)} \times \mathcal{A}^{(d)} \ni (A, B) \mapsto A \cup B \in \mathcal{A}^{(d)}$ is $(\psi^d \times \psi^d, \psi^d)$ -computable;
but intersection is not.
- h) Closed image $C(\mathbb{R}^d, \mathbb{R}^k) \times \mathcal{A}^{(d)} \ni (f, A) \mapsto \overline{f[A]} \in \mathcal{A}^{(k)}$ is $([\rho^d \rightarrow \rho^k] \times \psi_{<}^d, \psi_{<}^k)$ -computable.
- j) Preimage $C(\mathbb{R}^d, \mathbb{R}^k) \times \mathcal{A}^{(k)} \ni (f, B) \mapsto f^{-1}[B] \in \mathcal{A}^{(d)}$ is $([\rho^d \rightarrow \rho^k] \times \psi_{>}^k, \psi_{>}^d)$ -computable.
- k) $\{A \in \mathcal{A}^{(d)} : A \cap [0, 1]^d = \emptyset\}$ is $\psi_{>}^d$ -r.e.

6 Real Complexity Theory

6.2 Parameterized Type-2 Function Complexity

- Definition 6.1.** a) A partial function $F : \subseteq \Sigma^\omega \rightarrow \Sigma^\omega$ is *computable in time* $t : \mathbb{N} \rightarrow \mathbb{N}$ if a Type-2 Machine can, given $\bar{\sigma} \in \text{dom}(F)$, produce $\bar{\tau} = F(\bar{\sigma})$ such that the n -th symbol of $\bar{\tau}$ appears within $t(n)$ steps.
- b) For spaces X and Y with representations α and β , a partial multivalued $f : \subseteq X \rightrightarrows Y$ is *computable in time* $t(n)$ if it admits an (α, β) -realizer $F : \subseteq \Sigma^\omega \rightarrow \Sigma^\omega$ computable in time $t(n)$.

- Example 6.2** a) If $F : \subseteq \Sigma^\omega \rightarrow \Sigma^\omega$ is computable in time t , it has t as modulus of continuity.
- b) If $f : [0; 1] \rightarrow [0; 1]$ is $(\rho_{\mathbb{C}}, \rho)$ -computable in time t for some $t : \mathbb{N} \rightarrow \mathbb{N}$, f is constant.
- c) Every computable $f : [0; 1] \rightarrow \mathbb{R}$ is $(\rho, \rho_{\mathbb{C}})$ -computable in quadratic time.
- d) The following C^∞ 'pulse' function is computable in polynomial time:

$$[-1; 1] \ni x \mapsto \exp\left(-\frac{x^2}{1-x^2}\right), \quad [-1; 1] \not\ni x \mapsto 0$$

- e) If $F : \subseteq \Sigma^\omega \rightarrow \Sigma^\omega$ is computable and $\text{dom}(F)$ compact, then F is computable in some recursive time bound $t : \mathbb{N} \rightarrow \mathbb{N}$ depending on the output precision n only.
- f) Inversion $[2^{-K}; 1] \ni x \mapsto 1/x$ is (ρ, ρ) -computable in time polynomial in $n + K$.

6.3 Second-Order Representations

For $L > 0$ and for metric spaces (X, d) and (Y, e) let

$$\text{Lip}_L(X, Y) := \{f : X \rightarrow Y : e(f(x), f(x')) \leq L \cdot d(x, y)\}, \quad \text{Lip}(X, Y) := \bigcup_{L>0} \text{Lip}_L(X, Y) .$$

We may omit Y in case $Y = \mathbb{R}$.

- Problem 6.3** a) According to Example 6.2a), the evaluation operator $(F, \bar{\sigma}) \mapsto F(\bar{\sigma})$ admits no upper running time bound depending on the output precision n only.
- b) Moreover, even restricted to (the compact set of) non-expansive $F : \{0, 1\}^\omega \rightarrow \{0, 1\}^\omega$, the encoding of $F = f_\omega$ via the table of values of $f : \{0, 1\}^n \rightarrow \{0, 1\}^n$ makes evaluation computable in exponential time but no better.
- c) In fact the class $\text{Lip}_1([0; 1], [0; 1])$ of 1-Lipschitz $f : [0; 1] \rightarrow [0; 1]$ does not admit a representation rendering evaluation $(f, x) \mapsto f(x)$ computable in subexponential time.

