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# Analysis III – Complex Analysis

## Hints for solution for the

### 2. Exercise Sheet



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#### Groupwork

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#### Exercise G1 (Cauchy-Riemann differential equations I)

Consider the function  $f(z) := e^z$ . Use the Cauchy-Riemann differential equations to prove that  $f$  is differentiable on the whole complex plane.

**Hints for solution:** We compute the real vector field for  $f$ :

$$\begin{aligned} F(x, y) &= \begin{pmatrix} \operatorname{Re}f(x + y \cdot i) \\ \operatorname{Im}f(x + y \cdot i) \end{pmatrix} = \begin{pmatrix} \operatorname{Re}(e^x \cdot e^{yi}) \\ \operatorname{Im}(e^x \cdot e^{yi}) \end{pmatrix} \\ &= \begin{pmatrix} e^x \cdot \cos(y) \\ e^x \cdot \sin(y) \end{pmatrix}. \end{aligned}$$

The Jacobian von  $F$  is of course:

$$J_F(x, y) = e^x \cdot \begin{pmatrix} \cos(y) & -\sin(y) \\ \sin(y) & \cos(y) \end{pmatrix}.$$

The Cauchy-Riemann differential equations are obviously satisfied.

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**Exercise G2** (Cauchy-Riemann differential equations II)

Consider the function  $f(x + y \cdot i) := x^3 \cdot y^2 + x^2 \cdot y^3 \cdot i$  defined on the whole complex plane. Determine the subset  $\Omega \subseteq \mathbb{C}$  on which  $f$  has a complex derivative. Is there an inner point  $z_0 \in \Omega$ ?

**Hints for solution:** We compute the real vector field for  $f$ :

$$F(x, y) = \begin{pmatrix} \operatorname{Re}f(x + y \cdot i) \\ \operatorname{Im}f(x + y \cdot i) \end{pmatrix} = \begin{pmatrix} x^3 \cdot y^2 \\ x^2 \cdot y^3 \end{pmatrix}$$

The Jacobian von  $F$  is of course:

$$J_F(x, y) = \begin{pmatrix} 3x^2 \cdot y^2 & 2x^3 \cdot y \\ 2x \cdot y^3 & 3x^2 \cdot y^2 \end{pmatrix}.$$

The Cauchy-Riemann differential equations are satisfied, iff  $x = 0$  or  $y = 0$ . So we have

$$\Omega = \{z \in \mathbb{C} : \operatorname{Re}z = 0 \text{ or } \operatorname{Im}z = 0\}.$$

Of course the interior of  $\Omega$  is empty.

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### Exercise G3 (Path integrals)

Consider the vector field

$$\mathbb{R}^2 \ni (x, y) \rightarrow F(x, y) := \frac{1}{(x^2 + y^2 + 1)^2} \begin{pmatrix} -x^2 + y^2 + 1 \\ -2xy \end{pmatrix} \in \mathbb{R}^2.$$

Determine  $\int_{\gamma_1} F ds$  and  $\int_{\gamma_2} F ds$  for the paths  $\gamma_1 : [-1, 1] \rightarrow \mathbb{R}^2$  and  $\gamma_2 : [0, \pi] \rightarrow \mathbb{R}^2$  given by

$$\gamma_1(t) := \begin{pmatrix} -t \\ 0 \end{pmatrix} \quad \text{and} \quad \gamma_2(t) := \begin{pmatrix} \cos(t) \\ \sin(t) \end{pmatrix}.$$

**Hints for solution:** We write in this hint for solution  $x \cdot y := \langle x, y \rangle$  for vectors  $x$  and  $y$  and we write vectors as row vectors.

Let  $W := \gamma_1$ :

$$W : [-1, 1] \rightarrow \mathbb{R}^2, \quad W(t) = (-t, 0)$$

and let  $Z := \gamma_2$ :

$$Z : [0, \pi] \rightarrow \mathbb{R}^2, \quad Z(t) = (\cos(t), \sin(t)).$$

We get

$$\begin{aligned} \int_W F dt &= \int_{-1}^1 F(W(t)) \cdot \dot{W}(t) dt = \int_{-1}^1 \left( \frac{-t^2 + 1}{(t^2 + 1)^2}, 0 \right) \cdot (-1, 0) dt = \\ &= \int_{-1}^1 \frac{t^2 - 1}{(t^2 + 1)^2} dt = -\frac{t}{t^2 + 1} \Big|_{-1}^1 = -1, \end{aligned}$$