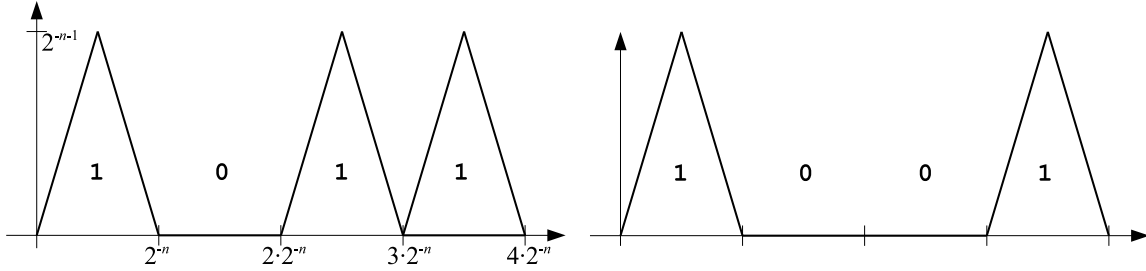


Fig. 1. Encoding the binary strings 1011 and 1001 into 1-Lipschitz functions f, g with $\|f - g\|$ not too small

Note that an implementation of the evaluation operator (e.g. in iRRAM) would *not* reasonably be provided with a function argument f as an infinite binary string but via ‘oracle’ access to approximate dyadic evaluation queries

$$\mathbb{Z} \times \mathbb{N} \ni (a, 2^n) \mapsto b \in \mathbb{N} \text{ s.t. } |f(a/2^{n+1}) - b/2^{n+1}| \leq 1/2^n .$$

- Definition 6.4.** a) An oracle Type-2 Machine \mathcal{M}^Ψ may write onto its query tape some $\vec{w} \in \Sigma^*$ which, when entered the designated query state, will be replaced with $\vec{v} := \Psi(\vec{w})$. (We implicitly employ some linear-time bicomputable self-delimited encoding on this tape such as $(w_1, \dots, w_n) \mapsto 1 w_1 1 w_2 \dots 1 w_n 0$.)
- b) \mathcal{M}^Ψ computes a partial mapping $\tilde{F} : \subseteq (\Sigma^*)^{\Sigma^*} \rightarrow (\Sigma^*)^{\Sigma^*}$ if, for every $\Psi \in \text{dom}(\tilde{F})$, \mathcal{M}^Ψ on input $\vec{v} \in \Sigma^*$ produces $\tilde{F}(\Psi)(\vec{v}) \in \Sigma^*$ and terminates.
- c) Let $\text{LM} \subseteq (\Sigma^*)^{\Sigma^*}$ denote the set of all total functions $\Psi : \Sigma^* \rightarrow \Sigma^*$ length-monotone in the sense of verifying

$$|\vec{v}| \leq |\vec{w}| \Rightarrow |\Psi(\vec{v})| \leq |\Psi(\vec{w})| . \quad (5)$$

Write $|\Psi| : \mathbb{N} \rightarrow \mathbb{N}$ for the (thus well-defined) mapping $|\vec{w}| \mapsto |\Psi(\vec{w})|$.

- d) A second-order representation for a space X is a surjective partial mapping $\tilde{\xi} : \subseteq \text{LM} \rightarrow X$.

Example 6.5 a) Any ordinary representation $\xi : \subseteq \{0, 1\}^\omega \rightarrow X$ induces a second-order representation $\tilde{\xi}$ as follows: Whenever $\bar{\sigma}$ is a ξ -name of x , then $\Psi : \Sigma^* \ni \vec{v} \mapsto \sigma_{|\vec{v}|} \in \Sigma$ is a $\tilde{\xi}$ -name of said x .

- b) (Re-)define a $\tilde{\rho}$ -name of $x \in \mathbb{R}$ to be a length-monotone mapping $\Psi : \{0, 1\}^* \rightarrow \{0, 1\}^*$ s.t.
- $$\left| x - \frac{\text{bin}(\Psi(\vec{w}))}{2^{|\vec{w}|+1}} \right| \leq 2^{-|\vec{w}|} \text{ for all } \vec{w} .$$

- c) Define a second-order representation $\rho^{\mathbb{D}}$ of $C[0;1]$ as follows: $\psi \in \text{LM}$ is a $\rho^{\mathbb{D}}$ -name of $f \in C[0;1]$ if, for all $\vec{w} \in \Sigma^*$, it holds

$$\left| \frac{\text{bin}(\psi(\vec{w}))}{2^{|\vec{w}|+1}} - f\left(\frac{\text{bin}(\vec{w})}{2^{|\vec{w}|+1}}\right) \right| \leq 2^{-|\vec{w}|} . \quad (6)$$