$$\begin{aligned} \int_Z F dt &= \int_0^\pi F(Z(t)) \cdot \dot{Z}(t) dt = \int_0^\pi \left( \frac{-\cos(2t) + 1}{4}, \frac{-\sin(2t)}{4} \right) \cdot (-\sin(t), \cos(t)) dt = \\ &= \int_0^\pi \frac{\cos(2t) \sin(t) - \sin(t) - \sin(2t) \cos(t)}{4} dt = \\ &= \int_0^\pi \frac{\sin(-2t) \cos(t) + \cos(-2t) \sin(t) - \sin(t)}{4} dt = \int_0^\pi \frac{\sin(-2t + t) - \sin(t)}{4} dt = \\ &= \int_0^\pi \frac{-\sin(t)}{2} dt = \frac{\cos(t)}{2} \Big|_0^\pi = -1. \end{aligned}$$

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**Exercise G4** (Elementary properties of the path integral)

Let  $F, G : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be continuously differentiable vector fields. Further let  $\gamma, \gamma_1 : [a, b] \rightarrow \mathbb{R}^n$  and  $\gamma_2 : [b, c] \rightarrow \mathbb{R}^n$  be continuously differentiable paths. Show that the path integral has the following properties:

(a) 
$$\int_{\gamma} \lambda F + \mu G ds = \lambda \int_{\gamma} F ds + \mu \int_{\gamma} G ds.$$

(b) 
$$\int_{\gamma_1 + \gamma_2} F ds = \int_{\gamma_1} F ds + \int_{\gamma_2} F ds.$$

(c) If  $\varphi : [\alpha, \beta] \rightarrow [a, b]$  is a diffeomorphism with  $\varphi'(t) > 0$  then 
$$\int_{\gamma} F ds = \int_{\gamma \circ \varphi} F ds.$$

Interprete part (c) in the special case of a “vector field”  $F : \mathbb{R} \supseteq [a, b] \rightarrow \mathbb{R}$  and the path  $\gamma : [a, b] \rightarrow \mathbb{R}, \gamma(t) = t$ .

**Hints for solution:** Standard Calculations. Part (c) is a multi dimensional version of integration by substitution.

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**Exercise G5** (Rotation of a vector field and a two dimensional version of Stoke's theorem)

Let  $\Omega \subseteq \mathbb{R}^2$  be an open subset and  $f : \mathbb{R}^2 \supseteq \Omega \rightarrow \mathbb{R}^2$  be a continuously differentiable vector field. Further let  $\nu \in \Omega$  be an arbitrary point and  $\varepsilon > 0$ . Assume that the closed square with side length  $\varepsilon$  and center  $\nu$  is contained in  $\Omega$  and let  $\gamma$  be the canonical parametrisation of the boundary of this square, i. e. it is counterclockwisely orientated.

(a) Prove that

$$\lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^2} \int_{\gamma} f ds = \text{rot}(f)(\nu),$$

where  $\text{rot}(f)(x, y) := \frac{\partial f_2}{\partial x}(x, y) - \frac{\partial f_1}{\partial y}(x, y)$  defines the rotation of  $f$ .

(b) Prove Stoke's theorem in the two dimensional case:

Let  $f : \mathbb{R}^2 \supseteq \Omega \rightarrow \mathbb{R}^2$  be a continuously differentiable vector field and  $R := [a, b] \times [c, d]$  be a rectangle with  $R \subseteq \Omega$ . If  $\gamma$  is the canonical parametrisation of the boundary of  $R$  then the following equation holds:

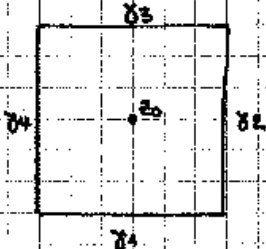
$$\int_{\gamma} f ds = \int_c^d \int_a^b \text{rot}(f)(x, y) dx dy.$$

**Hint:** Use Fubini's theorem.

**Hints for solution:**

This is purely analysis:

u=1

(G2) = 

$\gamma_1: t \mapsto \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + t \begin{pmatrix} \epsilon \\ 0 \end{pmatrix} \quad t \in [0,1]$   
 $\gamma_2: t \mapsto \begin{pmatrix} x_0 + \epsilon/2 \\ y_0 - \epsilon/2 \end{pmatrix} + t \begin{pmatrix} 0 \\ \epsilon \end{pmatrix} \quad t \in [0,1]$   
 $\gamma_3: t \mapsto \begin{pmatrix} x_0 + \epsilon/2 \\ y_0 + \epsilon/2 \end{pmatrix} + t \begin{pmatrix} -\epsilon \\ 0 \end{pmatrix} \quad t \in [0,1]$   
 $\gamma_4: t \mapsto \begin{pmatrix} x_0 - \epsilon/2 \\ y_0 + \epsilon/2 \end{pmatrix} + t \begin{pmatrix} 0 \\ -\epsilon \end{pmatrix} \quad t \in [0,1]$

$$\int_{\gamma} f ds = \sum_{i=1}^4 \int_{\gamma_i} f ds$$

$$= \int_0^1 f(\gamma_1(t)) \begin{pmatrix} \epsilon \\ 0 \end{pmatrix} dt + \int_0^1 f(\gamma_2(t)) \begin{pmatrix} 0 \\ \epsilon \end{pmatrix} dt + \int_0^1 f(\gamma_3(t)) \begin{pmatrix} -\epsilon \\ 0 \end{pmatrix} dt + \int_0^1 f(\gamma_4(t)) \begin{pmatrix} 0 \\ -\epsilon \end{pmatrix} dt$$

$$= \int_0^1 f_1 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + \epsilon \begin{pmatrix} t-1/2 \\ -1/2 \end{pmatrix} \right) \epsilon - f_1 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \epsilon \begin{pmatrix} t-1/2 \\ -1/2 \end{pmatrix} \right) \epsilon$$

$$+ f_2 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + \epsilon \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix} \right) \epsilon - f_2 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \epsilon \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix} \right) \epsilon dt$$

$$\frac{1}{\epsilon^2} \int_{\gamma} f ds = \frac{1}{\epsilon} \int_0^1 f_1 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + \epsilon \begin{pmatrix} t-1/2 \\ -1/2 \end{pmatrix} \right) - f_1 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \epsilon \begin{pmatrix} t-1/2 \\ -1/2 \end{pmatrix} \right)$$

$$+ f_2 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + \epsilon \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix} \right) - f_2 \left( \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} - \epsilon \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix} \right) dt$$

Nullen  
verschieben

$$= \int_0^1 \frac{f_1(z_0 + \epsilon \begin{pmatrix} t-1/2 \\ -1/2 \end{pmatrix}) - f_1(z_0)}{\epsilon - 0} + \frac{f_2(z_0) - f_2(z_0 - \epsilon \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix})}{0 - (-\epsilon)} dt$$

$$+ \frac{f_2(z_0 + \epsilon \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix}) - f_2(z_0)}{\epsilon - 0} + \frac{f_2(z_0) - f_2(z_0 - \epsilon \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix})}{0 - (-\epsilon)} dt$$

Richt'abl.  
erkennen

$$\lim_{\epsilon \rightarrow 0} \int_{\gamma} f ds = \int_0^1 \left( \frac{\partial f_1}{\partial x}, \frac{\partial f_1}{\partial y} \right)(z_0) \cdot \begin{pmatrix} t-1/2 \\ -1/2 \end{pmatrix} + \left( \frac{\partial f_1}{\partial x}, \frac{\partial f_1}{\partial y} \right)(z_0) \cdot \begin{pmatrix} t-1/2 \\ -1/2 \end{pmatrix}$$

$$+ \left( \frac{\partial f_2}{\partial x}, \frac{\partial f_2}{\partial y} \right)(z_0) \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix} + \left( \frac{\partial f_2}{\partial x}, \frac{\partial f_2}{\partial y} \right)(z_0) \begin{pmatrix} 1/2 \\ t-1/2 \end{pmatrix} dt$$

$$= 2 \int_0^1 \frac{\partial f_1}{\partial x}(z_0) \left( t - \frac{1}{2} \right) - \frac{\partial f_1}{\partial y}(z_0) \cdot \frac{1}{2} + \frac{\partial f_2}{\partial x}(z_0) \cdot \frac{1}{2} + \frac{\partial f_2}{\partial y}(z_0) \left( t - \frac{1}{2} \right) dt$$

$$= 2 \cdot \left[ \frac{\partial f_1}{\partial x}(z_0) \left( \frac{t^2}{2} - \frac{t}{2} \right) - \frac{\partial f_1}{\partial y}(z_0) \frac{t}{2} + \frac{\partial f_2}{\partial x}(z_0) \frac{t}{2} + \frac{\partial f_2}{\partial y}(z_0) \left( \frac{t^2}{2} - \frac{t}{2} \right) \right]_0^1$$

$$= - \frac{\partial f_1}{\partial y}(z_0) + \frac{\partial f_2}{\partial x}(z_0)$$