- d) Define a second-order representation $\rho^{\mathbb{D}} \sqcap L$ of $\text{Lip}[0;1]$ by saying that, whenever ψ is a $\rho^{\mathbb{D}}$ -name of $f \in \text{Lip}_{2^\ell}[0;1]$, then $\zeta : \Sigma^* \ni \vec{w} \mapsto 1^\ell 0 \circ \psi(\vec{w}) \in \Sigma^*$ is a $\rho^{\mathbb{D}} \sqcap L$ -name of f .
- e) Define a $[\widetilde{\rho \rightarrow \rho}]$ -name^{**} ψ of $f \in C[0;1]$ to be a mapping $\Sigma^* \ni \vec{w} \mapsto 1^{\mu(|\vec{w}|)} 0 \psi(\vec{w}) \in \Sigma^*$, where ψ denotes a $\rho^{\mathbb{D}}$ -name of f and $\mu : \mathbb{N} \rightarrow \mathbb{N}$ is a modulus of uniform continuity to it.

How ‘long’ are these names asymptotically? Relate $|\psi|(n)$ to quantitative properties of f . What is $|\psi|$ for names ψ w.r.t. a second-order representation induced by a first-order one?

6.4 Second-Order Polynomial-Time Complexity

Note that an oracle query $\vec{w} \mapsto \vec{v} := \psi(\vec{w})$ according to Definition 6.4b) may return a (much) longer answer for one argument ψ than for another ψ' . So in order to be able to even read such a reply, we have to consider as ‘polynomial’ a running time bound that depends on both n and $|\psi|$. The former being an integer and the latter an integer function, suggests

- Definition 6.6.** a) A *second-order polynomial* $P = P(n, \lambda)$ is a term composed from variable symbol n , unary function symbol $\lambda()$, binary function symbols $+$ and \times , and positive integer constants.
- b) Let $T : \mathbb{N} \times \mathbb{N}^{\mathbb{N}} \rightarrow \mathbb{N}$ be arbitrary. Oracle machine $\mathcal{M}^?$ computing $\tilde{F} : \subseteq \text{LM} \rightarrow \text{LM}$ according to Definition 6.4 operates in **time** T if, for every $\psi \in \text{dom}(\tilde{F})$ and every $\vec{v} \in \Sigma^*$, \mathcal{M}^ψ on input \vec{v} produces $F(\psi)(\vec{v})$ and terminates within at most $T(|\vec{v}|, |\psi|)$ steps.
- c) For second-order representations $\tilde{\xi}$ of X and $\tilde{\nu}$ of Y , a (possibly partial and multivalued) function $f : \subseteq X \rightrightarrows Y$ is $(\tilde{\xi}, \tilde{\nu})$ -computable in time T iff f has a $(\tilde{\xi}, \tilde{\nu})$ -realizer \tilde{F} computable in this time.
- d) Second-order polytime computability means computability in time P for some second-order polynomial P .

Computations on ‘long’ names ψ are thus allotted more time and still considered polynomial.

Example 6.7 a) $\lambda(n + \lambda(n^2 + 3n)) \cdot n \cdot \lambda^3(n) \cdot n$ is a second-order polynomial.

b) Second-order polynomials are closed under both kinds of composition:

$$(Q \circ P)(n, \lambda) := Q(P(n, \lambda), \lambda) \quad \text{and} \quad (Q \bullet P)(n, \lambda) := Q(n, P(\cdot, \lambda)) . \quad (7)$$

- c) Addition and multiplication are 2nd-order polytime $\tilde{\rho}$ -computable on \mathbb{R} ; but $x \mapsto e^x$ is not.
- d) Fix ordinary representations ξ of X and ν of Y with induced second-order representations $\tilde{\xi}$ and $\tilde{\nu}$. Then $f : \subseteq X \rightrightarrows Y$ is polytime (ξ, ν) -computable iff it is second-order polytime $(\tilde{\xi}, \tilde{\nu})$ -computable.

^{**} in [3] called a δ_{\square} -name

- e) Evaluation $\text{Lip}[0; 1] \times [0; 1] \ni (f, x) \mapsto f(x)$ is $(\rho^{\mathbb{D}} \sqcap L \times \tilde{\rho}, \tilde{\rho})$ -computable in second-order polytime.
- f) Evaluation $C[0; 1] \times [0; 1] \ni (f, x) \mapsto f(x)$ is $(\widetilde{[\rho \rightarrow \rho]} \times \tilde{\rho}, \tilde{\rho})$ -computable in second-order polytime.