(G3) Zunächst stellen wir fest, daß  $Z$  kompakt ist,  $f$  und seine partiellen Ableitungen stetig sind, wir können also den Satz von Fubini anwenden (\*)

$$\int_c^d \int_a^b \frac{\partial f}{\partial x} - \frac{\partial f}{\partial y} dx dy \stackrel{(*)}{=} \int_c^d \int_a^b \frac{\partial f}{\partial x} dx dy - \int_c^d \int_a^b \frac{\partial f}{\partial y} dy dx$$

$$= \int_c^d [f_z(b,y) - f_z(a,y)] dy - \int_a^b [f_z(x,d) - f_z(x,c)] dx = (A)$$

Wir setzen

$$\left. \begin{aligned} \gamma_1(t) &= \begin{pmatrix} b \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \end{pmatrix}, t \in [c, d] \\ \gamma_2(t) &= \begin{pmatrix} a \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \end{pmatrix}, t \in [c, d] \\ \gamma_3(t) &= \begin{pmatrix} a \\ c \end{pmatrix} + t \begin{pmatrix} 1 \\ 0 \end{pmatrix}, t \in [a, b] \\ \gamma_4(t) &= \begin{pmatrix} b \\ c \end{pmatrix} + t \begin{pmatrix} 1 \\ 0 \end{pmatrix}, t \in [a, b] \end{aligned} \right\} \begin{aligned} \gamma'(t) &= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ \gamma'(t) &= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{aligned}$$

und erhalten somit

$$(A) = \int_c^d f(\gamma_1(t)) \gamma_1'(t) dt - \int_c^d f(\gamma_2(t)) \gamma_2'(t) dt$$

$$- \int_a^b f(\gamma_3(t)) \gamma_3'(t) dt + \int_a^b f(\gamma_4(t)) \gamma_4'(t) dt$$

$$= \int_{\gamma_1} f ds - \int_{\gamma_2} f ds - \int_{\gamma_3} f ds + \int_{\gamma_4} f ds$$



$$= \int_{\gamma} f ds$$

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## Homework

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### Exercise H1 (Connectedness and path-connectedness)

(1 point)

Let  $(X, d)$  a metric space. The space  $X$  is called *connected*, if the only subsets of  $X$  which are both open and closed are  $X$  and the empty set.

(a) Prove that the following conditions are equivalent:

(i) The space  $X$  is connected.

(ii) If  $X = A \cup B$  for open sets  $A$  and  $B$  with  $A \cap B = \emptyset$ , then  $A = \emptyset$  or  $B = \emptyset$ .

(iii) If  $X = A \cup B$  for closed sets  $A$  and  $B$  with  $A \cap B = \emptyset$ , then  $A = \emptyset$  or  $B = \emptyset$ .

(iv) Every continuous function  $f : X \rightarrow \{0, 1\}$  is constant.

(b) Is there a metric on  $\mathbb{R}$  such that  $(\mathbb{R}, d)$  is disconnected, i. e. not connected? Prove your claim.

(c) Show that every path connected metric space is connected.

(d) Let

$$\Gamma := \left\{ \left( x, \sin \left( \frac{1}{x} \right) \right)^T : 0 < x \leq 1 \right\} \subseteq \mathbb{R}^2.$$

Define  $X := \bar{\Gamma}$  where the closure is taken in the natural metric. Then  $(X, d)$  is a metric space with  $d(x, y) := \|x - y\|_2$ . Sketch the set  $X$  and show that  $X$  is connected but not path connected.

### Hints for solution:

(a) (i)  $\Rightarrow$  (ii): Let  $X = A \cup B$  with  $A \cap B = \emptyset$  and  $A$  open and  $B$  open. Then  $B = A^c$  is a closed set. So  $A$  is open and closed. By (i) we have  $A \in \{\emptyset, X\}$  so  $B \in \{\emptyset, X\}$ .

(ii)  $\Leftrightarrow$  (iii) Cause  $A = B^c$  and  $B = A^c$  these conditions are trivially equivalent.

(ii)  $\Rightarrow$  (i) Let  $A \subseteq X$  be open and closed. Then  $A^c$  is open and closed, too. Further we have  $X = A \cup A^c$  with  $A \cap A^c = \emptyset$ . By (ii) we have  $A \in \{\emptyset, X\}$ , so there is no nontrivial open and closed subset of  $X$ .

(i)  $\Rightarrow$  (iv): Assume there is a surjective  $f : X \rightarrow \{0, 1\}$  then  $A = f^{-1}(\{0\})$  is open and closed and not empty and  $B = f^{-1}(\{1\})$  is open and closed and not empty since  $\{0, 1\}$  is discrete. So  $X$  is disconnected.

(iv)  $\Rightarrow$  (iii): Assume,  $X = A \cup B$  with  $A \cap B = \emptyset$  and  $A$  closed and  $B$  closed. Define

$$f(x) = \begin{cases} 1 & x \in A \\ 0 & x \in B. \end{cases}$$

Since the preimage of closed sets in  $\{0, 1\}$  is closed in  $X$ , the function  $f$  is continuous and not constant.

(b) Choose the discrete metric on  $\mathbb{R}$ , i. e.

$$d(x, y) = \begin{cases} 0 & x = y \\ 42 & x \neq y \end{cases}.$$

Then the set  $A := \{42\}$  is closed and we have  $A = K_\varepsilon(42)$  with  $\varepsilon = \frac{1}{42}$ . It follows that  $A$  is open. Of course, every subset  $B \subset \mathbb{R}$  in the discrete topology is open and closed.



- (c) Assume  $(X, d)$  to be path connected and let  $A \subseteq X$  be open and closed. Define a function  $f : X \rightarrow \{0, 1\}$  by

$$f(x) = \begin{cases} 1 & x \in A \\ 0 & x \notin A \end{cases}.$$

This function is continuous since every preimage of an open set  $B \subset \{0, 1\}$  (of course with discrete topology, i. e. discrete metric) is open in  $X$ . Let  $a \in A$  and  $b \in X$  be arbitrary. Then by path connectedness there is a continuous path  $\gamma : [0, 1] \rightarrow X$  with  $\gamma(0) = a$  and  $\gamma(1) = b$ . Then of course the function  $f \circ \gamma : [0, 1] \rightarrow \{0, 1\}$  is a continuous path, too. Since this path must be constant, we have  $f(\gamma(1)) = f(\gamma(0)) = 1$ . So we have  $b = \gamma(1) \in A$  and since  $b \in X$  was arbitrary we conclude  $A = X$ . So  $X$  is connected.

- (d) The set  $X$  is the union of the graph of  $\varphi : ]0, 1] \rightarrow \mathbb{R}$ ,  $\varphi(x) = \sin(1/x)$  and the strip of accumulation points  $S := \{(0, y)^T : -1 \leq y \leq 1\}$ . This is easy to show by using the continuity of  $\varphi$  on  $]0, 1]$  and the fact, every  $t \in [-1, 1]$  is a limit of the image of a nullsequence under the map  $\varphi$ .

We have  $X = \Gamma \cup S$ . This is a disjoint union of path connected subsets. Assume  $X = A \cup B$  as a disjoint union of both open and closed sets  $A$  and  $B$ . Then there is a continuous function  $g : X \rightarrow \{0, 1\}$  with  $g(a) = 0$  for all  $a \in A$  and  $g(b) = 1$  for all  $b \in B$ . We have  $\text{obd} A \subseteq A$ . Since  $S$  is not open, there is a subset  $C \subseteq X$  with  $A = S \cup C$  and  $S \cap C = \emptyset$ . But for every  $c \in C$  and every  $x \in \Gamma$  there is a continuous path  $\gamma : [0, 1] \rightarrow X$  with  $\gamma(0) = c$  and  $\gamma(1) = x$ . We conclude  $A = X$  and  $B = \emptyset$ , so  $X$  is connected.