- Definition 6.8.** a) Write $\text{PRED} \subseteq \text{LM}$ for the class of $\psi : \Sigma^* \rightarrow \{0, 1\}$.
- b) Let \mathcal{P}^2 denote the class of $\tilde{F} : \subseteq \text{LM} \rightarrow \text{PRED}$ computable by an oracle Type-2 Machine in second-order polytime.
- c) Let \mathcal{NP}^2 denote the class of $\tilde{F} : \subseteq \text{LM} \rightarrow \text{PRED}$ computable by a non-deterministic oracle Type-2 Machine in second-order polytime.
- d) We may identify a $\tilde{F} : \subseteq \text{LM} \rightarrow \text{PRED}$ with the set $\{(\psi, \vec{v}) : \psi \in \text{dom}(\tilde{F}), \vec{v} \in \Sigma^*, \tilde{F}(\psi, \vec{v}) = 1\}$ considered as a promise (second-order decision) problem.

Example 6.9 The following problem EXIST^2 belongs to \mathcal{NP}^2 but not to \mathcal{P}^2 :

$$\{(P, \vec{x}) : P \in \text{PRED}, \exists \vec{y} \in \Sigma^{|\vec{x}|} : P(\langle \vec{x}, \vec{y} \rangle) = 1\}$$

6.5 Reductions

Definition 6.10. Fix spaces A, B, X, Y with respective (ordinary or second-order) representations α, β, ξ, ν . Consider (possibly multivalued but total) functions $f : A \rightrightarrows B$ and $g : X \rightrightarrows Y$.

- a) Call f **computably** $(\alpha, \beta, \xi, \nu)$ -**reducible** to g if there exist multi-functions $r : A \rightrightarrows X$, (α, ξ) -computable, and $s : Y \times A \rightrightarrows B$, $(\nu \times \alpha, \beta)$ -computable, such that for all $a \in A$ it holds $s(g(r(a)), a) \subseteq f(a)$.
- b) The above functions r and s constitute a (second-order) polytime reduction if they are (second-order) polytime computable.

Example 6.11 Consider the following multivalued mappings:

$$\begin{aligned} - \text{LLPO} : \{0, 1\}^\omega \ni \vec{\sigma} &\rightrightarrows \begin{cases} \{0^\omega\} & : \exists! n : \sigma_n = 1, n \text{ even} \\ \{1^\omega\} & : \exists! n : \sigma_n = 1, n \text{ odd} \\ \{0^\omega, 1^\omega\} & : \forall n : \sigma_n = 0 \\ \{\} & : \exists n \neq m : \sigma_n = 1 = \sigma_m \end{cases} \\ - \text{B}_I : \{(a, b) : 0 \leq a \leq b \leq 1\} &\ni (a, b) \rightrightarrows y \in [a, b] \subseteq [0; 1] \\ - \text{IVT} : \{f : [0; 1] \rightarrow [-1; 1] \text{ continuous s.t. } f(0) < 0 < f(1)\} &\ni f \rightrightarrows x \in f^{-1}[0] \subseteq [0; 1] \end{aligned}$$

- a) Every $\tilde{F} \in \mathcal{NP}^2$ is second-order polytime reducible to EXIST^2 .
- b) $\text{MAX} : C[0; 1] \rightarrow C[0; 1]$ is 2nd-order polytime $(\widetilde{[\rho \rightarrow \rho]}, \widetilde{[\rho \rightarrow \rho]}, \text{id}, \text{id})$ -reducible to EXIST^2
- c) and EXIST^2 is second-order polytime $(\text{id}, \text{id}, \widetilde{[\rho \rightarrow \rho]}, \widetilde{[\rho \rightarrow \rho]})$ -reducible to $\text{MAX}|_{C^\infty[0; 1]}$.
- d) LLPO is not computable;
 B_I is not $(\rho_{<} \times \rho_{>}, \rho)$ -computable and IVT is not $([\rho \rightarrow \rho], \rho)$ -computable.
- e) LLPO is $(\text{id}, \text{id}, \rho_{<} \times \rho_{>}, \rho)$ -reducible to B_I .
- f) IVT is $([\rho \rightarrow \rho], \rho, \rho_{<} \times \rho_{>}, \rho)$ -reducible to B_I .
- g) B_I is $(\rho_{<} \times \rho_{>}, \rho, [\rho \rightarrow \rho], \rho)$ -reducible to IVT .

7 A View on the Practical Side: iRRAM

- Restricted to $f : [0; 1] \rightarrow \mathbb{R}$ with $f(0) < 0 < f(1)$ and a *unique* root, this root can be found computably: How?
- REAL semantics provided by iRRAM via automatic re-iteration
- multivalued intrinsic functions;
e.g. `bool bound (const REAL& x, const long k)` where

$$\text{bound}(x, k) = \begin{cases} \text{true} & : |x| \leq 2^{k-2} \\ \text{false} & : |x| > 2^k \\ \text{true or false} & : 2^k \geq |x| > 2^{k-2} \end{cases}$$

- lazy Booleans and branching on multivalued tests

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