We have to show that  $X$  is not path connected. Choose  $x = (1, \sin(1))$  and assume there is for a  $s \in S$  a path  $\gamma$  with  $\gamma(0) = x$  and  $\gamma(1) = s$ . Since  $S$  is closed there is a smallest number  $a \in [0, 1]$  with  $\gamma(t) \in \Gamma$  for  $0 \leq t < a$  and  $s := \gamma(a) \in S$ . Let  $p$  be the projection map  $p : X \rightarrow \mathbb{R}$ ,  $p(x, y) := x$ . This map is continuous. Define for  $n > 0$  the set  $K_n := K_{\frac{1}{n}}(s)$ . We have  $\Gamma \cap K_n \neq \emptyset$  and  $p(K_n) \subseteq [0, \frac{1}{n}]$ . Since  $\gamma : [0, a] \rightarrow X$  is a continuous path from  $x$  to  $s$  and the map  $p \circ \gamma$  is continuous, we have by the intermediate value theorem  $p \circ \gamma([0, a]) = [0, 1]$ : The preimage of  $K_n$  under  $\gamma^{-1}$  is an open subset of  $[0, 1]$ . This means there is for every  $n > 0$  a point  $t \in [0, a[$  with  $\gamma(t) \in K_n$  and we follow  $\Gamma \subseteq \gamma([0, a])$ . Now there are different ways to prove that this path can't exist. The first way:  $\gamma : [0, a] \rightarrow X$  is uniformly continuous since  $[0, a]$  is compact. This means there is a  $\delta > 0$  with  $|s - t| \leq \delta \Rightarrow \|\gamma(s) - \gamma(t)\| \leq \frac{1}{2}$ . But for  $s_n = \frac{2}{n\pi}$  and  $t_n = \frac{2}{(n+1)\pi}$  one can choose  $n > 0$  large enough to get a contradiction.

The second way: The image  $\gamma([0, a])$  is compact especially closed in  $X$ . But we have  $\gamma([0, a]) \cap S = \{s\}$  and  $X = \overline{\gamma([0, a])} = \gamma([0, a]) \neq X$  is a contradiction.

**Exercise H2** (Curves, path length and rectifiability I)

(1 point)

We first introduce some notation. A *partition*  $Z$  of  $[0, 1]$  is given by a finite ordered subset  $Z = \{t_0, \dots, t_n\}$  with  $0 = t_0 < t_1 < t_2 < \dots < t_n = 1$ . For simplicity we write  $Z = \{t_0, \dots, t_n\}$ .

Let  $\gamma : [0, 1] \rightarrow \mathbb{R}^n$  be a continuously differentiable path and  $Z$  a Partition of  $[0, 1]$ . We define piecewise a new path  $\gamma_Z : [0, 1] \rightarrow \mathbb{R}^n$ : For  $t \in [t_n, t_{n+1}]$  we set

$$\gamma_Z(t) := \frac{t_{n+1} - t}{t_{n+1} - t_n} \cdot \gamma(t_n) + \frac{t - t_n}{t_{n+1} - t_n} \cdot \gamma(t_{n+1}).$$

Then  $\gamma_Z$  approximates  $\gamma$  by a polygon.

To understand this we consider an example: Let  $\gamma : [0, 1] \rightarrow \mathbb{R}^2$  defined by

$$\gamma(t) := \begin{pmatrix} \cos(\pi \cdot t) \\ \sin(\pi \cdot t) \end{pmatrix}.$$

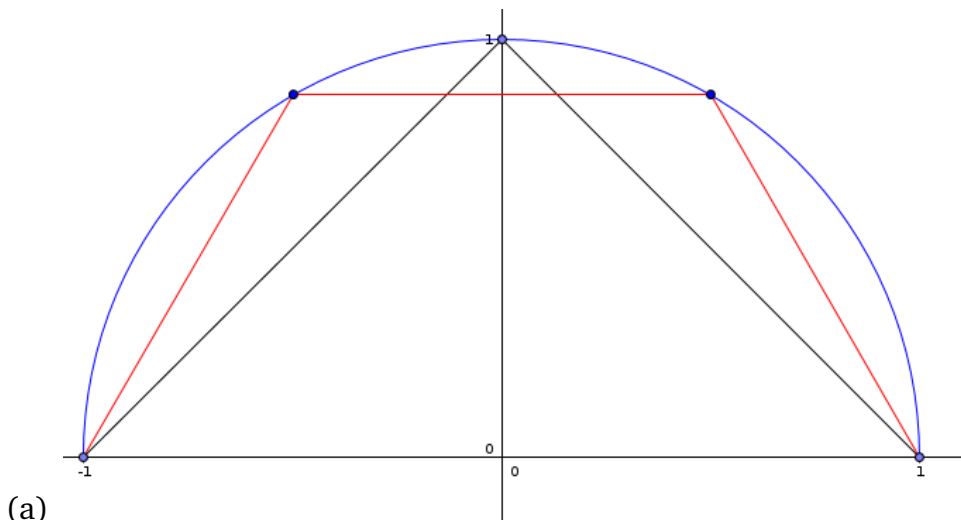
Let  $Z_n$  be the partitions  $\{0, \frac{1}{n}, \frac{2}{n}, \dots, 1\}$ .

- (a) Visualise the path  $\gamma$  and the paths  $\gamma_{Z_2}$  and  $\gamma_{Z_3}$ .
- (b) Determine the length  $L(\gamma)$  and  $L(\gamma_{Z_n})$  for each  $n \in \mathbb{N} \setminus \{0\}$ .
- (c) Show that  $L(\gamma) = \lim_{n \rightarrow \infty} L(\gamma_{Z_n})$ .

**Remark:** Let  $\gamma : [0, 1] \rightarrow \mathbb{R}^n$  a path which is continuously differentiable except in finitely many points, then the length of  $\gamma$  is defined by

$$L(\gamma) := \int_0^1 \|\gamma'(t)\| dt.$$

**Hints for solution:**



(b) We calculate:

$$\begin{aligned} L(\gamma) &= \int_0^1 \|\gamma'(t)\| dt = \int_0^1 \pi \sqrt{\cos^2(\pi \cdot t) + \sin^2(\pi \cdot t)} dt \\ &= \pi. \end{aligned}$$

Let  $n > 0$  then we have with  $\cos(x - y) = \cos(x)\cos(y) + \sin(x)\sin(y)$  and  $x = \frac{k+1}{n}\pi$  and  $y = \frac{k}{n}\pi$ :

$$\begin{aligned}
 L(\gamma_{Z_n}) &= \int_0^1 \|\gamma_{Z_n}(t)\| dt = \sum_{k=0}^{n-1} \int_{\frac{k}{n}}^{\frac{k+1}{n}} n \cdot \left\| \gamma\left(\frac{k+1}{n}\pi\right) - \gamma\left(\frac{k}{n}\pi\right) \right\| dt \\
 &= \sum_{k=0}^{n-1} \left\| \begin{pmatrix} \cos\left(\frac{k+1}{n}\pi\right) - \cos\left(\frac{k}{n}\pi\right) \\ \sin\left(\frac{k+1}{n}\pi\right) - \sin\left(\frac{k}{n}\pi\right) \end{pmatrix} \right\| \\
 &= \sum_{k=0}^{n-1} \sqrt{2 - 2 \left( \cos\left(\frac{k+1}{n}\pi\right) \cdot \cos\left(\frac{k}{n}\pi\right) + \sin\left(\frac{k+1}{n}\pi\right) \cdot \sin\left(\frac{k}{n}\pi\right) \right)} \\
 &= \sum_{k=0}^{n-1} \sqrt{2 - 2 \cos\left(\frac{\pi}{n}\right)} \\
 &= \sqrt{2} \cdot n \cdot \sqrt{1 - \cos\left(\frac{\pi}{n}\right)}.
 \end{aligned}$$

(c) After this calculation we have to consider the limit of these numbers. Happy about L'Hospital's rule we get:

$$\begin{aligned}
 \lim_{n \rightarrow \infty} \sqrt{2} \cdot n \cdot \sqrt{1 - \cos\left(\frac{\pi}{n}\right)} &= \sqrt{2} \cdot \lim_{n \rightarrow \infty} \frac{\sqrt{1 - \cos\left(\frac{\pi}{n}\right)}}{\frac{1}{n}} \\
 &= \sqrt{2} \cdot \lim_{n \rightarrow \infty} \frac{-\sin\left(\frac{\pi}{n}\right) \cdot \frac{\pi}{n^2}}{-2 \cdot \sqrt{1 - \cos\left(\frac{\pi}{n}\right)} \cdot \frac{1}{n^2}} \\
 &= \frac{\pi}{\sqrt{2}} \cdot \sqrt{\lim_{n \rightarrow \infty} \frac{1 - \cos^2\left(\frac{\pi}{n}\right)}{1 - \cos\left(\frac{\pi}{n}\right)}} \\
 &= \frac{\pi}{\sqrt{2}} \cdot \sqrt{\lim_{n \rightarrow \infty} \frac{2 \sin\left(\frac{\pi}{n}\right) \cdot \cos\left(\frac{\pi}{n}\right)}{\sin\left(\frac{\pi}{n}\right)}} \\
 &= \pi.
 \end{aligned}$$

**Exercise H3** (Curves, path length and rectifiability II)

(1 point)

Let  $\gamma : [0, 1] \rightarrow \mathbb{R}^n$  be a path. We call  $\gamma$  rectifiable, if the following supremum exists:

$$l(\gamma) = \sup\{L(\gamma_Z) : Z \text{ is a partition of } [0, 1]\}.$$

Let  $Z$  be a partition of  $[0, 1]$ . We call a partition  $Z'$  of  $[0, 1]$  a refinement of  $Z$ , if  $Z \subseteq Z'$  and write  $Z \leq Z'$ . The *mesh*  $|Z|$  of a partition  $Z = \{0 = t_0, t_1, \dots, t_n = 1\}$  is defined by

$$|Z| := \max\{t_{k+1} - t_k : 0 \leq k \leq n - 1\}.$$

- (a) Show that for each refinement  $Z \leq Z'$  one has  $L(\gamma_Z) \leq L(\gamma_{Z'})$ .  
 (b) Show that every continuously differentiable path is rectifiable with  $l(\gamma) = L(\gamma)$ .

**Hints for solution:**

- (a) Assume one has a refinement  $Z'$  of  $Z$ . Then for each pair  $(s_i, s_{i+1})$  consecutive elements of  $Z$  one has a finite chain  $t_0^i < \dots < t_n^i$  in  $Z'$  with  $t_0^i = s_i$  and  $t_n^i = s_{i+1}$ . With the triangle inequality one gets

$$\|\gamma(s_{i+1}) - \gamma(s_i)\| = \left\| \sum_{j=0}^{n-1} \gamma(t_{j+1}^i) - \gamma(t_j^i) \right\| \leq \sum_{j=0}^{n-1} \|\gamma(t_{j+1}^i) - \gamma(t_j^i)\|.$$

Summarising over all consecutive pairs  $(s_i, s_{i+1})$  proves the claim.

- (b) Let  $\varepsilon > 0$ . We have to show  $\left| l(\gamma) - \int_0^1 \|\gamma'(t)\| dt \right| \leq \varepsilon$ .

Choose a partition  $Z_0$  with  $|l(\gamma) - L(\gamma_{Z_0})| \leq \frac{\varepsilon}{2}$ . Of course  $t \rightarrow \gamma'(t)$  is uniformly continuous and so is  $t \rightarrow \|\gamma'(t)\|$ . So we can find a  $\delta > 0$  with  $|s - t| < \delta \Rightarrow \|\gamma'(s) - \gamma'(t)\| < \frac{\varepsilon}{2n}$ . Let  $Z \geq Z_0$  with  $|Z| < \delta$ . By (a) we have  $|l(\gamma) - L(\gamma_Z)| \leq \frac{\varepsilon}{2}$ . Let  $m \in \mathbb{N}$  the number of elements of  $Z$ .

We conclude using the mean value theorems for differentiation and integration:

$$\begin{aligned} \left| L(\gamma_Z) - \int_0^1 \|\gamma'(t)\| dt \right| &= \left| \sum_{j=0}^{m-1} \|\gamma(t_{j+1}) - \gamma(t_j)\| - \int_{t_j}^{t_{j+1}} \|\gamma'(t)\| dt \right| \\ &= \left| \sum_{j=0}^{m-1} \left\| \begin{pmatrix} \gamma'_1(\tau_j^j) \\ \vdots \\ \gamma'_n(\tau_j^j) \end{pmatrix} \right\| (t_{j+1} - t_j) - \|\gamma'(\tau_j^j)\| (t_{j+1} - t_j) \right| \end{aligned}$$

with  $\tau_j^j, \tau_1^j, \dots, \tau_n^j \in [t_j, t_{j+1}]$ . Since  $|\gamma'_i(s) - \gamma'_i(t)| \leq \|\gamma'(s) - \gamma'(t)\| < \frac{\varepsilon}{2n}$  we conclude

$$\begin{aligned} \left| L(\gamma_Z) - \int_0^1 \|\gamma'(t)\| dt \right| &= \left| \sum_{j=0}^{m-1} \left\| \begin{pmatrix} \gamma'_1(\tau_1^j) \\ \vdots \\ \gamma'_n(\tau_n^j) \end{pmatrix} \right\| (t_{j+1} - t_j) - \|\gamma'(\tau_j^j)\| (t_{j+1} - t_j) \right| \\ &\leq \sum_{j=0}^{m-1} \left\| \begin{pmatrix} \gamma'_1(\tau_1^j) \\ \vdots \\ \gamma'_n(\tau_n^j) \end{pmatrix} \right\| (t_{j+1} - t_j) \\ &\leq n \cdot \frac{\varepsilon}{2n} = \frac{\varepsilon}{2} \end{aligned}$$

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This means

$$|l(\gamma) - L(\gamma)| \leq |l(\gamma) - L(\gamma_Z)| + |L(\gamma_Z) - L(\gamma)| \leq \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon.$$

This completes the proof.